

Visualization and analysis of LiDAR waveform data

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Introduction



- Goal:
 - Explore LiDAR waveform data using techniques previously applied to spectral imagery.
- Background:
 - Limited work with waveform data in the existing literature. Discussion seems to have started ~2003 by Wagner (Univ of Vienna)
 - Data have been hard to come by, data formats not defined*, software not available.
 - Existing work mostly focuses on Gaussian fitting or taking moments of waveform distributions. Innovative approach by UT using Voxels.
 - Bathymetry community excluded here – techniques there strongly focused on that application.

* Thank you to Andre Jalobeanu for breaking the code..



Sensor



Teledyne Optech Titan Multispectral Lidar System

- 3 Channel
 - Channel 1: 1550 nm SWIR – 3.5° forward tilt
 - Channel 2: 1064 nm NIR – 0° forward tilt
 - Channel 3: 532 nm VIS – 7° forward tilt
- Programmable Pulse Repetition Frequency
 - 50 – 300 kHz (per channel); 900 kHz total
 - Operated for NPS by NCALM on June 5, 2016
 - Limited to 100 kHz/channel by waveform collection





Flight – Parameters



Parameter	Value
PRF (per channel)	100 KHz
Field of view	30°
Scan Frequency	40 Hz
Altitude	~ 400 m
Speed	~ 150 knots
Point Spacing (DT/CT)	0.10 m/0.96 m
Point Density	12 points/m ² (discrete data)



The Software issue



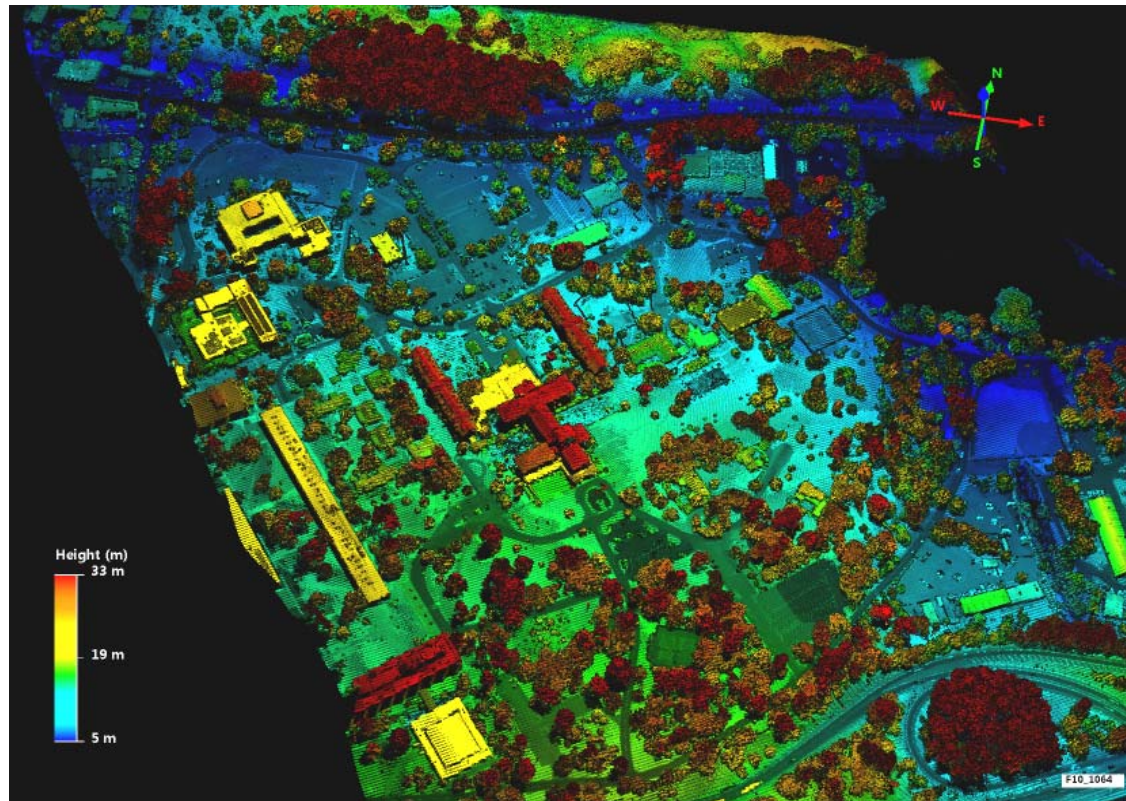
- There seemed to be a disconnect between the data, data format, software, and platform (Windows, Unix...)
- Analysis done with data in PulseWaves format (Martin Isenburg, rapidlasso)
- Interactive Data Language (IDL) used to read in and re-arrange the data so that ENVI could be used.



NPS Campus



- Point cloud display of study area.
- NPS campus – height elevation model
- QTM software





2-color display

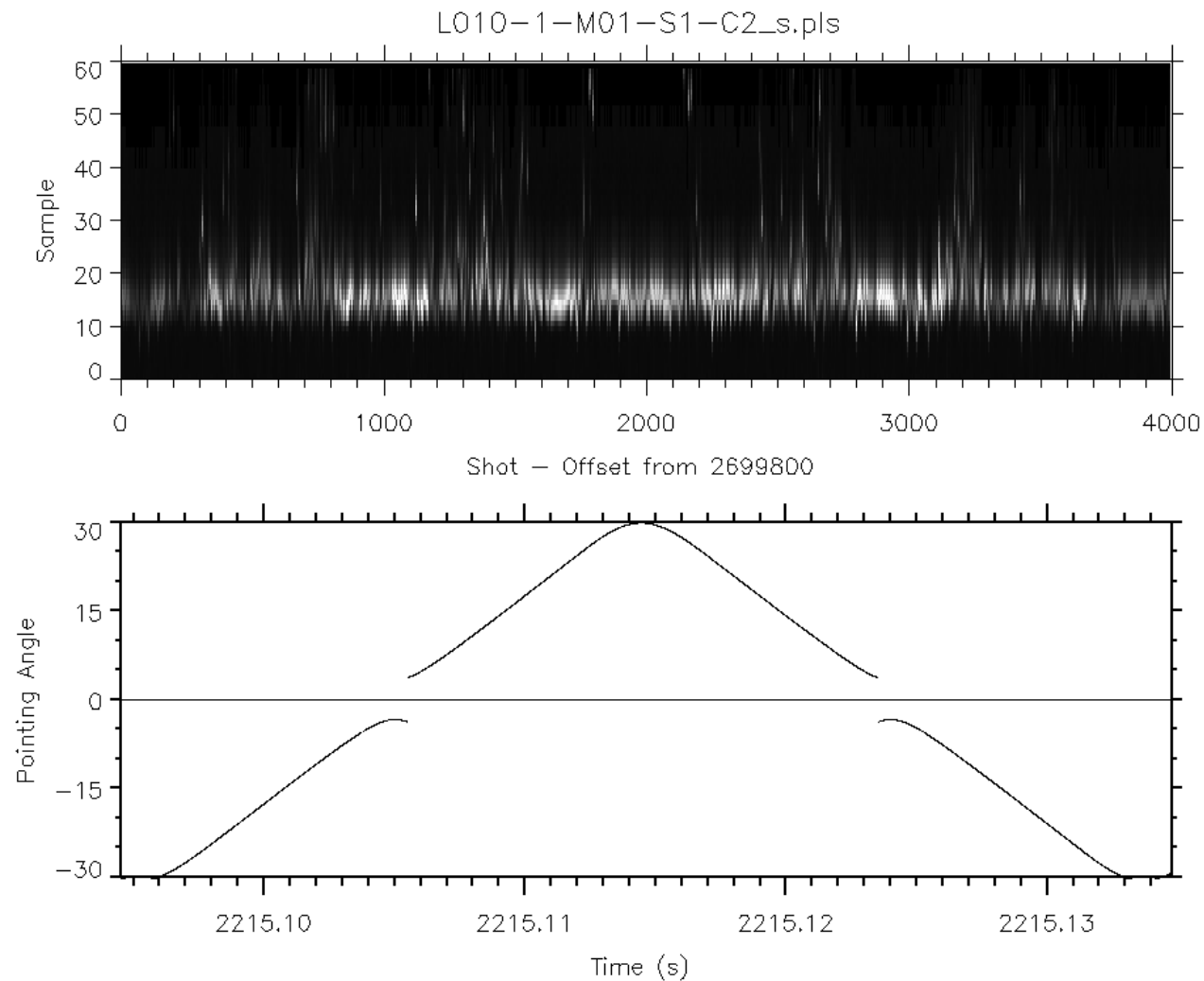


Flight line 10
Channels
2&3
1064/532 nm
Some
spectral
variability –
see McIver
paper



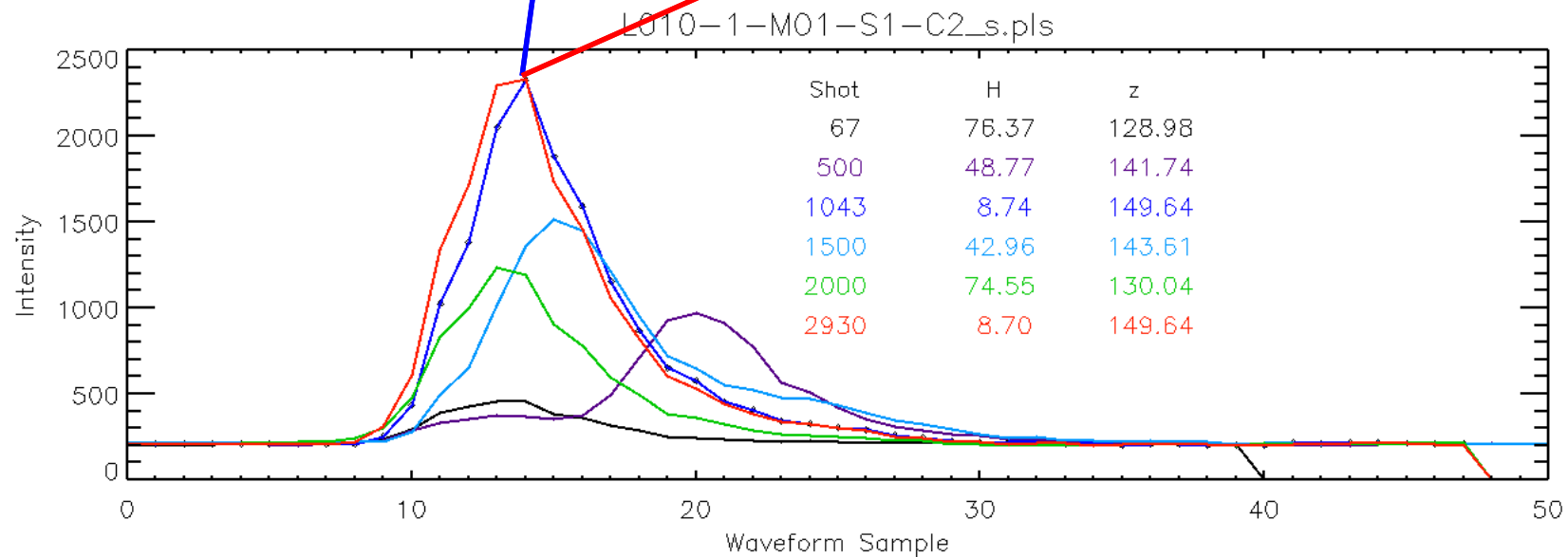
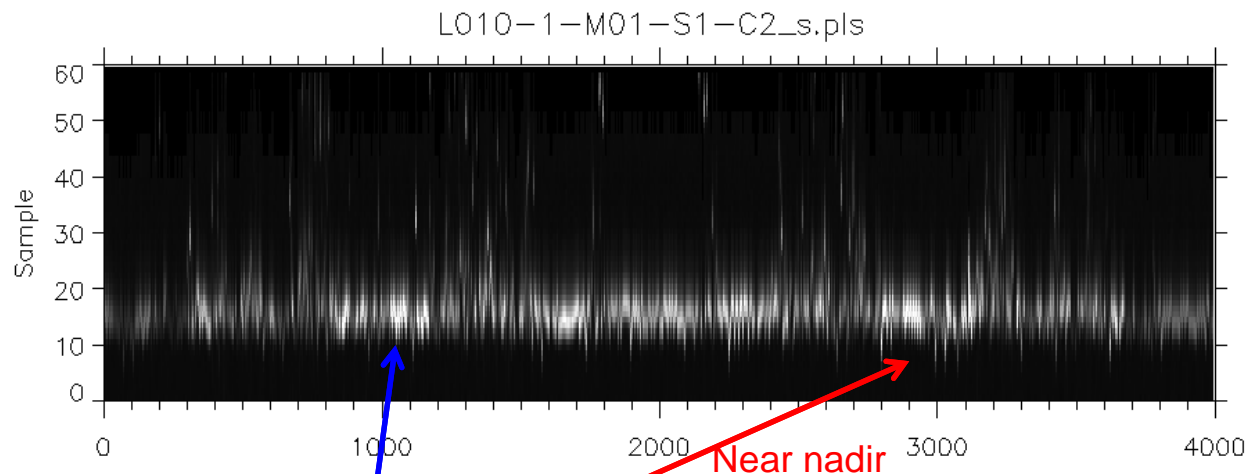


Waveform Data Waterfall Display





Waveform Data Waterfall Display





Programming



- Data were read in, gridded at ~1 point/cell using “target” xy information.
 - *An interim solution to the display problem – need to write smarter display approach that maintains full vector quality of the data.*
- Available parameters include an ‘intensity’ parameter which can be used to compare the two channels.
- Reflectance contrast between buildings and vegetation is much greater at 532 nm.



Intensity, 1064 nm



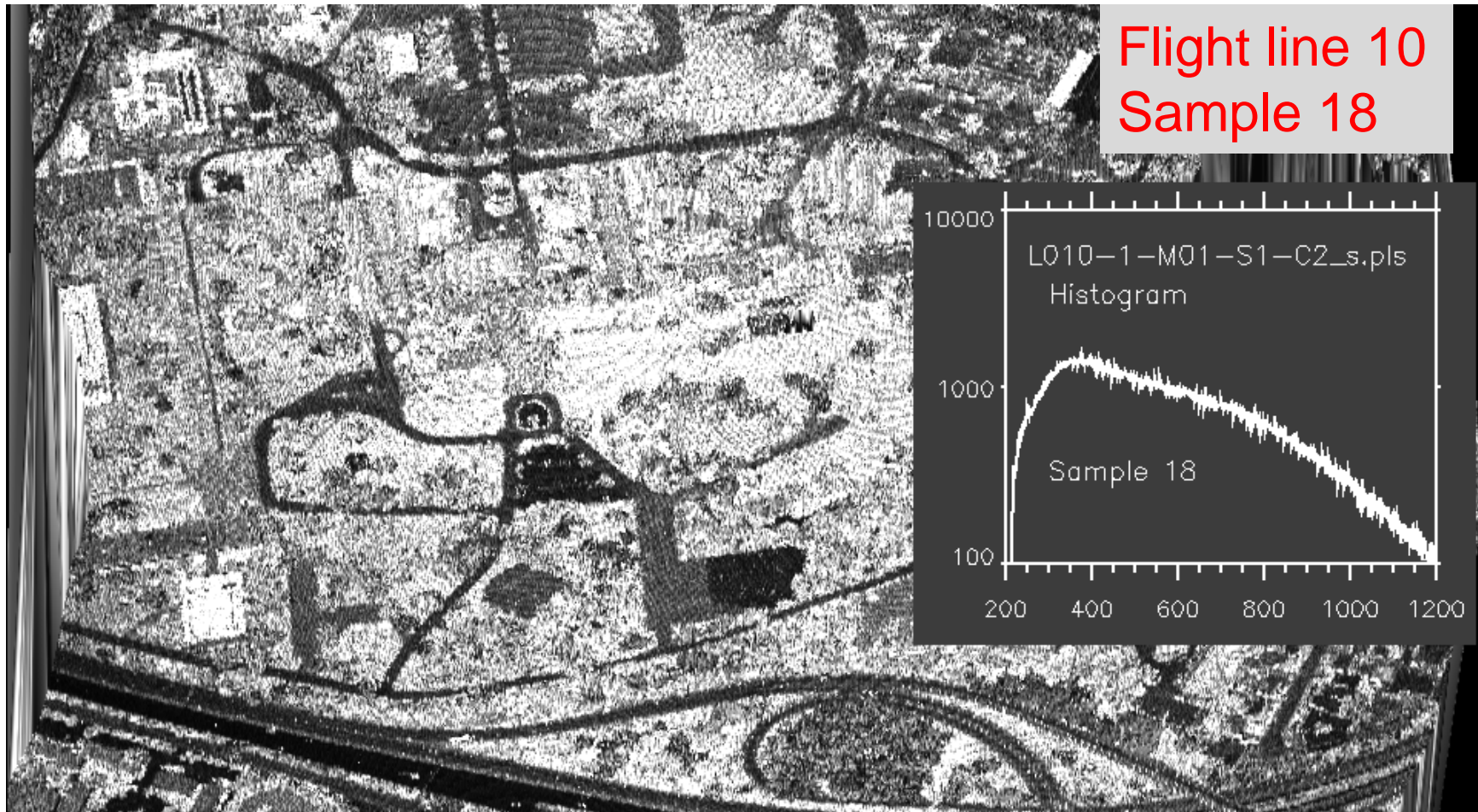


Intensity, 532 nm



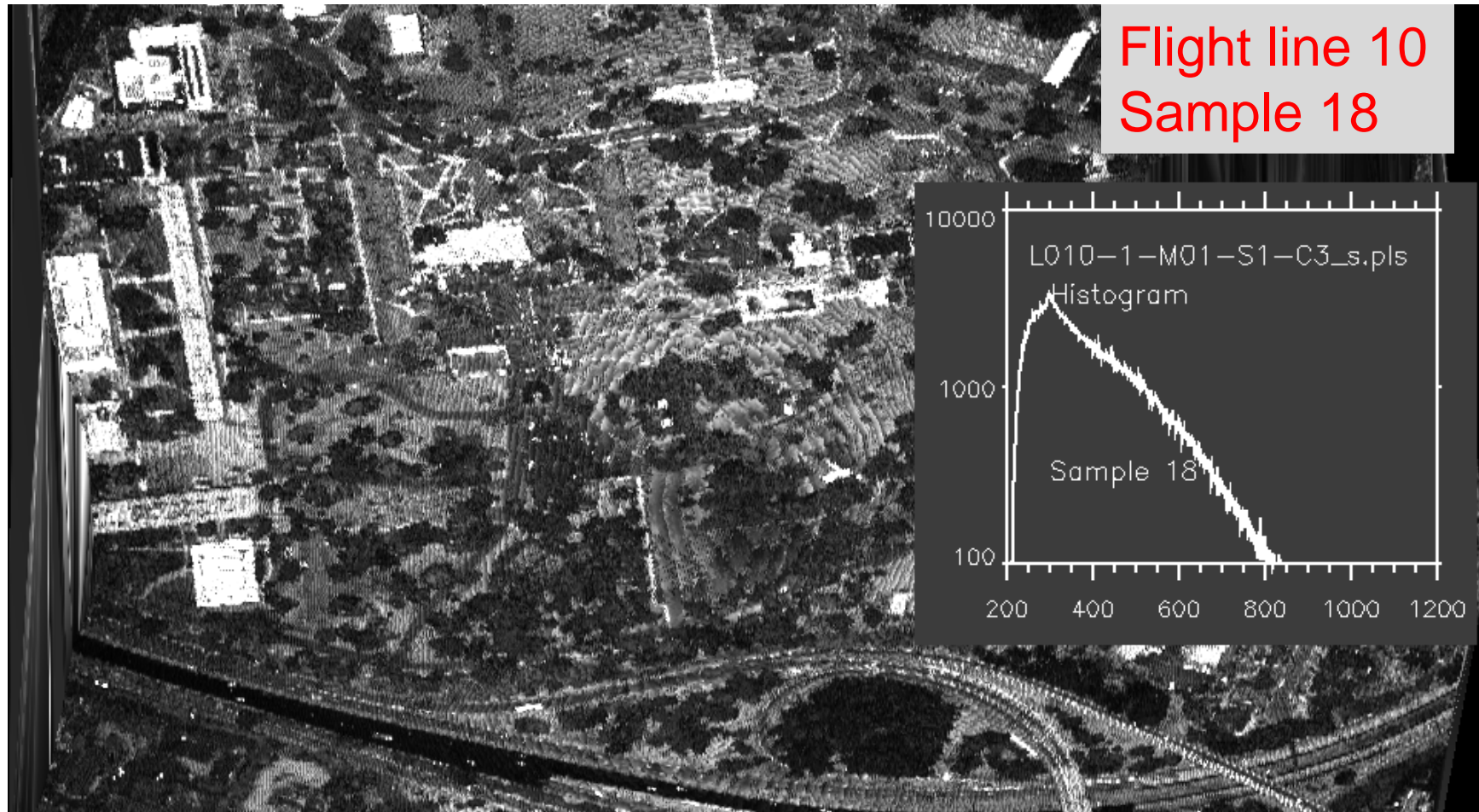


C2 Waveform Samples



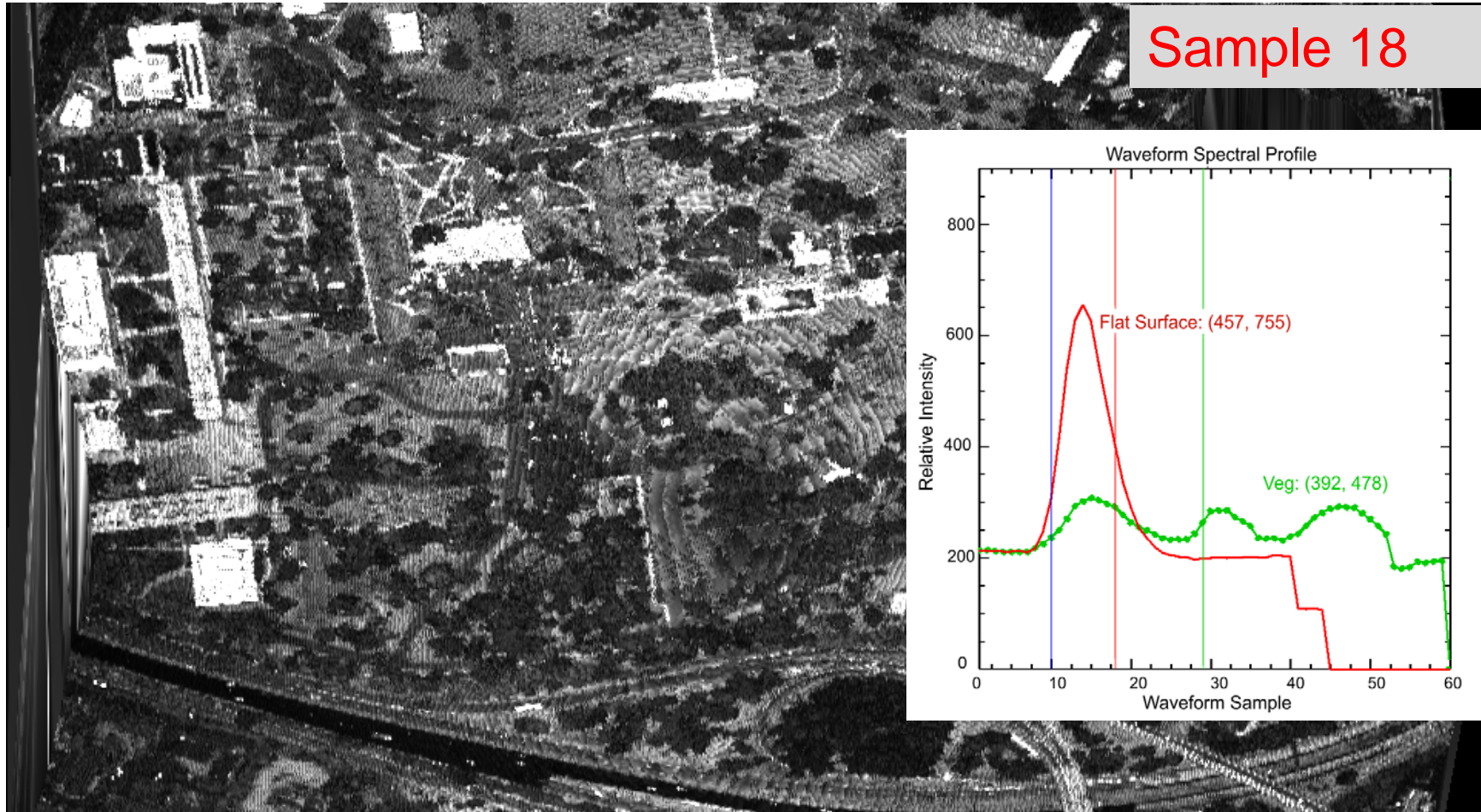


C3 Waveform Samples





C3 Waveform Samples

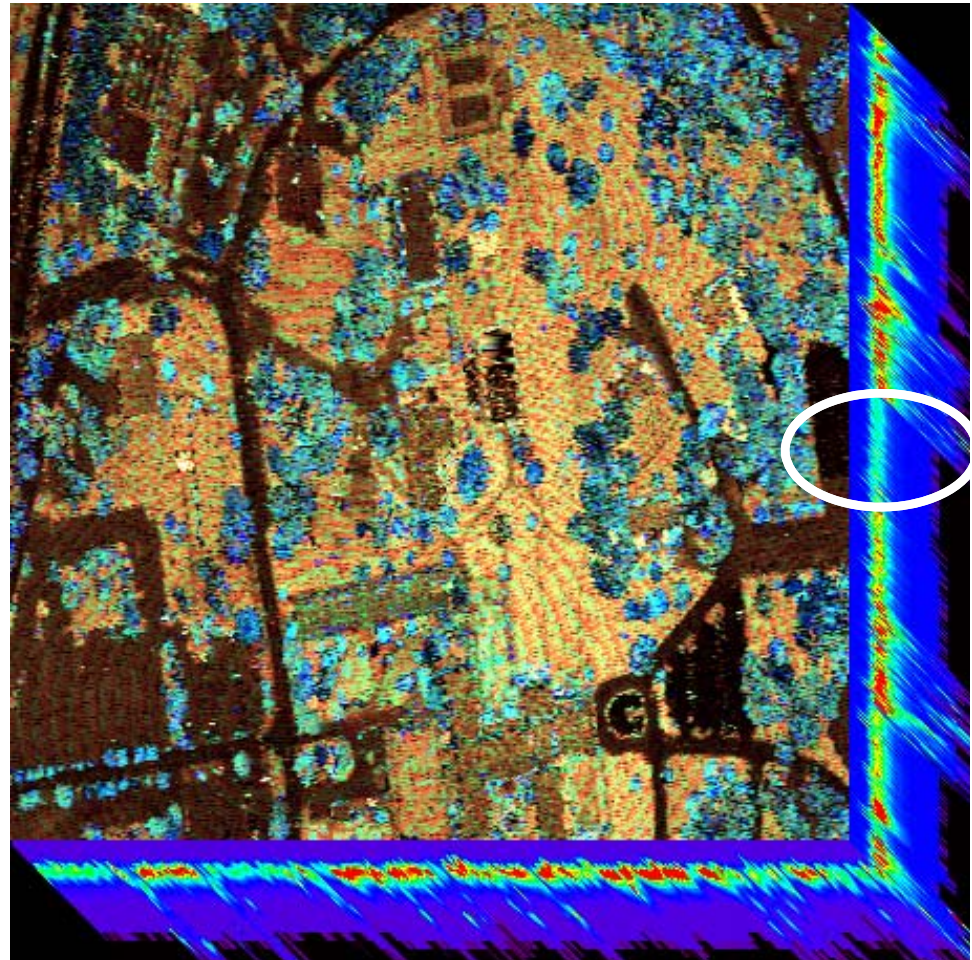




Hypercube



- Spectral Samples, 1032 nm
- R:15
- G:20
- B:25

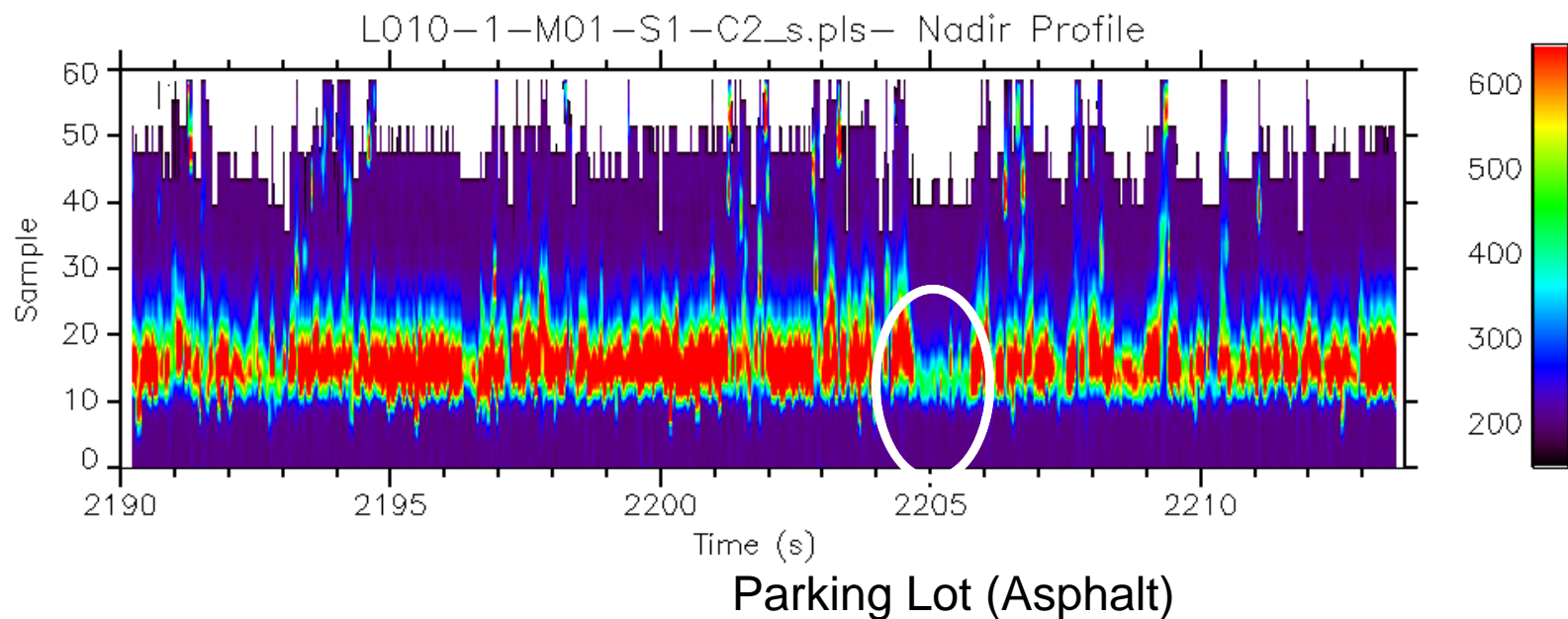




Spectral Profile



- Nadir track, 1032 nm



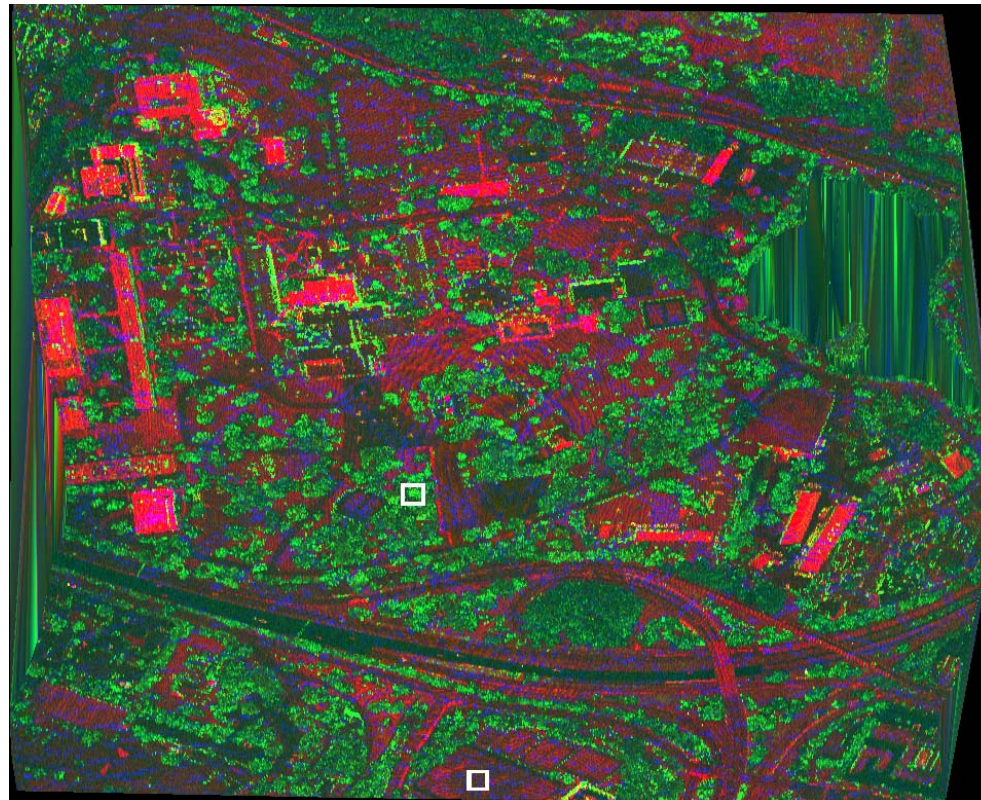


C3 532 nm

R:18, G:29, B:10.



- RGB representation of waveforms, C3



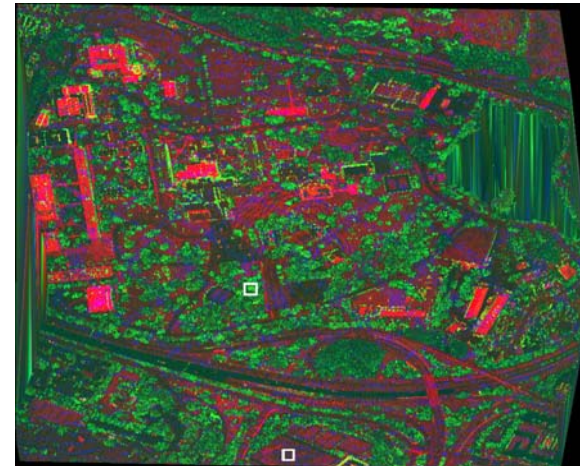
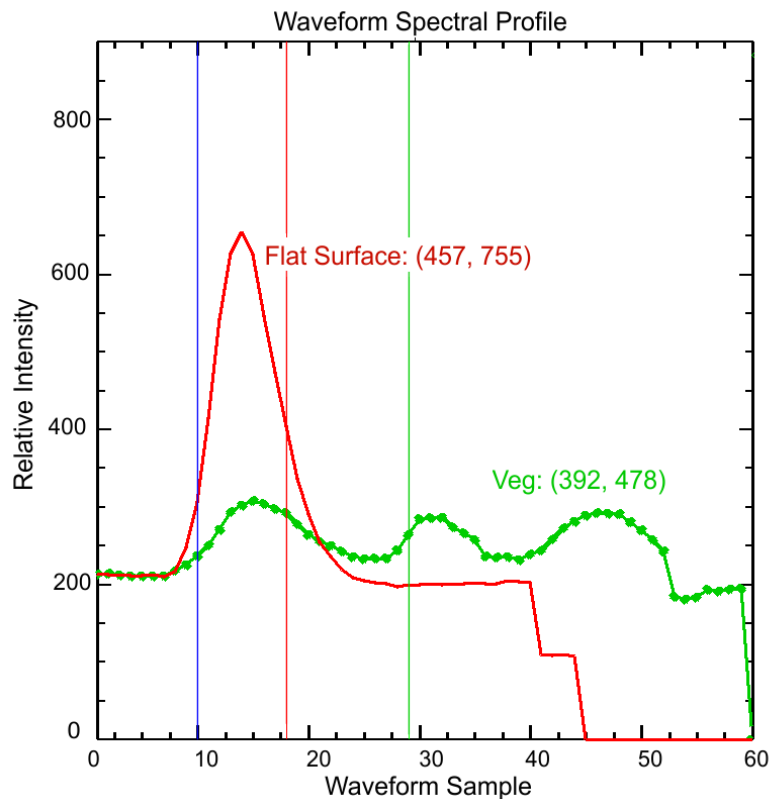


C3 532 nm

R:18, G:29, B:10.



- RGB representation of waveforms, C3

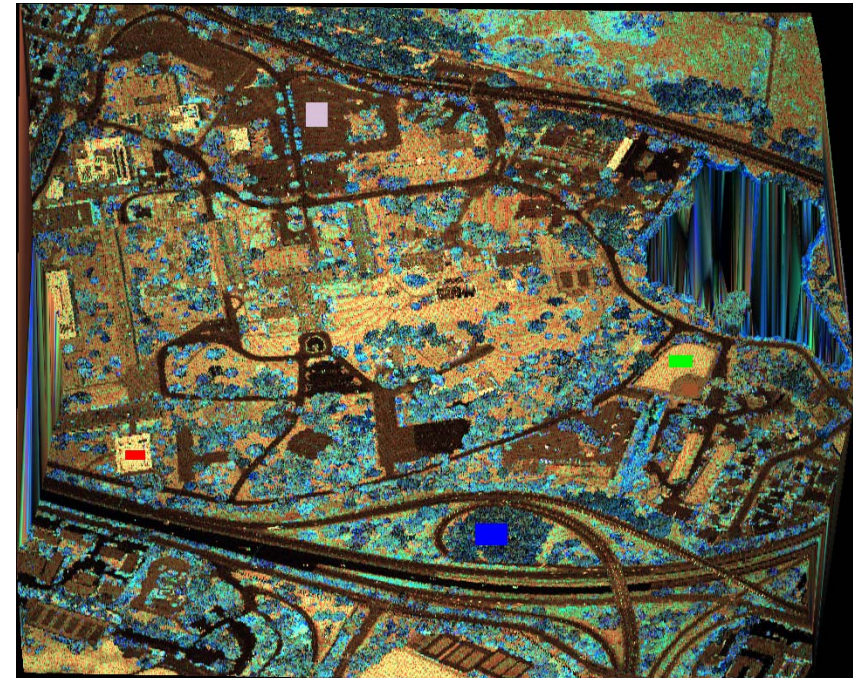
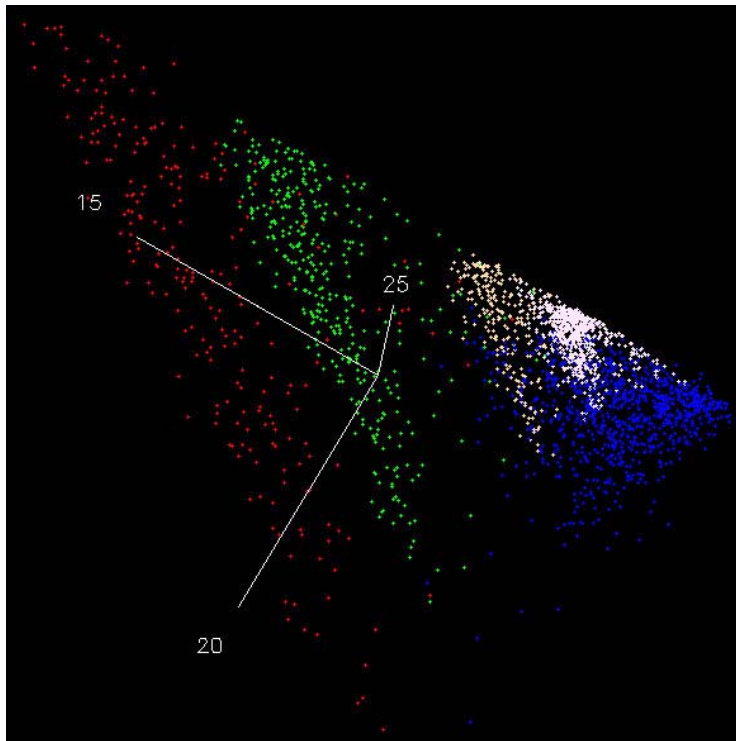




N-Dimensional Visualize



- C2

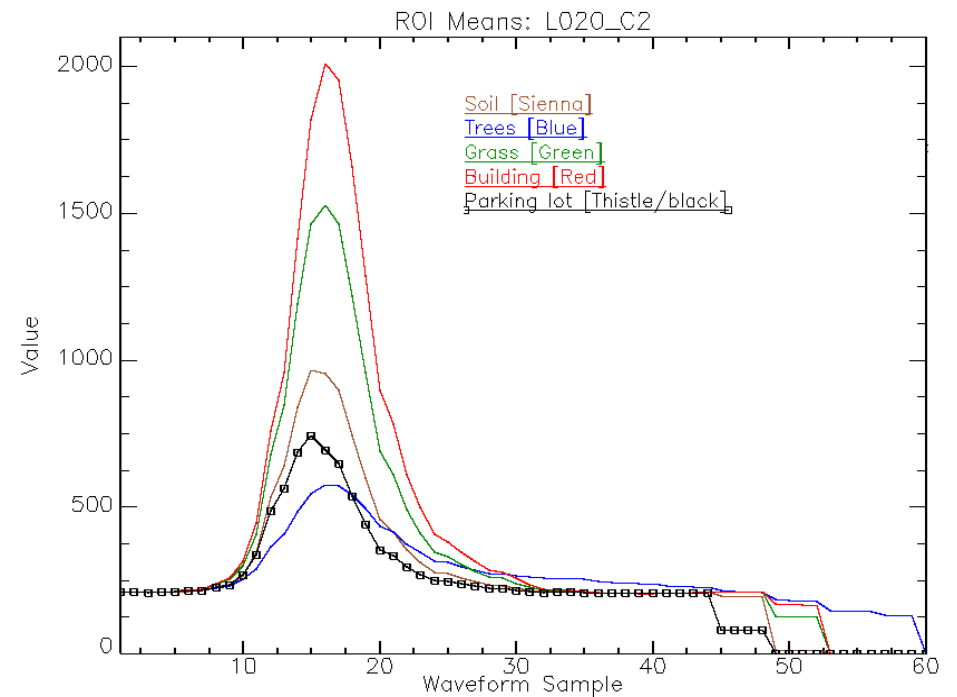
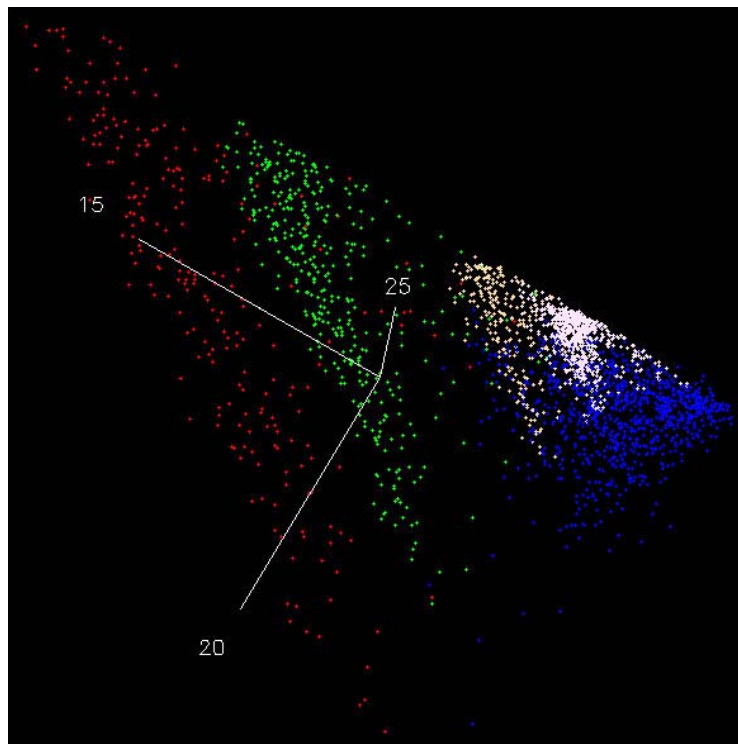




N-Dimensional Visualize



- C2.





Classification



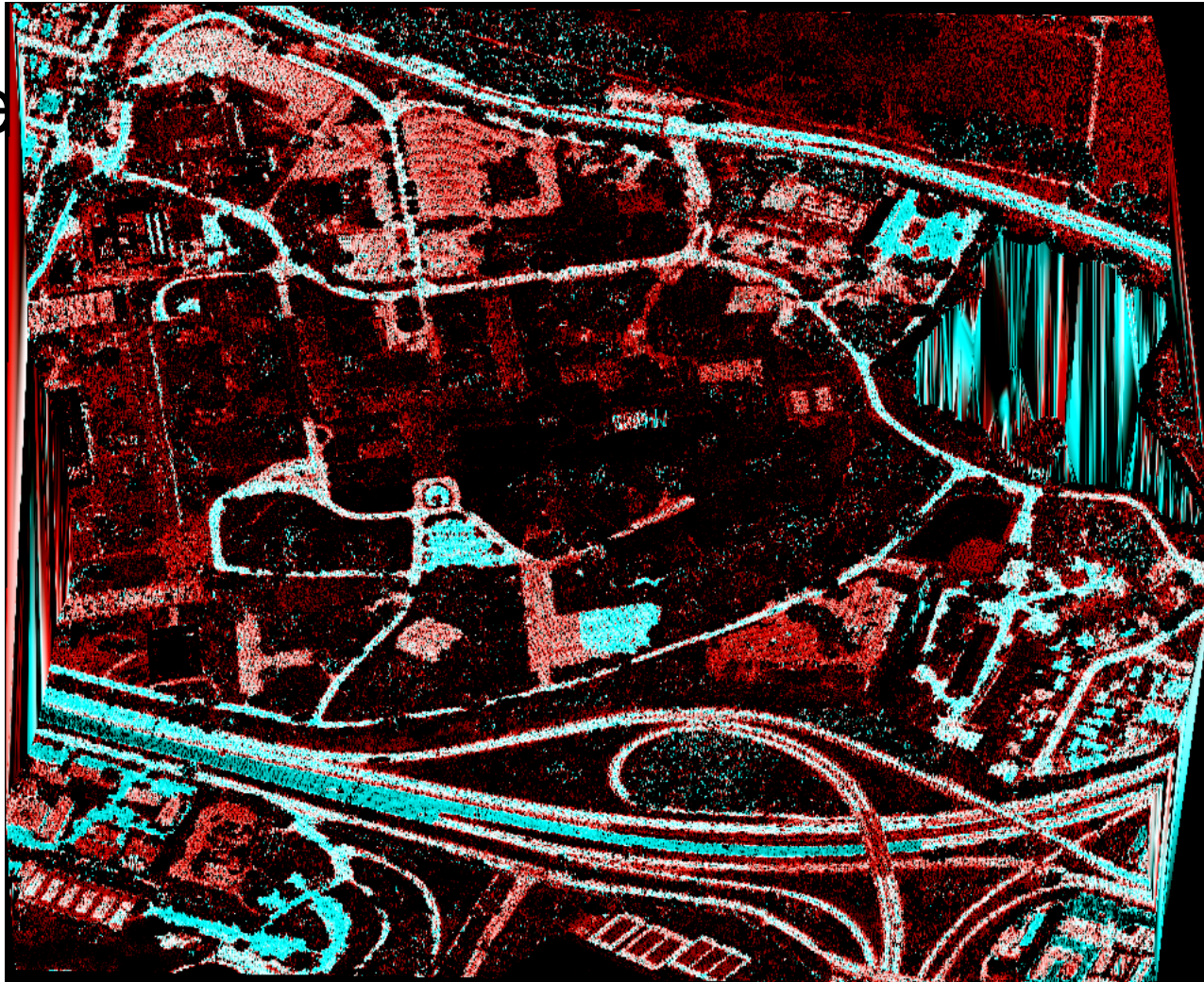
- The idea here is to use the spectral classification tools available for analysis.
- A quick run with a maximum likelihood classifier was unproductive.
- The more primitive spectral angle mapper had some limited success, as illustrated next.
 - Two classes of asphalt, which the n-D visualizer separated, did classify different regions in the scene



Classification



- Spe





Conclusion



- Waveform data have been transformed into x, y, and a waveform spectral dimension analogous to that found in hyperspectral data.
- The display of waveform data in an RGB triple display shows clear distinctions between scene elements.
- A simple classification run showed some success in identifying different asphalt types. (recent result – need to go study in-situ).
- Work to do:
 - Transition to a vector based display approach that does not require gridding the data
 - Study classifiers appropriate to the data
 - Review impact of radiometric correction
 - Compare the two wavelengths
 - Study forest data (Point Lobos)
 - Review data from different systems (Riegl, AHAB, Leica)

For More Information Please Contact:

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