Technology in the littorals

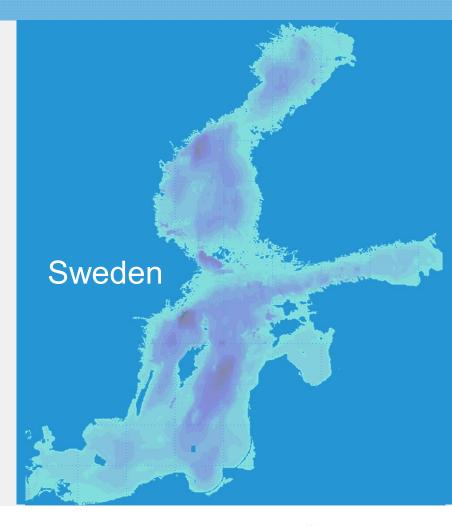
Below the surface and in-shore

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The Baltic Sea: Physical environment

- Shallow
 - Mean depth about 60 m
- Large river outlets
- Brackish water,
 - salinity 1/7 of the Atlantic
- Strong seasonal variations
 - Sound velocity profiles vary
- Complicated bottom topography
 - Archipelagos
- Complicated bottom geology
 - Bare rock with pockets of postglacial clay, sand,...
 - Thick sediments over limestone



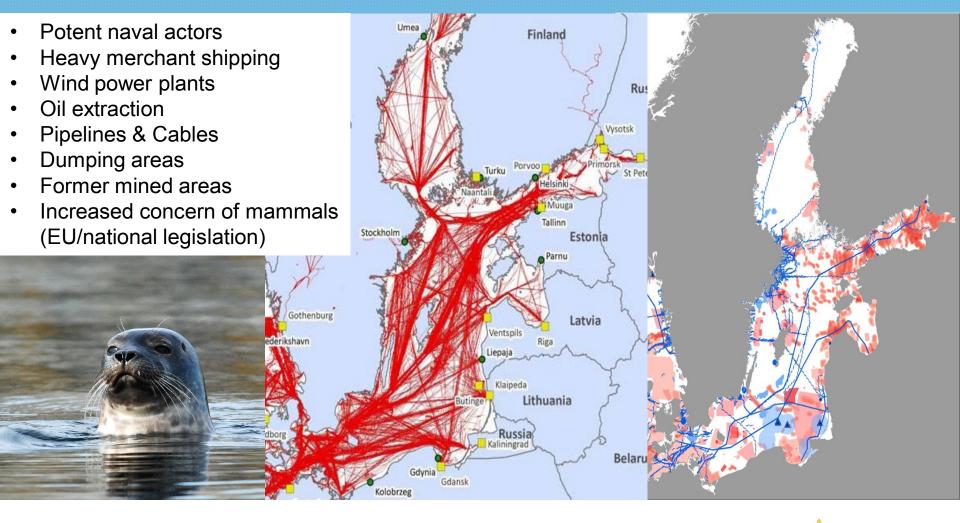




Stockholm archipelago – an extreme littoral environment



The Baltic Sea: Operational environment





The Baltic Sea

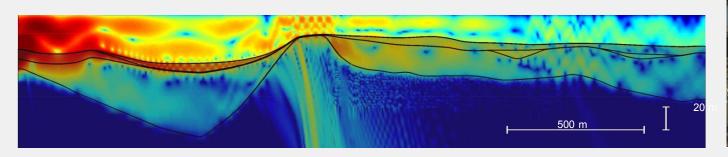
Technological aspects

Physical environment

- Salinity and use of "HF" acoustics
- Electromagnetic sensor systems
- Wave propagation & reverberation
- Signature management
- Tactical decision aids
 - Access to physical parameters

Operational environment

- Threat analyses
- Noise and interference analysis & suppression
- Safety issues (mines, mammals, etc)

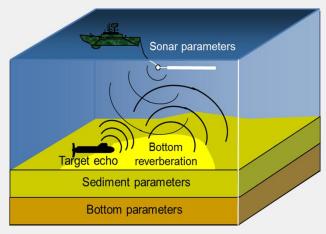


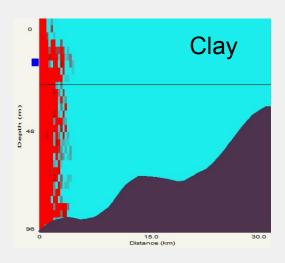


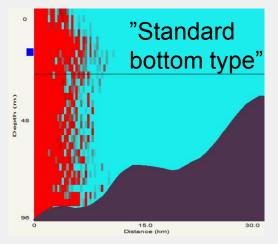


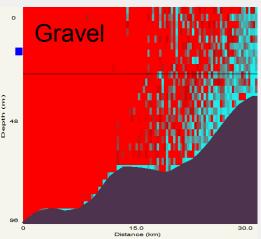
Sediment and bottom parameters

Effect on detection ranges





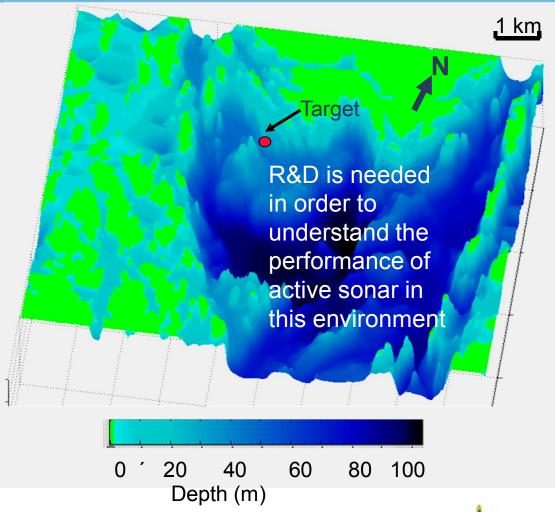






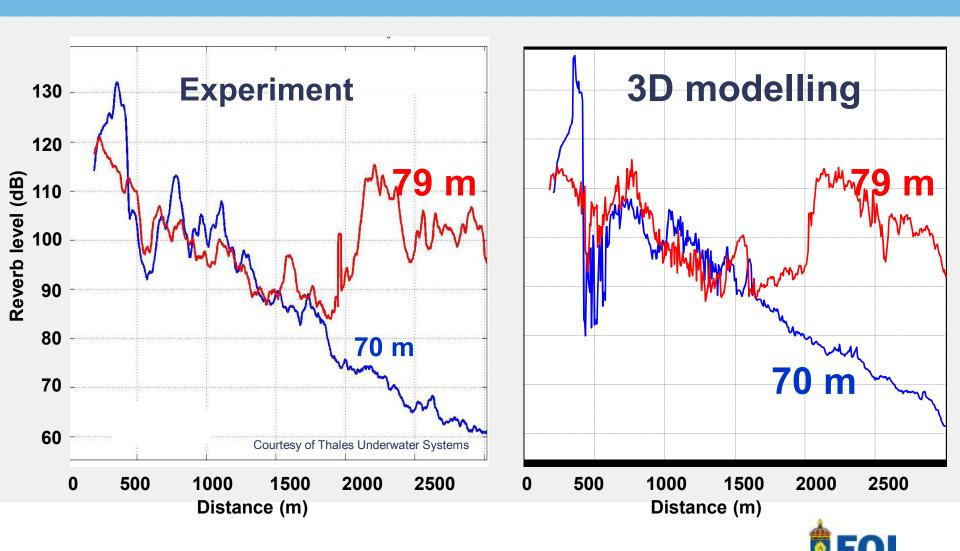
Shallow waters and complicated bottom topography







Reverberation – Source Depth Dependance

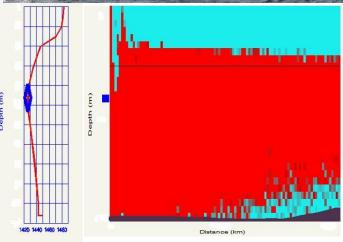




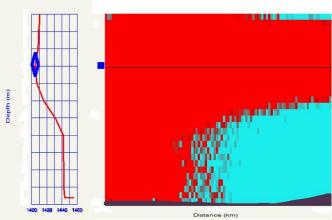
Sensors Environment Ship status Crew Tactics

Figure of advantage, FOA Mission profile Signature

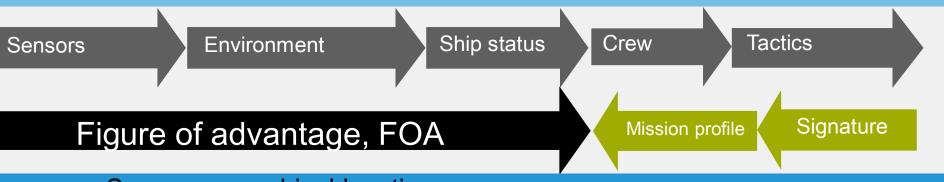




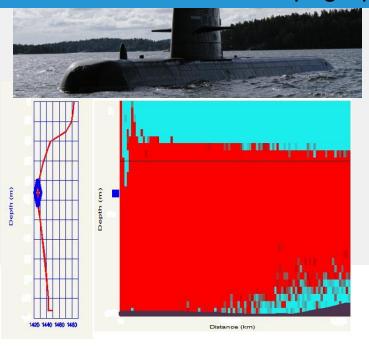


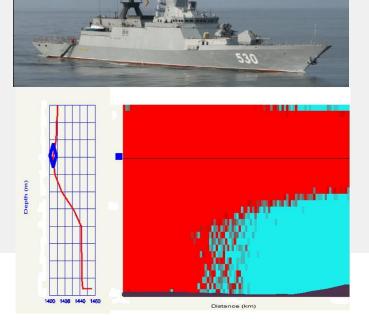




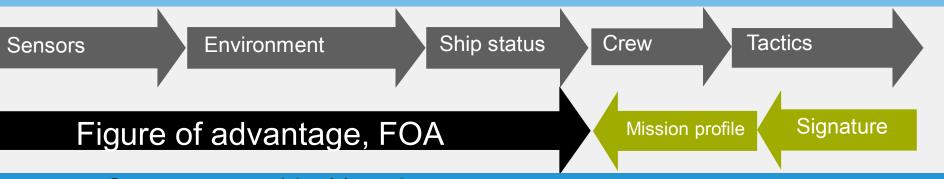


Same geographical location:
Same bottom topography and same sediment and bottom parameters



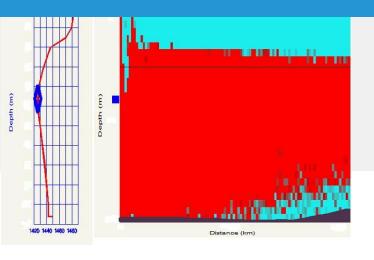


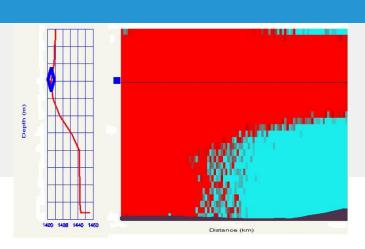




Same geographical location: Same bottom topography and same sediment and bottom parameters

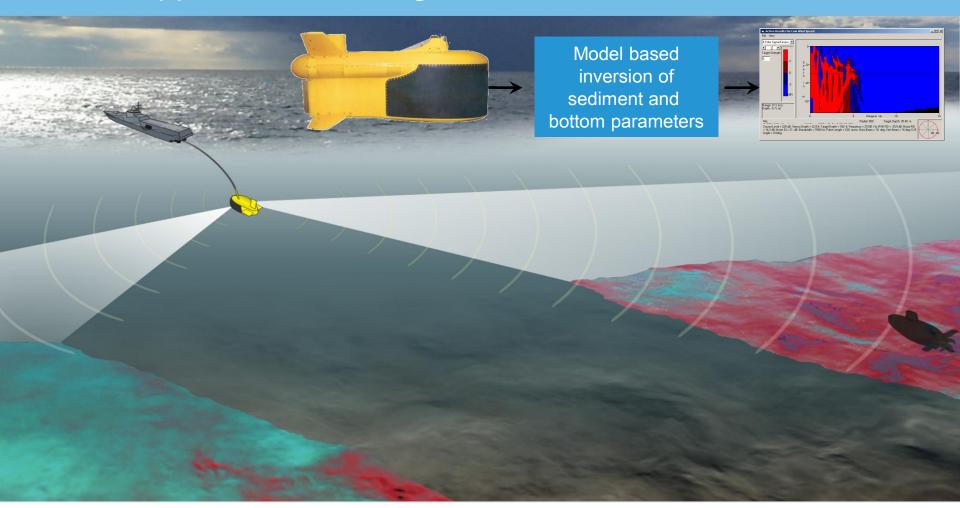
Strong seasonal variations: Variations in sound velocity profiles





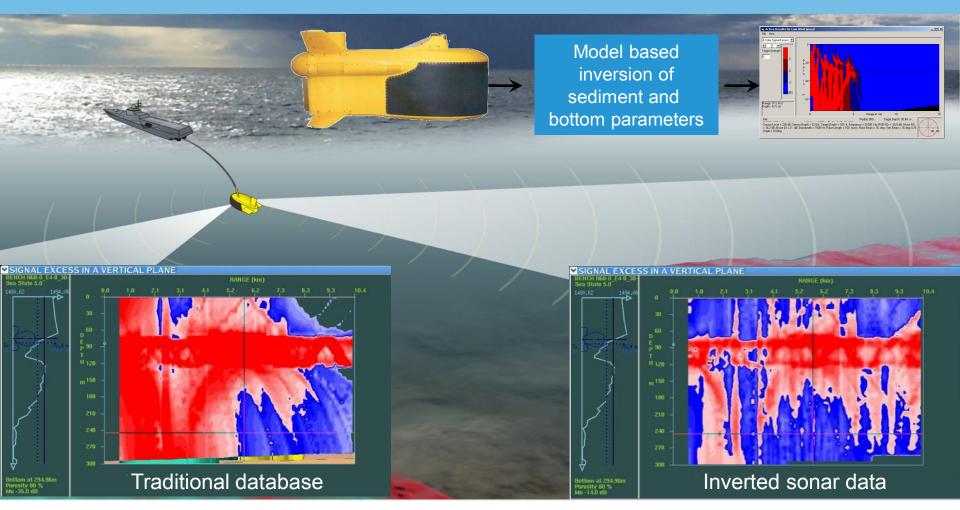


Signal processing ASW applications: Through the sensor REA





Signal processing ASW applications: Through the sensor REA

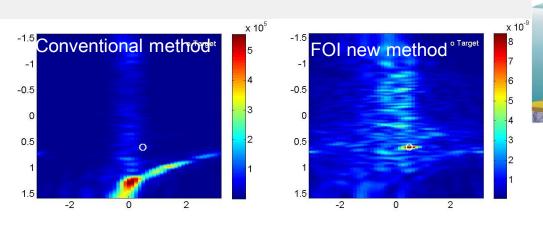


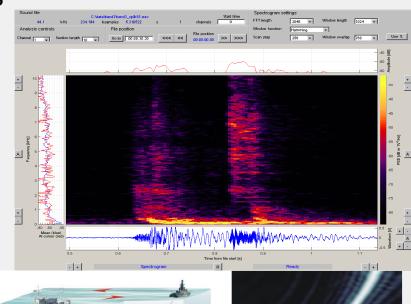


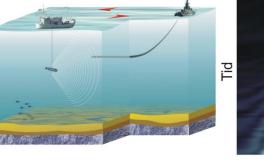
Signal processing Submarine applications

Development of array processing algorithms for submarines

- Passive ranging/localization and target tracking
- Torpedo warning
- Noise and interference analysis & suppression
- High resolution/adaptive beamforming
- Automatic detection (transients, pings)





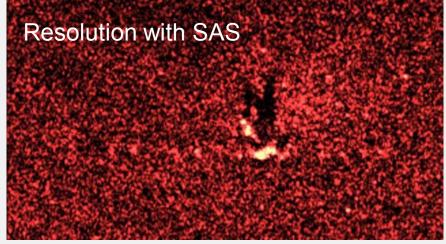


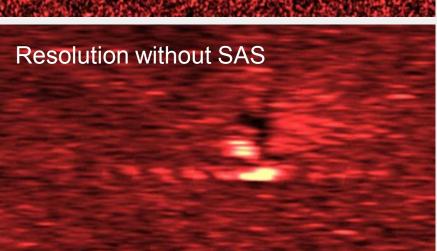


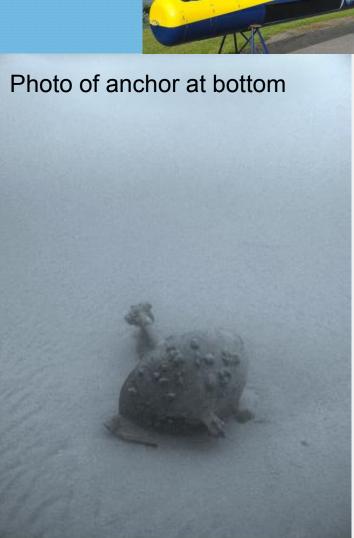


Signal processing UUV/AUV applications



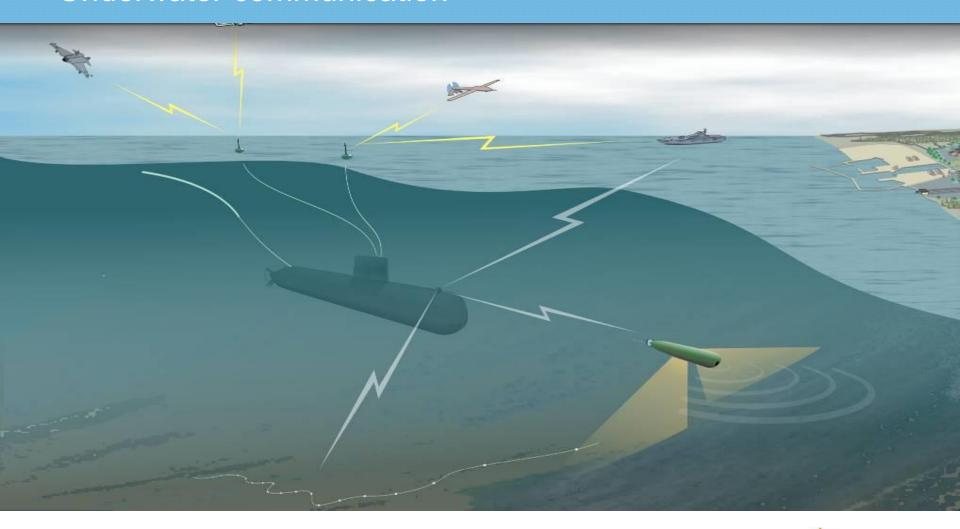








Signal processing Underwater communication





Signal processing Underwater communication

//	Area	Range	Error free bitrate (infobits per second)
	Baltic Gotland Late summer	40 km 60 km	10000 4000
	Baltic Bornholm Fall	54 km	Stealth (low data rate)
	Archipelago	1 km	54000
3	Ship to sub making speed	Intentionally blank	Digital speech, SMS, images





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- There is a need to explore "systems-of –systems capability" in the underwater domain. Solutions for underwater communication is an essential precondition



- The Baltic Sea represents a particularly difficult environment for sensor optimization, signature generation and signal propagation
- In depth knowledge of environmental impact on sensors, signatures and signal propagation is essential to win the underwater battle
- There is a need to explore "CEC-solutions" in the underwater domain
- R&D-support is a decisive factor for successful operations in the Baltic sea

