# NAVALPOSTGRADUATE SCHOOL Monterey, California



#### A Regional Deterrence Ship Design

by

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A systems engineering approach to the development of a warship optimized for the deterrence of regional conflicts in littoral waters is presented, followed by a description of the preliminary design of the ship shown by analysis to be most effective. The requirement for the project reported was to develop a ship which would be effective in deterring regional wars among third world nations; in hampering the military effectiveness of the aggressor should deterrence fail and in protecting or evacuating limited numbers of civilians. The study reports on an analysis of likely threat weapons, on the means used to choose defensive combat system capabilities to defeat such weapons and on the selection of capabilities necessary for successful operation in littoral waters. Major emphasis is placed on measures intended to significantly improve the ship's survivability relative to existing combatants. The design description includes data and numerous drawings.				
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## A Regional Deterrence Ship, RDS 2010

This report documents a systems engineering and design capstone project undertaken by students in the Total Ship Systems Engineering program at the Naval Postgraduate School. The project was performed under the direction of Prof. C. N. Calvano. (The officer students who comprised the design team were: LCDR Dwight Alexander, LCDR Dean Cottle, LT Kent Ketell and LT Jeff Riedel, all USN.)

## ABSTRACT

A tentative operational requirement was given to the development team, calling for analysis and design of a ship which would be highly effective, through presence-projection, at operating in littoral waters to deter regional conflicts between third world nations and at hampering the military operations of the aggressor nation in the event the deterrent effort failed. The ship was also required to have significant capability to support the evacuation of friendly personnel; to be fully capable to be operationally integrated into a battle group; to support limited amphibious operations (conducted from other ships) and to have robust selfdefense (but not area defense) capabilities. Because the ship would be operating in a hightension area, it is likely to be fired upon from a peacetime footing and, therefore, was required to have significant vulnerability reduction features.

The report documents the identification of threat weapon characteristics and the analysis of four possible threat attack scenarios. For each scenario, the team required that the RDS 2010 be capable of achieving a kill probability in excess of .99 against all assumed threat weapon combinations. The report describes the analyses conducted and the combat systems suite selected to be incorporated in the ship.

Minimization of the likelihood and numbers of crew casualties was a high priority design guideline and the report discusses the various design alternatives considered to reduce the ship's vulnerability to threat weapons. A double hull was incorporated, providing significant reserve buoyancy, a measure of additional standoff distance against warhead detonations and providing the necessary volume for incorporation of yet-to-be-defined measures for defeating warhead effects. Considerable care was given to the arrangements of combat capabilities in *enclaves* to reduce the likelihood of loss of multiple capabilities from a single hit.

A complete description of the ship resulting after the first iteration of preliminary design is provided and considerable detail in the description of the ship is provided in appendices.

# TABLE OF CONTENTS

T TX 171	rn c			Page
		ענ		1
			EMENTS SETTING PHASE	
F	4.		IO TENTATIVE REQUIREMENT STATEMENT	4
		1.	World View-2010 time frame	4
		2.	FPS Role in 2010	5
		3.	Political Considerations	6
-	_	4.	Other	6
Ŀ	3.	RE	QUIREMENTS DOCUMENT FOR REGIONAL DETERRENCE	
			IP (RDS) 2010	7
		1.	General Description of Operational Requirement.	7
		2.	Threat	8
		3.	Shortcomings of Existing Systems.	8
		4.	Range of Capabilities Desired.	9
		5.	General Affordability Limits	10
		6.	Platforms/Quantities	.10
		7.	Integrated Logistics Support (ILS).	.10
		8	Related Efforts.	.11
-	С.	RE	QUIRED OPERATIONAL CAPABILITIES	.13
III. II	NIT	'IAL	DESIGN DECISIONS	.17
•	<b>\</b> .	DE	SIGN PHILOSOPHY	.17
E	3.	CO	NCEPTIONS AND INNOVATIONS	.22
		1.	Total Ship Innovations.	.22
		2.	Combat System Innovations	.22
		3.	Affordability Studies	.23
		4.	Survivability Features	.24
		5.	Propulsion Plant Vision	.25
		6.	Electric Plant Vision	.25
C	Ζ.	ELI	EMENT SELECTION OPTIONS	.26
		1.	HULL	.28
			a. DOUBLE HULL vs. SINGLE HULL	.28
			b. Collective Protection System	.29
		2.	MECHANICAL	.29
			a. Plant Type (Including Transmission)	.29
			b. Propeller - Variable Pitch vs. Controllable Reversible Pitch	
			(CRP)	.31
		3.	ELECTRICAL	.31
			a. Generation Scheme	.31
			b. Distribution system	31
			c. Power management system	32
			d. Emergency power	

	4.	COMBAT SYSTEMS	32
		a. Detection Systems/Sensors	32
		b. Command and Decision	34
		c. System Information Coordination	
		d. System Readiness Coordination	
		e. External Communications	
		f. Interior Communications	
		g. Weapon Control System	
		h. Navigation System	
		i. Engagement/Weapons	
		j. Countermeasures	
		ILITY STUDIES - COMBAT SYSTEM DEFINITION	
<b>A</b> .	TH	REATS	38
В.		REAT SCENARIOS AND EVALUATION	
	1.	Background Developments	
		a. Assumptions	
		b. General Scenario Rules	
	•	c. Analysis.	45
	2.	SCENARIO I: Simultaneous launched high-altitude and sea	
	-	skimming missiles	
	3.	SCENARIO II: Simultaneous launched sea skimming missiles	
	4.	SCENARIO III: Two simultaneous launched mobile sea skimming	
	r	missiles and a delay launched sea skimming missile	
	5.	SCENARIO IV: Simultaneous launch of shoulder missiles	
0	6.		
C.		ABAT SYSTEM DESCRIPTION AND ARCHITECTURE	
	1.	Design Statement	
	2.	Top Level Design Goals.	
D.	3.	Combat System Description and Capability	
- •			
		ECHANICAL, AND ELECTRICAL FEASIBILITY STUDIES	
		JALIZATION OF MAJOR SHIP CHARACTERISTICS AND	87
<b>B</b> .			•
C			89
C. D.		ST REDUCTION SUMMARY QUEST FOR ADJUSTMENT TO COST CEILING	
		SULT OF COST CEILING ADJUSTMENT PROPOSAL	
E.			
		CLAVED SHIP	
		CTORS AFFECTING EQUIPMENT COMBINATIONS	
B. VII SU	EN נסיכי	CLAVE ARRANGEMENT ELECTRICAL GENERATION AND DISTRIBUTION SYSTEM	97
		ESCRIPTORS	
A.	- INA	VAL ARCHITECTURAL CURVES	105

·----.

. . . . . . . . . . . . . . . .

----

		1.	Hull Geometry	
		2.	Hull Coefficients	
		3.	Displacement and other curves	
		4.	Static Stability	
•	B.	AR	RANGEMENTS	
		1.	Internal Arrangements	
		2.	Detailed arrangement	
		3.	Topside Arrangement	
	C.	HU	LL DAMAGE AND FLOODABLE LENGTH	130
-	D.	SH	IP STRUCTURE REPORT	
		1.	Ship Structural Loads	134
		2.`	Static loading	
		3.	Wave induced loading	142
	<b>B</b> .		NGITUDINAL STRENGTH	
	С.	RD	S 2010 ANALYSIS	149
	D.	MI	DSHIP SECTION DESIGN	
IX. J			EVALUATION	
REF				167
APP	ENI	DIX .	A DESIGN HISTORY	
			B PAYLOAD SELECTION MATRIX	
			C ELEMENT SELECTION MATRICES	
APP	ENT	DIX	D ASSET SUMMARY REPORTS	<b>D-</b> 1

- . .

## LIST OF FIGURES

Figure	e]	Page
1-1.	Design Timeline.	2
4-2	ASM Defensive Ranges	42
4-2.	PkSS of 5"/54 Mk 45 Gun System with IR fused round	50
4-3.	Scenario I.	55
4-4.	Scenario II	61
4-5.	Scenario III.	67
4-6.	Scenario IV.	
<b>4-7</b> .	RDS-2010 Combat System Connectivity Diagram	80
4-8.	Condition I Battle Organization	
4-9.	Condition III Battle Organization.	83
<b>4</b> -10.	Departmental Organization	85
6-1.	Enclave Boundaries.	99
<b>7-1</b> .	Bus Tie Diagram	101
7-2.	Load Center Locations	102
7-3.	Electrical System Interconnectivity.	103
8-1.	RDS-2010 Lines Drawing	106
8-2.	Hull Coefficients of Form	107
8-3,	Displacement And Other Curves.	109
8-4.	Static Stability Curve with Wind Heeling Arm	111
8-5.	Static Stability Curve with Turn Heeling Arm.	
8-6.	Damaged Static Stability Curve	
8-7.	03 Level General Arrangements	
8-8.	02 Level General Arrangements	
8-9.	01 Level General Arrangements	
8-10.	Damage Control Deck General Arrangements	
8-11.	2nd Deck General Arrangements.	
8-12.	3rd Deck General Arrangements.	
8-13.	4th Deck General Arrangements.	
8-14.	Primary CIC Detailed Arrangement	
8-15.	Pilothouse Detailed Arrangements.	
8-16.	RDS-2010 Topside Arrangements	
8-17.	Arcs of coverage for AAW self-defense weapons.	
8-18.	Arcs of coverage for ship's guns.	
8-19.	Arcs of coverage for ship's ASW defense weapons.	
8-20.	Floodable Length Curve	
8-21.	Static loads and structural response.	
8-22.	Static loads, shear, and bending moment.	141
8-23.	Typical wave induced ship loads.	144
8-24,	Coordinate description and sign convention.	
8-25.	Still water force curves.	
		****

8-26.	Hogging condition force curves.	
8-27.	Sagging condition force curves.	
8-28.	Still water force and bending moment curves.	
8-29.	RDS 2010 Midship section design	
9-1.	AAW Readiness Logic Diagram	160
9-2.	ASUW Readiness Logic Diagram.	161
9-3.	ASW Readiness Logic Diagram	162
9-4.	Mobility Readiness Logic Diagram	
9-5.	Enclave level survivability assessment.	

# LIST OF TABLES

Table	Ĭ	Page
2-1.	Primary Required Operational Capabilities	15
3-1	Element Selection List	27
4-1.	RDS-2010 Threat Weapons.	39
4-2.	ASM THREAT PHALANX PKILL	
4-3.	Scenario I	56
4-4.	Scenario II	
4-5.	Scenario III.	68
4-6	Scenario IV	72
4-7	Manning for the RDS-2010	84
5-1.	ASSET Ship's Design Summary, Initial Convergence.	88
5-2.	ASSET Summary, Final Run	89
6-1.	Location of Major Equipment and Functions by Enclave	
9-1.	Mission Readiness Rating Level Definitions.	

## I. INTRODUCTION

This paper is the final report for the Total Ship Systems Engineering (TSSE) student design project for the TSSE class of 1993. This report represents the compilation of all work performed over a two quarter period from October 1992 through March 1993. The various assignments and design products created have been integrated into this one design report to provide a detailed and comprehensive record of the work completed.

The design of the Regional Deterrence Ship (RDS) 2010 (formerly known as the Force Projection Ship (FPS) 2010) included all facets of a real design, though some detail had to be omitted in the interest of time and resource constraints. Overall, the project included the following major design phases:

- (1) Requirements Setting
- (2) Threat Environment and Analysis
- (3) Combat System Definition
- (4) Hull, Mechanical, and Electrical Feasibility Tradeoff Studies
- (5) Preliminary Design and Cost Analysis
- (6) Design Evaluation

The chapters of this report will include salient results of these design phases and other relevant material.

Figure 1-1 illustrates the timeline of the major evolutions which occured during the two quarter design effort. Appendix A contains the design history which chronicles the major design decisions associated with the various design phases.

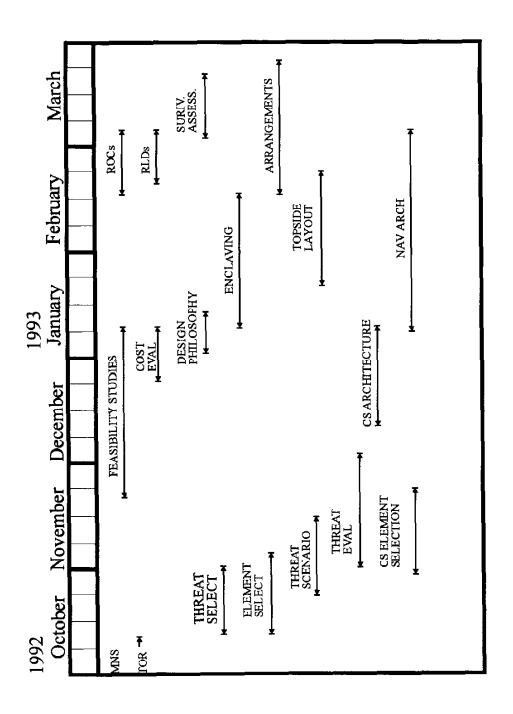


Figure 1-1. Design Timeline.

#### **II. REQUIREMENTS SETTING PHASE**

The requirements setting phase of the ship design process begins with the articulation of a need that is not being met by the current ship inventory. For this class, the professors acted as the "operators", representing the OPNAV structure. They articulated the geopolitical view of the world in the year 2010, with specific emphasis on the Naval roles and missions in this world view. Based on these roles and missions, they then postulated a Force Projection Ship (FPS) to meet a specific niche in the required U.S. defense posture. They defined in general terms the roles and capabilities of this envisioned ship, intending it to be the CNO top level guidance to kick off the design study.

The report provided by the professors is included in the pages which directly follow. The student design team was tasked to produce a requirements document for submittal to the CNO. This requirements document would then be given back to NAVSEA (the design team) to initiate feasibility studies for the FPS-2010.

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#### A. CNO TENTATIVE REQUIREMENT STATEMENT

#### 1. World View-2010 time frame

In terms of global reach, the world will be unipolar, with only the U.S. possessing meaningful global reach capabilities. The fundamental U.S. - FSU (Former Soviet Union) relationship will be one of cooperation--rather than competition--on most issues. This relationship, however, is becoming less important because the FSU is becoming fragmented to such an extent that, except for nuclear weapons capability, it possesses virtually no attributes normally associated with superpower status.

In regional terms, the 2010 world will be multipolar and the fundamental relationship among regional powers, on most issues of importance, will also tend to be more cooperative than competitive. The world will seem "kinder and gentler" in most respects, although potentially destabilizing developments will continue to bubble just below the surface in several of the world's traditionally troublesome regions. Any one, or a combination, of these could erupt and result in international crisis conflict in the near future.

- a. The U.S. Navy will continue to require the ability to:
  - operate in a forward-deployed mode, far from U.S. shores, for lengthy periods of time;
  - (2) project power ashore via tactical air power and cruise missiles;
  - (3) conduct opposed amphibious assaults;
  - (4) protect U.S. interests and U.S. nationals worldwide.

b. In this changed world, however, blue-water Naval engagements with a powerful adversary Navy will not be a threat. U.S. Navy operations are likely to have the following characteristics:

(1) take place mostly in littoral waters off the shores of nations which are now frequently referred to as "third-world";

(2) be of a peacekeeping or tension-reducing nature; Navy ships will find themselves introduced into volatile areas for the purpose of "cooling" down adversary nations within a region (transition from "peacetime" conditions to active engagement may occur without warning);

(3) be intended to remove U.S. nationals from trouble spots, or showU.S. resolve to protect its nationals as well as its other interests in the area;

(4) be part of a collective security organization (e.g. UN) sanctionenforcement effort and take the form of trade interdiction or embargo;

(5) consist of strike operations intended to "decapitate" an aggressor nation's war fighting capabilities, or opposed landings of limited size forces (up to Marine brigade size), or covert insertion of special forces;

(6) be challenged by nations with modern equipment (probably purchased from "first world" powers) in limited numbers; but operated in a skilled and determined way.

#### 2. FPS Role in 2010

The study team sees the role of the envisioned FPS-2010 as follows:

- a. lengthy deployment, world wide;
- b. operations in all oceans (but not in polar regions);
- c. either independent or Battle Group operations;
- d. AAW (self defense but not area defense) against attacks launched by third world nations;
- e. ASW against nuclear and non-nuclear submarines in shallow water;
- f. ASUW against third world surface naval forces;
- g. presence projection;
- h. keeping ports and choke-points open to peaceful sea borne commerce;
- i. support of special operations;

- j. destruction of high-value, land-based Military targets;
- k. support of amphibious assaults;
- 1. operations in mined areas;
- m. interdiction of contraband-carrying ships.

## 3. Political Considerations

It is clearly in the best interests of the United States to be able to intervene early in potential regional violence in order to avert it or, at least, affect the outcome. However, such actions will not be acceptable if they carry a high price tag--in dollars, in international political impact or in American lives. Therefore, a surface ship to fill these roles must be designed to minimize:

- a. the probability (and numbers) of crew member losses;
- b. the probability of loss of the ship;
- c. the share of the shrinking defense budget that the ships represent;
- d. the probability of causing damage to non-combatants or neutrals.

#### 4. Other

It is anticipated that 8 to 10 of these ships would be built.

#### Summary:

The design team's requirements document is included next. This is the result of a few iterations of submittals and revisions between NAVSEA (student design team) and CNO (professors). One major change that occurred during this process was a change in the name of the ship from *Force Projection Ship* (FPS) to *Regional Deterrence Ship* (RDS).

# B. REQUIREMENTS DOCUMENT FOR REGIONAL DETERRENCE SHIP (RDS) 2010

#### 1. General Description of Operational Requirement.

The Chief of Naval Operations (CNO) and Joint Chiefs of Staff (JCS) guidance for the Navy in the decade beginning in 2010 describes a change in emphasis and requirements for Naval combatants designed to be deployed in that time frame. The world will be unipolar with only the United States possessing meaningful global reach capabilities. The intense Cold War adversarial relationship with the republics of the former Soviet Union will have changed to one of cooperation on most issues. The republics of the former Soviet Union will possess virtually no attributes normally associated with superpower status, with the exception of their remaining nuclear weapons arsenal and capability.

The regional view of the world will be multipolar with the fundamental relationships between regional powers being more cooperative than competitive on most germane issues. However, potentially destabilizing developments will continue to simmer amongst nations in some traditionally troubled regions. As nations emerge from under unifying but repressive regimes, traditional ethnic strife will come to the forefront. These regional friction points could involve U.S. citizens and erupt into international incidents resulting in a crisis that draws in the United States.

To operate effectively in the world environment of 2010, a balanced Navy force structure is required which includes a Regional Deterrence Ship (RDS). The RDS 2010 is needed to meet the challenge of a reduced blue water threat while enhancing the capabilities required for operating in the coastal waters of third-world nations. The RDS 2010 will effectively show an American presence in any part of the world as a peacekeeping and tension reducing tool and show American resolve to protect U.S. citizens in a volatile region. Additionally, the RDS 2010 will be capable of operating as part of a collective security force with the ability to project power ashore while minimizing its own vulnerability and susceptibility.

#### 2. Threat

The U.S. Navy faces a threat in 2010 primarily from modern and capable weapon systems possessed and skillfully operated by third-world nations in limited regional engagements. These weapon systems are purchased from first-world powers such as the U.S., its allies, China and member states and former allies of the former Soviet Union. The capability, skill, and determined manner in which these weapons may be deployed, though contained to a limited region, must be appreciated. The RDS 2010 must be capable of successfully defending itself while penetrating this weapons environment to complete its tasks. Specifically, these threats include:

- a. air and surface launched anti-ship missiles with all categories of sophisticated homing techniques;
- b. surface and submarine launched torpedoes in shallow water engagements;
- c. waters mined with all varieties of mines;
- d. small and medium caliber gunfire from coastal patrol craft;
- e. biological and chemical agents;
- f. attempted boarding by determined and professional forces.

Third-world nations have possessed and used many of the above listed weapons and techniques with increasing frequency over the past twenty-five years.

### 3. Shortcomings of Existing Systems.

To support the Navy's mission against the threats enumerated in Sections II.B.1 and II.B.2, the present inventory of U.S. Navy ships and ship acquisition schedule is too costly considering the drastically reduced defense budget. Present ships in the inventory are either over designed to meet conventional aspects of the above threat, and thus too expensive to send into such an unconventional environment, or lack the fundamental capabilities to engage or survive encounters with the specific threat categories listed in Section II.B.2. Specifically, no ship in the current inventory will effectively:

- (a) conduct shallow water ASW;
- (b) support the variety of aircraft associated with joint/coalition style force structures;
- (c) transfer ("hand-off") AAW self-defense information between own-ship systems; or
- (d) remain in a high readiness condition for a prolonged period without crew performance degradation.

Additionally, since pre-attack threat recognition is nearly impossible and defensive reaction time is exceedingly short during hostile encounters in congested coastal waters, the probability of a hit is high. The present ship candidates available to meet the mission needs have inadequate self-defense and survivability features.

#### 4. Range of Capabilities Desired.

The RDS 2010 shall provide the following capabilities:

- a. sustain a six month forward deployment with a two week replenishment interval;
- b. completely integrated shipboard combat system;
- c. AAW self defense against limited intensity/duration attacks;
- d. ASUW against third world surface naval forces;
- e. ASW in deep and shallow water while employed independently;
- f. support amphibious assaults;
- g. attack high value land based military targets (both coastal and interior);
- h. receive real time targeting information from diverse sources;
- i. interdict contraband carrying ships;
- j. operate in mine infested waters;

- rapidly configurable C<sup>3</sup> system for interoperability with joint/coalition forces;
- 1. operate at highest readiness condition for two weeks at a time;
- m. operate in chemical, biological, and radiological environments;
- n. operate in all oceans, less polar, in at least sea state five;
- o. transit all major commercial shipping canals and waterways;
- p. maximum speed of 25 knots for 85 hours;
- endurance: 4000 nautical miles at 16 knots, followed by 20 days on
   station at 8 knots with a 400 nautical mile withdrawal distance at 6 knots;
- r. projected lifetime of 40 years;
- s. low signatures to avoid being detected, targeted or hit (enhance deception effectiveness.;
- t. have special features to enhance the ability to fight hurt;
- u. shock qualification required;
- v. semiautomatic intelligent damage control system with remote sensors;
- w. support short duration, covert operations;
- x. incorporate an appropriate SSES;
- y. support flight operations of non-assigned joint forces helicopters;
- z. carry a surgeon and have operating room facilities.

## 5. General Affordability Limits.

The acquisition cost of RDS 2010 will not exceed 500 million dollars.

## 6. Platforms/Quantities.

Approximately 10 ships will be built.

## 7. Integrated Logistics Support (ILS).

Two key factors drive the required maintenance support for this class of ship: (1) forward based maintenance assets are not anticipated, and (2) lengthy,

independent operations remote from other naval assets are anticipated. Therefore, incorporated into the ship design will be the following ILS features:

a. Built-In-Test-And-Evaluation (BITE) capability in all weapons, sensors, communications, and supporting vital equipment; Automated Test and Evaluation (ATE) capability to troubleshoot and fault isolate to replaceable components all removable and repairable circuit card assemblies; adequate manning and facilities to support micro-miniature component repair;

b. phased maintenance concept with a 15 year overhaul cycle for major system upgrades;

c. modular design of weapons, sensors and communications systems to facilitate system upgrades;

d. arrangement of machinery and equipment, including shipping/unshipping paths, to ease the change-out of equipment components and minimize adjacent system interference ripout (this facilitates at sea replacement and repair and lowers regular maintenance availability costs);

e. commonality of components for all ship systems, unless a significant loss of system performance would result;

f. automated component monitoring system in the engineering spaces to aid in phased maintenance planning and to minimize engineering watchstanders;

g. manning not to exceed 175.

#### 8 Related Efforts.

TASM capability will continue to be available. To support the maintenance needs of this class, a forward deployable tender capability will be maintained.

## Summary:

This requirements document kicks off the actual ship design process. These requirements are translated into desired operational capabilities which form the backbone of the ship design. The ability of the ship to perform these operational capabilities is a major judge of ship performance to design guidelines. The Required Operational Capabilities are included in the next section.

#### C. REQUIRED OPERATIONAL CAPABILITIES

Based upon the Range Of Capabilities Desired (Section II.B.4), the following primary and secondary Required Operational Capabilities (ROCs) and design requirements are delineated:

#### 1. Primary ROCs

- a. AAW self defense against limited intensity/duration attacks
- b. ASUW against third world surface naval forces
- c. ASW in deep and shallow water while employed independently
- d. rapidly configurable C<sup>3</sup> system for interoperability with joint/coalition forces
- e. receive real time targeting information from diverse sources
- f. operate in chemical, biological, and radiological environments
- g. operate in all oceans, less polar, in at least sea state five
- h. attack high value land based military targets (both coastal and interior)

### 2. Secondary ROCs

- a. support amphibious assaults
- b. interdiction of contraband carrying ships
- c. support short-duration covert operations
- d. incorporate an appropriate SSES

## 3. Primary Design Requirements

- a. operate in mine infested waters
- b. sustain a six month forward deployment with a two week replenishment interval
- c. completely integrated shipboard combat system
- d. operate at highest readiness condition for two weeks at a time
- e. operate in chemical, biological, and radiological environments

- f. operate in all oceans, less polar, in at least sea state five
- g. transit all major commercial shipping canals and waterways
- h. maximum speed of 25 knots for 85 hours
- endurance: 4000 nautical miles at 16 knots, followed by 20 days on station at 8 knots with a 400 nautical mile withdrawal distance at 6 knots
- j. have special features to enhance the ability to fight hurt
- k. semiautomatic intelligent damage control system with remote sensors
- 1. carry a surgeon and have operating room facilities

#### 4. Secondary Design Requirements

- a. projected lifetime of 40 years
- b. low signatures to enhance deception effectiveness
- c. shock qualification required
- d. support flight operations of non-assigned joint forces helicopters

Table 2-1 shows the primary required operational capabilities applicable to this ship as taken from standard Navy ROC definitions.

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#### **TABLE 2-1. PRIMARY REQUIRED OPERATIONAL CAPABILITIES.**

ANTI-AIR WARFARE (AAW). The destruction or neutralization of enemy air platforms and airborne weapons, whether launched from air, surface, subsurface, or land platforms.

- AAW 6 Detect, identify, and track air targets.
  - AAW 6.2 Recognize by sight friendly and enemy aircraft which may be encountered in expected operating areas.
  - AAW 6.3 Maintain accurate air plot.
  - AAW 6.4 Measure aircraft altitude with radar.
  - AAW 6.5 Detect, identify and track air targets with radar.
  - AAW 6.6 Acquire and track air targets with gunfire and missile control systems.
  - AAW 6.9 Conduct radar approaches for embarked aircraft.
  - AAW 6.\* Detect and track air targets with an infrared sensor.
- AAW 9 Engage airborne threats using surface-to-air armament.
  - AAW 9.1 Engage high speed, med/long range airborne threats with med/long range missiles.
  - AAW 9.3 Engage low altitude threats with missiles and gunfire.
  - AAW 9.4 Engage low/medium/high altitude airborne threats with gunfire.
  - AAW 9.7 Engage airborne threats using portable missile systems.

ANTI-SURFACE SHIP WARFARE (ASUW). The destruction or neutralization of enemy surface combatants and merchant ships.

#### ASU 1 Engage surface threats with anti-surface armaments.

- ASU 1.1 Engage surface ships with long range cruise missiles.
- ASU 1.2 Engage surface ships with medium range cruise missiles.
- ASU 1.4 Engage surface ships with major caliber gunfire.
- ASU 1.6 Engage surface ships with minor caliber gunfire.
- ASU 1.9 Engage surface ships with small arms gunfire.
- ASU 4 Detect, identify, localize, and track surface ship targets.
  - ASU 4.1 Detect, localize and track surface contacts with radar.
  - ASU 4.2 Detect, identify, and track surface contacts visually.
  - ASU 4.5 Detect, identify, and track surface contacts with infrared equipment.
  - ASU 4.6 Detect, identify, and track surface contacts by ESM.
  - ASU 4.7 Identify surface contacts.
- ASU 6 Disengage, evade, and avoid surface attack.
  - ASU 6.1 Employ countermeasures.
  - ASU 6.2 Employ evasion techniques.
  - ASU 6.3 Employ EMCON procedures.

ANTI-SUBMARINE WARFARE (ASW). The destruction or neutralization of enemy submarines.

- ASW 5 Provide for air operations in support of airborne anti-submarine operations.
  - ASW 5.1 Launch rotary wing aircraft involved in anti-submarine operations.
  - ASW 5.2 Recover rotary wing aircraft involved in anti-submarine operations.
  - ASW 5.4 Provide required conventional ordnance to support anti-submarine operations.
  - ASW 5.6 Conduct operations during all EMCON conditions.
  - ASW 5.7 Load/unload ordnance compatible with required aircraft turnaround times.
- ASW 7 Engage submarines with anti-submarine armament.
  - ASW 7.2 Attack with ASROC.
    - ASW 7.4 Attack with mortar/depth charges.
- ASW 8 Disengage, evade, avoid and deceive submarines.
  - ASW 8.1 Employ torpedo countermeasures and evasion techniques.
  - ASW 8.2 Employ acoustic countermeasures against submarines.

MOBILITY (MOB). The ability of Naval forces to move and maintain themselves in all situations over, under, or upon the surface.

- MOB 1 Steam to design capability and in the most fuel efficient manner
  - MOB 1.1 Steam at full power.
  - MOB 1.2 Steam with split plant operations.
  - MOB 1.7 Transit at high speed.
- MOB 3 Prevent and control damage.
  - MOB 3.1 Control fire, flooding, electrical, structural, propulsion, and hull/airframe casualties.
    - MOB 3.2 Counter and control CBR contaminants/agents.
    - MOB 3.3 Maintain security against unfriendly acts.
    - MOB 3.5 Provide damage control security/surveillance.
- MOB 7 Perform seamanship, airmanship, and navigation tasks.
  - MOB 7.1 Navigate under all conditions of geographic location, weather, and visibility.
  - MOB 7.2 Conduct precision anchoring.
  - MOB 7.3 Get underway, moor, anchor, and sortie with duty section in a safe manner.
  - MOB 7.4 Abandon/scuttle ship rapidly.
  - MOB 7.7 Provide life boat/raft capacity in accordance with unit's allowance.
  - MOB 7.15 Operate in chemically contaminated environment.

MOB 10 Replenish at sea.

- . MOB 10.1 Receive vertical replenishment.
- MOB 10.2 Receive fuel while underway (alongside method).
- MOB 10.3 Receive munitions and provisions while underway.
- MOB 10.6 Receive fuel while underway (astern method).
- MOB 12 Maintain the health and well-being of the crew.
  - MOB 12.1 Ensure all phases of food service operations are conducted consistent with approved sanitary procedures and standards.
  - MOB 12.2 Ensure the operation of the potable water system in a manner consistent with approved sanitary procedures and standards.
  - MOB 12.3 Maintain the environment to ensure the protection of personnel from overexposure to hazardous levels of radiation, temperature, noise, vibration, and toxic substances per current instructions.
  - MOB 12.5 Monitor to ensure that habitability is consistent with approved habitability procedures and standards.
  - MOB 12.6 Ensure operation and maintenance of all phases of shipboard environmental protection systems do not create a health hazard and are consistent with other naval directives pertaining to the prevention of pollution of the environment.
- STRIKE WARFARE (STW). Support the destruction or neutralization of enemy targets ashore through the use of conventional weapons. STW 3
  - Support/conduct multiple cruise missile strikes either independently or in support of other strike forces.
    - STW 3.2 Support/conduct conventionally armed cruise missile strikes.

COMMAND, CONTROL AND COMMUNICATIONS (CCC). Providing communications and related facilities for coordination and control of external organizations or forces and control of unit's own facilities.

- Provide own unit's command and control functions. CCC 3
  - Maintain a CIC capable of collecting, processing, displaying, evaluating, and disseminating tactical CCC 3.1 information
  - CCC 3.3 Provide all necessary personnel services, programs, and facilities to safeguard classified material and information.
  - CCC 3.4 Carry out emergency destruction of classified matter and equipment rapidly and efficiently.
  - CCC 3.5 Employ Identification Friend or Foe/Selective Identification Feature (IFF/SIF) secure IFF mode 4.
  - CCC 3.6 Coordinate and control the operation of remotely piloted vehicles.
  - CCC 3.8 Establish voice communications with U.S. Marine Corps (USMC) evacuation and command nets and Naval Support Activity (NSA) net.
- CCC 4 Maintain Navy Tactical Data System (NTDS) or data link capability.
  - CCC 4.3 Transmit/receive and support Link 11.
    - CCC 4.5 Receive and process data link information from Satellite Communication (SATCOM).
    - CCC 4.6 Receive and process data link information from High Frequency (HF) systems.
    - CCC 4.7 Receive Link 14 information.
  - CCC 4.10 Transmit/receive and correlate targeting information with Link 4A.
- CCC 6 Provide Communications for own unit.
  - CCC 6.2 Provide visual communications.
  - CCC 6.3 Provide multi-channel cryptographically covered teletype send and receive circuits.
  - CCC 6.4 Provide uncovered Radio-Teletype/Continuous Wave communications.
  - CCC 6.5 Provide full duplex cryptographically covered HF teletype circuits.
  - CCC 6.10 Provide voice/teletype/computer data cryptographically covered satellite communication circuits.
  - CCC 6.11 Establish and provide fixed combat communications and relay support for NSW operations.
  - CCC 6.12 Provide internal communications systems
  - Provide tactical, secure, anti-jam Ultra-High Frequency (UHF) voice communications. CCC 6.16
  - CCC 6.18 Provide tactical, secure, anti-jam HF voice communications.
  - CCC 6.19 Provide tactical, secure voice or data communications.
  - CCC 6.20 Provide internal Ship Signal Exploitation System (SSES) communications system.

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#### **III. INITIAL DESIGN DECISIONS**

At this point in the design process, several elements must essentially come together simultaneously. First, based upon the capabilities that this ship must possess and the political factors addressed in the requirements section, a prioritized listing of factors must be developed to aid the design team in the tradeoff and decision making process. This collection of priorities is known as the design philosophy.

While developing the design philosophy, initial thought is occurring on the types of technology and elements that we believe need to be placed on the ship to meet the aggregate of capabilities desired. This process includes drawing from the design team's experience base, researching design innovations in the literature, and examining existing equipment that may be suitable for inclusion on this ship. Some of the design innovations considered/desired are included in section two of this chapter.

This process culminates in the development of an element selection list, which is included in the third section of this chapter. The items on the element selection list are then examined, weighted, and judged to determine the elements that we believe will be most suitable for this ship design. It is not until after further stages of design effort that all of the elements can be deemed feasible.

#### A. DESIGN PHILOSOPHY

This design philosophy provides a prioritized listing of factors used in guiding design tradeoff decisions during all phases of the RDS-2010 design process. The factors selected and their relative weighting were governed by the *Requirements Document for RDS-2010* (Section II.B).

This design philosophy is intended for use exclusively by members of the RDS-2010 design team in determining tradeoffs and selections of design alternatives. Other uses or applications of this document are beyond the scope of its intent.

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Specifically, the Range of Capabilities Desired and General Affordability Limits

(Sections II.B.4 and II.B.5), lead to the following list of prioritized factors:

- 1. Cost, Acquisition
- 2. Combat System, Defensive
- 3. Vulnerability
- 4. Manning Reduction
- 5. Combat Capability, Offensive
- 6. **R**, **M** & A
- 7. Appearance
- 8. Signature/Detectability Reduction
- 9. Standardization
- 10. Upgradability
- 11. Sustainability
- 12. Environmental Impact
- 13. Future Growth
- 14. Habitability

## **Discussion**:

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(1) Cost, Acquisition - this factor ranked number one due to the severe budgetary constraints this ship must be designed and built under. Failure to account adequately for cost savings as a prime objective will most probably kill this project during the DOD and congressional approval levels of review. Cost is listed explicitly instead of some indirect parameters such as length, beam, draft, or displacement since cost control is the factor actually desired. Some may regard placing of the cost factor ahead of a military capability such as defensive systems as untenable, but it merely recognizes the reality of the current environment.

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(2) Combat System, Defensive - also known as hard and soft kill capability, this feature addresses one portion of the susceptibility equation. The ability to defeat an incoming threat is of paramount importance for decreasing the vulnerability of this ship. This capability should be considered essentially equal with cost reduction in importance.

(3) Minimizing Vulnerability - once the ship is hit, minimizing this ship's vulnerability ranks high in importance due to the ship's mission requirements. Operating close ashore in unstable world regions greatly increases the likelihood of unexpected, close aboard attack.

(4) Manning Reduction - in concert with minimizing ship's vulnerability and reducing acquisition cost, adequate consideration will be placed on minimizing ship's manning consistent with mission needs, available technology and damage control requirements. Manning reduction is primarily achieved through automation of functions in all aspects of ship operations including ship control, engineering plant operations, and war fighting operations. Design decisions to automate functions to reduce manning requirements will reduce vulnerability if all aspects of the vulnerability equation are properly taken into account. The largest counter point to reduced ship's manning is the impact on damage control capability. Present design and practice makes damage control operations 100% manual (hence, manpower intensive). Failure of current ship designs to take advantage of the technological innovations which could supplant or enhance the requirement for a crew member involvement in damage control operations may prove to be as significant a driver on crew size as watch, quarter, and station bill requirements. The salient point remains that merely automating operating stations and maintenance functions will not necessarily alleviate the crew requirement if active measures are not taken to address the requirements driven by damage control teams and damage control concepts.

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(5) Offensive Combat Capability - the RDS-2010 is not a major offensive strike platform, though any offensive capability which enhances the utility of the ship above and beyond the ship's tactical land strike mission requirements commensurate with the previous factors should receive consideration.

(6) Reliability, Maintainability, and Availability (R, M & A) - these design attributes are considered more important than the related areas of standardization, upgradability and sustainability, due to their impact on ship mission attainment and synergistic impact on manning reduction. Specifically, this ship's requirement to operate independently for sustained periods of time (no external maintenance support) make the reliability, maintainability, and availability of ship's equipment paramount.

(7) Appearance - the requirement of this ship to "show the flag" and perform the role of "presence projection" make design decisions affecting ship appearance a moderate attribute to be considered. Strong consideration should be made for design attributes which improve the "war fighting" appearance of the ship without excessive negative impact on the previous factors.

(8) Signature/Detectibility Reduction - ranked considerably lower than the other half of the susceptibility equation (defensive capability), these design features are not as important when taken in context with the ship's mission and probable operating theaters. Any design attributes which improve this factor without impacting previous factors should be considered, however.

(9) Standardization of shipboard components - since these features tend to drive up design and acquisition costs with little improvement in capability, this is not ranked high. This is a desirable attribute in cases where it can be obtained without disproportionate costs increases or in cases where it would dramatically improve aspects of R, M, & A. (10) Upgradability - this factor which is the ease of implementing improvements to existing systems is driven by accessibility and the system architecture. It is desirable but not enhancing to the ship's mission.

(11) Sustainability - enhancement above baseline design requirements for ship's sustainability should only be considered if they do not negatively impact previous factors.

(12) Environmental Impact - enhancements beyond regulatory requirements are of lesser importance than other factors.

(13) Future Growth - design attributes that enhance the ease and capability for addition of new systems impacts original system architecture and architectural design margins. This capability is not considered important in view of the ship's small size and mission.

(14) Habitability - embellishment of ship's living spaces are inconsistent with mission requirements and stated design goals of decreased vulnerability and increased R, M, & A. Embellishments include features such as false bulkheads and overheads, wall and floor coverings chosen for cosmetic purposes and any other features which would enhance the spread of fire, toxicity of smoke, impede or obscure access to equipment, cabling, ventilation ducting, piping or other ship's systems. Aspects of habitability which would benefit crew morale should be considered and primarily include the allocation of adequate living space for each individual and the capability of the individual to control the environment of their living space.

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#### **B. CONCEPTIONS AND INNOVATIONS**

During the early phases of any design process there are many ideas which are considered. The length of consideration may be limited to a few seconds or it may be extended through long discussions while determining what must be incorporated into the design. This section addresses some major ideas which the design team considered worthy of inclusion. The absence of a particular item from this section does not necessarily mean that it was overlooked or deemed unimportant. While some concepts were envisioned and dwelt on at great length, time and resources did not always permit the effort to proceed to as detailed level as would have occurred in industry.

#### 1. TOTAL SHIP INNOVATIONS

Extensive use of computers throughout the ship will smooth the flow of data and information and automate many low level routine tasks. Personnel will serve in a supervisory role to monitor the "system". Multi-purpose interface consoles will be used to the maximum extent possible in *all* system interface capacities. These would include a software driven interface with touch sensitive screens. Essentially, any system function will be available from any interface terminal with appropriate access control. This allows for easy system upgrade without requiring changes in hardware consoles and associated interface cabling.

Ship maneuvering functions will be controlled automatically. Tracks will be entered at the navigation console and controlled through an auto pilot. The auto pilot will be linked to the combat system for proactive defensive maneuvers and collision avoidance. Roll stabilization can also be incorporated through the use of the rudder.

A survivability management system will be used to smartly reconfigure systems in anticipation of a weapon hit and provide proactive damage control to minimize the spread of secondary damage.

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## 2. COMBAT SYSTEM INNOVATIONS

The ship's radar cross section is critical to the performance of the ship's defensive posture. The use of signature reduction technology in designing the ship's structure will significantly reduce detection ranges by redirecting incident energy away from the source. This enhances the effectiveness of decoys thus reducing susceptibility. As designers we can incorporate these ideas into our design by canting the ship's structure and providing storage compartments flush with the superstructure to remove topside clutter.

We envision a completely integrated combat system which includes all warfare areas. Each piece of equipment will be connected through a redundant, fiber optic multiring data bus. This will centralize information flow allowing any system to easily access the appropriate data on the bus. This will greatly improve the flexibility, survivability and upgradability of the system.

A Built-In Test and Evaluation module will be installed in every system to aid in minimizing system down time caused by failures and damage to system components. This would interface with another higher level system module, and by using System Readiness Logic provide up-to-date system status to operators. This would also provide a means to reconfigure the system for maximum combat readiness as required by tactical situations and doctrine planned into the software.

This ship has an expected life of 40 years. Historically, combat systems have been replaced every decade. Modular system design will be emphasized for ease of replacement, interface compatibility and for reduction in the cost associated with overhauls.

#### 3. AFFORDABILITY FEATURES

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Affordability was at the top of our design philosophy. Although production cost is only a small percentage of the overall acquisition cost, advanced production concepts will be used to achieve cost savings. This can be accomplished by reducing the cross boundary interface between production modules and minimizing the use of compound curvature requirements in steel work. Building zones need to be established early on so that the ship can also be built more efficiently.

In order to improve ship readiness for lengthy deployments we must improve the current maintenance philosophy. Designing this ship for a 15 year overhaul cycle and incorporating condition based maintenance should reduce system down time on patrol and improve operability. This statistically based replacement program will be accompanied by various new test methods in order to overcome some of the pitfalls experienced by the current generation of preventive maintenance. This process may incur a higher ship acquisition cost but will be significantly offset by a reduced life cycle cost. Standardization of components will also synergistically benefit the total ship through greater availability of parts and the requirement to stock fewer parts.

## 4. SURVIVABILITY FEATURES

Survivability features are integral to this design. The standard concepts considered to reduce the ship's susceptibility to a weapon's hit are threat warning, noise jamming and deception, signature reduction, threat suppression, use of expendables, and equipment to support the use of tactics. The standard concepts considered to reduce the ship's vulnerability are component redundancy or elimination, component location and/or shielding, passive damage suppression, and active damage control. Reduced manning also lowers the likelihood of casualties and reduces vulnerability. While manning reductions require additional acquisition investment for automation, there is a significant reduction in life-cycle cost associated with personnel. Designing with redundancy, the equipment capable of performing the same task, and enclaving together all equipment necessary for proper operation of that system will improve the damage tolerance of this design. This will be discussed in greater detail later.

A double hull design concept has great merit for the shell of this ship. The primary purpose of using a double hull is to reduce vulnerability. The significant addition of reserve buoyancy improves the ability to "FIGHT HURT". The inherent strength in the double hull design allows for reduced scantlings due to the higher section modulus, thereby reducing cost. The between skin distance will accommodate the latest in programmable welding technologies and provide for ease of inspection and maintenance.

#### 5. PROPULSION PLANT VISION

From the results of several studies that have been done on modern propulsion systems, we determined that the Integrated Electric Drive was superior from the perspective of survivability, reduction in total weight of the propulsion system, and ease of arrangement. The flexibility associated with arrangements would also reduce the vulnerability of the propulsion system. Since shallow water operations pose a higher likelihood of propeller damage, a controllable reversible pitch propeller is not considered the best candidate. The integrated electric drive combines well with the fixed pitch propeller because each reversible propulsion motor has a full range of speed control.

Combined diesel electric and gas turbine propulsion has many advantages as well. Although the specific weight and volume of this system is higher than a conventional gas turbine system, the fuel efficiency at patrol speeds could justify consideration due to reduced fuel payload.

#### 6. ELECTRIC PLANT VISION

Using today's technology ship service electric power can be generated from the variable frequency propulsion generators using solid state power converters. This power will be distributed throughout the ship using a ring bus, and each system will provide for its own specific voltage and frequency needs from the main power grid. Power management will be controlled automatically with smart load shed coordination with the combat system. System reconfiguration due to degraded capacity will be performed automatically to maximize available power consistent with the ship's tactical situation.

# C. ELEMENT SELECTION OPTIONS

Table 3-1 lists the element selections that resulted from our study of design innovations and available equipment for inclusion on the ship. In some categories, there are multiple choices which must be winnowed out during the early phase of the design process. Other categories list only a single item, indicating our conclusion that this item is required for inclusion on the ship.

Using the Element Selection List, a lengthy search was conducted for data pertaining to the specific elements. This data, when available, was used for performing detailed comparisons of functional capabilities and physical parameters. Appendices B and C contain some of the relevant portions of that study. In Appendix B, page one, the *Payload Selection Matrix* is shown. This matrix includes all of the elements considered by mission warfare area. For the proposed ship there are several cases where two closely related alternatives exist for some of the clements under consideration. Option 1 and Option 2 are described in chart form for a quick comparison. In rows two and three the elements which were selected based on the various decision matrices are listed. The pertinent decision matrices which led to those conclusions are included in Appendix C.

ON STREET PROTECTION

- A. HULL
  - 1. Туре
    - a. Single/mono
    - b. Double/mono
  - 2. Collective Protection System
- B. MECHANICAL
  - 1. Plant type
    - a. Diesel engines
    - b. Gas turbines
    - c. Combined diesel and gas turbine
    - d. Combined diesel or gas turbine
  - 2. Reduction gear
    - a. Mechanical (reversing, w/clutch)
    - b. Direct shaft coupled
    - c. Electric drive
    - d. Mechanical (non-reversing)
  - 3. Propeller
    - a. Variable pitch
    - b. Controllable and reversible pitch
- C. ELECTRICAL
  - 1. Generator system
    - a. Diesel
    - b. Gas turbine
    - c. Propulsion derived
  - 2. Distribution system
  - 3. Power management system
  - 4. Emergency power system

#### D. COMBAT SYSTEMS

1.

- Detection/sensors
  - a. Air: SPS-48/49/IFF, Low budget phased array
  - h. Surface search: SPS-67 family
  - c. IR search: SAR-8
  - d ESM: SLO-32(V)3
  - e. Sonar: High resolution hull and remote, SQS-53 (low budget)

- f. LAMPS III
- g. Acoustic intercept: WLR-9,
- SRS-1 (Combat DF)
- h. Mk 23 (TAS)
- i, KAS-1 (CWDD)
- 2. Command and decision
  - a. NTDS (Link 11)
  - b. WSA 423 C&C
  - c. ACDS
- 3. System information coordination
- 4. System readiness coordination
- 5. External communications: WQC,
- HF, UHF, VHF, SATCOM, JITDS, JOTS
- 6. Interior communications
- 7. Weapon control
- a. Mk 92 FCS
  - b. Mk 91 FCS
- 8. Navigation
  - a. Furuno, LN-66, SPS-64
  - b. GPS, SATNAV
  - c. TACAN
  - d WRN-5,
- 9. Engagement/weapons/countermeasure a. Missile /Point defense: RAM, NSSM, SM-1/2, CIWS Mk 15, Goalkeeper, Stinger missile turret
  - b. Gun: 5" -54 cal Mk 45 gun, Mk 24 TDT, OTO 76mm gun, 25mm
  - Chain gun, 7.62mm mini-gun
  - c. Torpedo: SVTT Mk 32, Mk 50
  - d. Depth charge system: RBU/
  - Hedgehog (upgrade)
  - e. Tomahawk VLS/ Harpoon
  - f. CM: Mk 38 decoy launcher,
  - SRBOC, LAD Chaff, 3" rocket decoys

g. Anti-torpedo defense: Talisman, Nixie, NAE, ADC, CSA

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10. Remote vehicle mine hunter/avoidance

The second page of the *Payload Selection Matrix* (Appendix B) includes all of the elements considered by equipment categories. Page two of Appendix B contains all equipments/systems considered whereas page one only lists those associated with a specific warfare area. This step of the process addressed the elements, but not the quantity or arrangement of them. The intent is to determine the most cost effective (dollars, weight, area, etc.), yet capable equipment/system to meet the required capabilities as delineated in the CNO Tentative Requirement Statement. When two elements under consideration had a wide host of utility factors for comparison, it occasionally seemed appropriate to have a second alternative based on factors such as cost, weight, political mood, logistical commonality. The combat system elements have undergone a preliminary threat evaluation consisting of four diverse scenarios. This threat evaluation is presented in the next chapter as part of the Combat System Definition. The reasoning for the decisions which were agreed upon by the design team are described below, supported by Appendices B and C.

#### 1. HULL

#### a. DOUBLE HULL vs. SINGLE HULL

Major issues: Passive protection, survivability, displacement, and cost Minor issues: Ease of arrangement and producibility (ease of fabrication)

Proposed is the advanced double hull design (ADHD) concept which consists of two shells connected by longitudinal web girders and floors. Simply put, it will resemble the corrugated design used in designing high toughness, high strength cardboard boxes. Transverse frames and longitudinal stiffeners can be eliminated because of the inherent strength achieved by the cellular concept. Benefits include reduced vulnerability in the event of a hull impact, higher hull girder stiffness based on higher section modulus and greater producibility (easier to fabricate, insulate, outfit, and paint) with a projected cost savings of 8-12% now with further savings inevitable during maintenance periods. The

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between skin distance will be large enough to accommodate the latest programmable welding technology and to provide for ease of inspection, maintenance and preservation.

Disadvantages: 1% increase in displacement for the double hull design.

# b. Collective Protection System

First option is to install a full collective protection system. Based on total ship impact (cost, weight, etc.), the system may be degraded to include two or three zones. This concept dovetails with the intent to enclave the ship into three to five enclaves. Ideally, each enclave will have collective protection, though if this becomes unreasonable from a size and weight (and thus cost) point of view, then selective collective protection sub-enclaves will be considered. Primary focus will be to maximize the mission readiness of the ship when collective protection zones are detailed.

# 2. MECHANICAL

# a. Plant Type (Including Transmission)

Several exhaustive studies have been conducted in order to determine the optimum power plant for destroyers and frigates [Ref. 1, 2, 3 and 4]. The term power plant here is used to include both propulsion and electrical plant. Factors addressed in these studies included:

- (1) Propulsion and Electrical Plant Weight
- (2) Propulsion and Electrical Plant Volume
- (3) Power Plant Survivability
- (4) Sustained Speed Margin
- (5) Ship Top Speed
- (6) Ship Detectability
- (7) First Cost (Power plant)
- (8) Life Cycle Cost (Power plant)

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(9) Crew Size (Engineering)

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- (10) Energy Consumption
- (11) Ship Displacement & Volume
- (12) Ship Operability (Ease of Control)
- (13) Complexity
- (14) Standardization of Components
- (15) Technical Risk

Evaluation criteria included many factors. The initial cost factor had highest priority. Risk and standardization of components had low priority in one of the studies. All of the other factors had medium priority. All of the studies showed that mechanical drive systems were inferior to the electric drive system options based primarily on weight and ease of arrangement. Some of the combined diesel and gas turbine systems had low energy consumption rates, though they were not rated well overall. A medium speed diesel may have an efficiency as high as 46% while a gas turbine has an efficiency of about 35%. On the other hand, a medium speed diesel may have a specific weight of 25 lb/HP, while the gas turbine specific weight is 3.5 lb/HP. These two factors give just a brief glimpse of why a very thorough study such as [1] is needed. Primarily, this study was used to determine which propulsion plant was optimum for this new ship class. The innovative and expensive podded propulsor seemed to be optimum in some cases, but considering that the low cost RDS 2010 must be capable of operating in mine infested shallow waters it does not seem a worthy candidate for this ship design. In order to obtain a balanced total ship design, a second propulsion plant candidate may have to be considered. The two options are addressed below.

# (1) Option 1: Gas turbine integrated electric drive system

System consists of multiple propulsion gas turbines generators (PGTGs) supplying a propulsion power bus. Additional smaller gas turbine driven generators may be needed for efficient low speed cruising conditions. Ship's electric power

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needs will be derived from the propulsion bus via solid-state power converters. This system allows maximum flexibility in machinery plant layout to allow dispersion of components within the hull to decrease ship vulnerability.

#### (2) Option 2: Combined diesel electric and gas turbine electric drive

This combined diesel electric and gas turbine electric drive (CODLAG) system has the potential of increased plant efficiency at low cruising speeds based on a lower specific fuel consumption (lb/hp-hr), yet still provides the flexibility in machinery plant arrangement that is available with gas turbine electric drive. Additionally, this system may lead to smaller volume/fewer intakes and uptakes. The disadvantage of this system would be higher specific volume (ft<sup>3</sup>/hp), specific weight (lb/hp) and initial ship cost (\$).

# b. Propeller - Variable Pitch vs. Controllable Reversible Pitch (CRP) This decision is based on :

(1) the fact that the electric drive motors are reversible and have fullrange speed control; and

(2) shallow water operations pose a higher likelihood of propeller damage, making a CRP propeller too high a risk (not robust enough).

#### 3. ELECTRICAL

#### a. Generation Scheme

Electric power for either option will be derived from the propulsion power bus via solid-state ac-ac power converters.

#### b. Distribution system

The propulsion power bus will be a standard ring bus configuration for maximum flexibility and reliability. It is not perceived that propulsion power will be distributed to portions of the ship in which it is not required. The load power bus will also be a ring configuration. The electric loads will be supplied from solid-state power

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converters located in each enclave, with redundant capability to supply other enclaves (and vice versa).

#### c. Power management system

Power management will be controlled automatically with smart load shed coordination with the combat system. System reconfiguration due to degraded capacity and capability will be performed automatically to maximize available power consistent with ship's tactical situation. Deriving the ship's service electrical power from the propulsion generators allows the capability to momentarily divert all propulsion power from propulsion to ship's service to support critical combat systems operations during system reconfiguration.

#### d. Emergency power

There will be no dedicated emergency power system, though generator sizing and quantity will allow sufficient capacity for some generation capacity to remain in standby during full load conditions.

# 4. COMBAT SYSTEMS

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# a. Detection Systems/Sensors

# (1) Air Search Radar

Several studies were performed comparing the SPS-48, SPS-49, Mk 92, and a Low Budget Phased Array (LBPA) radar systems. The LBPA is envisioned to be of the Aegis style, yet with reduced capability and cost. The system characteristics, weight and cost were compared and weighted so that cost and weight were of primary importance. Summaries of the analyses are included in Appendix C under the heading of *Primary Air Search Sensor Matrix* and *Secondary Air Search Sensor Matrix*.

(a)	<b>Option 1</b> :	Primary: SPS-49	Secondary: Mk-92
(b)	<b>Option 2</b> :	Primary: SPS-49	Secondary: SPS-48

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#### (2) Surface Search Radar

The SPS-67 will be employed as the primary surface search radar with the primary navigation radar, the SPS-64, as the backup.

(3) IR Search

The SAR-8 will be used for infrared detection and tracking.

(4) ESM

The SLQ-32(V)3 will be used.

(5) Sonar

(a) The SQS-53 (low power/low budget) hull mounted sonar will be used. The Kingfisher mine hunting adjunct to the SQS-53 will be available before letting of the contract, so the technical risk in this area has diminished significantly. One concern, however, is that the SQS-53 sonar in general is too powerful in omni-directional and Sector Search modes for shallow water ASW missions, which is its primary purpose. However, a localization mode by beam steering could be used in shallow water with only minor degradation. A variant needs to be designed which will allow omni directional operation at low power.

(b) The Light Airborne Multi-Purpose helicopter (LAMPS III) will be the primary off hull sonar system for submarine detection and targeting with the Unmanned Undersea Vehicle, UUV, as the primary off hull mine hunting sonar system. The UUV is under risk of being dropped form the RDS 2010 class because of its high cost and low mission utility for the expected threats.

#### (6) Acoustic Intercept Receiver

The WLR-9 will not be used for detecting incoming torpedoes, since this function is inherent to the surface ship torpedo defense system (SSTD).

# (7) Chemical Detection System

The KAS-1 chemical warning directional detector will be used.

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#### b. Command and Decision

An integrated Command and Decision system will need to be designed around the specific elements of the combat system.

#### c. System Information Coordination

An integrated System Information Coordination system will need to be designed around the specific elements of the combat system.

#### d. System Readiness Coordination

An integrated System Readiness Coordination system will need to be designed around the specific elements of the combat system.

# e. External Communications

The communications suite will consist of the following types of equipment to perform the functions currently done by underwater telephone, HF, UHF, VHF, and SATCOM transmitters and receivers. Additionally the suite of COPERNICUS architecture will include JTIDS, JOTS and SSES capabilities. It is conceived that these elements will be housed in panels, enclaved throughout the ship and that a radio room as we know it today will not exist. Data links for ship-ship and ship-shore data transfer will also be required.

# f. Interior Communications

The interior communications system will consist of a fiber optic digital multiplexing system for voice and data distribution and traditional sound powered phone circuits for robust, damage control voice communications.

#### g. Weapon Control System

An integrated Weapon Control System will need to be designed around the specific elements of the combat system.

#### b. Command and Decision

An integrated Command and Decision system will need to be designed around the specific elements of the combat system.

## c. System Information Coordination

An integrated System Information Coordination system will need to be designed around the specific elements of the combat system.

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The interior communications system will consist of a fiber optic digital multiplexing system for voice and data distribution and traditional sound powered phone circuits for robust, damage control voice communications.

# g. Weapon Control System

An integrated Weapon Control System will need to be designed around the specific elements of the combat system.

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#### h. Navigation System

The navigation system will consist of SPS-64 as the primary radar system, and the Furuno as the backup radar system. TACAN will be required as helicopter support. A study of this mission area was performed and is included in Appendix C as the *Navigation Radar Matrix*. Although the SPS-64 did not rate as well as the LN-66 or the Furuno overall, it was chosen as the primary navigation radar since it can send data to the fire control system and serves as the backup to the SPS-67 in the ASUW mission area. The Furuno and the LN-66 radar are essentially commercial grade, low cost navigation radars with no capability to be interfaced with the ship's combat system. They are useful in providing a low-cost navigation backup capability, however.

#### i. Engagement/Weapons

#### (1) Long Range Intercept Missile

The SM-1/2 family of missiles will be used for long range intercept of air and surface targets. The *Missile Selection Matrix* in Appendix C shows how the candidate's ratings compared.

#### (2) Short Range Intercept Missile

The RAM (RIM-116) series of missiles will be used for short range intercept of airborne targets.

#### (3) Anti-ship Missile

The Harpoon missile will be used, including the upgraded IR version of Harpoon, the Sea Launched Attack Missile (SLAM) version.

#### (4) **Point Defense system**

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The Phalanx (MK-15) CIWS will be used for ultra-short range airborne target intercept. The CIWS Selection Matrix in Appendix C shows how the candidate's ratings compared.

#### (5) Naval Gunfire Support

(a) Option 1: The 5"-54 Mk-54 medium caliber gun provides a higher weight round and slightly improved range over option 2, but has a lower firing rate and double the weight. Use of the autonomous Naval strike round (ANSR) has the potential of increasing range to 50 nm, however at a significant cost increase per round.

(b) Option 2: The 76 mm Oto Melara medium caliber gun provides higher firing and training rates, but the round weight is one-fifth the weight of a 5" round. The Medium Caliber Gun Selection Matrix in Appendix C shows how the candidate's ratings compared.

#### (6) Small Caliber Gun

(a) The 25 mm Chain gun will be used.

(b) The 7.62 mm minigun will be used.

# (7) Land Strike Missile

The Tomahawk Land Attack Missile (TLAM) will be used. With the system installed, it will be possible to use the Tomahawk Anti-Ship Missile (TASM).

# (8) Anti-Torpedo Defense

The new Surface Ship Torpedo Defense (SSTD) system will be

used.

# (9) Torpedo

The Mk 50 Barracuda torpedo will be launched from the SVTT Mk 32 torpedo tube by the Mk 116 Fire Control System or a new fully integrated fire control system. In addition, the LAMPS helo has the capability to launch torpedoes.

# (10) Depth Charge/Mortar System

The Soviet RBU-6000 and the antique US Hedgehog mortar systems are very heavy (30,000 lb loaded launcher) and would impose a significant impact on the RDS 2010. The need for this type of system still exists based on the fact that a Mk 50 torpedo acquisition of an enemy submarine in shallow water has a lower than desired probability. A new light weight launcher is necessary since the Hedgehog is limited in range to 270 yards and a submarine's location could likely be determined at a longer range. Ideally, the LAMPS or UUV will assist in locating the submarine and the integrated fire control system would launch mortars aimed at a specific coordinate and set to explode at a designated depth. It is recommended that OPNAV assign a study group to determine the usefulness of deploying this type of weapon against submarines in shallow water.

- j. Countermeasures
  - (1) ECM

(a) Based on the perceived threat, all of the countermeasures which were considered will be used and launched using the Mk 36 Super Rapid-Blooming Chaff (SRBOC) Launcher. These included Launched Active Decoy (LAD), SRBOC, and TORCH. These expendables will provide protection against missiles with active and passive radar and infrared homing systems. Most of the new countermeasures currently being developed will be launchable with this launcher.

(b) The SLQ-32(V3) provides ECM capabilities.

#### (2) Sonar Acoustic

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The outdated Talisman and Nixie were compared and found to be similar except Nixie weighs 50% less. Additionally, the new Surface Ship Torpedo Defense (SSTD) will be operable by the year 2000. This system contains both active and passive defense measures and will be used on the RDS 2010 instead of the towed noisemakers and launched submarine style noisemakers (ADC, CSA and NAE).

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# **IV. FEASIBILITY STUDIES - COMBAT SYSTEM DEFINITION**

The next phase of the design process is defining the combat system. This is the first part of performing the feasibility studies. Since the combat system represents a major payload of the ship, the determination of the specific elements chosen for the combat system is required to proceed on with the Hull, Mechanical, and Electrical Feasibility Studies. The size, weight, location, power and other auxiliary service requirements of the payload, when combined with the performance requirements of the ship, will in many respects define the ship's HM&E characteristics.

Final selection of the combat system elements which comprise the combat systems suite of the RDS-2010 is an iterative process of selecting candidate combat system elements and then evaluating their ability to defeat threat weapons in plausible threat scenarios. Based upon the results of the threat scenario evaluation, adjustments can be made to the combat system elements. In addition, the minimum number of engagement elements are determined from the threat scenario evaluation.

In this chapter, the threats are first defined. Plausible threat scenarios are then presented to evaluate the ability of the candidate combat system elements chosen in the last chapter. Based upon this evaluation and the ability of the combat system elements to defeat the proposed threats, the minimum number of combat system elements can be chosen in the context of defeating the threat in the specified scenarios. This determination of number of combat system elements does not include the consideration of redundancy for reliability or survivability reasons.

#### A. THREATS

A survey was completed of the current threat weapon inventory using Naval Postgraduate School library resources. Based upon this survey, a number of threat weapons were developed that were felt to be similarly challenging as the actual threats.

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This procedure, however, allowed the design team to keep this portion of the design process unclassified. Table 4-1 lists the threats that will be used to determine the combat system performance for the RDS-2010.

TABLE 4-1. RDS-2010	THREAT WEAPONS.
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Туре	RPS 2010 Designated	RADAR Cross-	Speed	Range	Warhead Yield	Guidance	Profile Trajectory
	Enemy Name	Section (m²)	(mach)	(nm)	(kg)		( Hajeo Kin y
Missiles	THRASHER (A-S)	0.013	2.5	40	10	Passive Radar	Homes on Radar
	TAKEOVER (A-S)	0.7	3.4	300	1000	Active or Passive Radar	High Alt. w/50° terminal dive to target
	SEAGULL (S-S)	0.22	0.7	15	110	IR	15 meter sea skimmer
	SUNSTROKE (S-S)	0.1	2.5	65	450	Active Radar	10 meter sea skimmer w/1° dive
Subsurface	Small Mines	R≖1 ſt.				Various	
	Mk48		55 kts	35 kyds			
	Spearfish		70 kts	18 kyds			

**AIR/SURFACE/SUBSURFACE THREATS** 

#### **B. THREAT SCENARIOS AND EVALUATION**

In this section, the threats are combined with likely engagement actions to form plausible engagement scenarios. The scenarios consist of specified threat weapons launched at the ship. The number, range, and bearing of the threats were picked to match likely encounters in the suspected operational area in which this ship will be patrolling.

Due to time and resource constraints, only four AAW scenarios were evaluated. In actuality, additional scenarios would have to be developed and evaluated in the other warfare categories (ASUW, ASW, and mine warfare).

One of the most challenging defensive capabilities of the RDS-2010 ship is the defeat of the Anti-Shipping Missile (ASM) threat. Conflicts within recent memory have proven the effectiveness and lethality of the ASM threat, including the susceptibility of warships to damage. The solution to Anti-Shipping Missile Defense (ASMD) demands a mix of

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defensive concepts, including such hard kill weapons as missiles, guns and high-energy directed energy weapons be deployed in addition to other defensive systems such as ECM, ECCM, and decoys. Note that the success of these types of ASMD systems requires an overt and explicit effort in applying the techniques of vulnerability reduction to the ship to reduce its susceptibility to damage by ASM debris at the mission or firepower kill levels. Also, success of the ASMD system chosen for the ship requires the adoption of tactical plans and procedures tailored to the changing ASM threat.

The ASMD elements chosen for the RDS-2010 include:

- Missiles SM-1/2 and RAM
- Guns Mk15 Phalanx and Mk 45 5"/54
- ► ECM SLQ-32 (V3)
- CHAFF

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This section presents the results of the study of four diverse Anti-Air Warfare (AAW), defensive threat scenarios (specifically, ASMD) and is to be used in conjunction with the previous chapter's section on element Selection Options. Specifically, this section is used to determine and validate choices for the minimum number of missiles, types of missiles, guns, and close-in protection systems required to separately defeat the four surmised threat scenarios. Modifications to these quantities may and probably will occur as the design progresses. The threat ASMs used in these scenarios were defined in the previous section of this chapter.

Only AAW threat scenarios are presented. This does not imply that the ASW, ASUW, or mine-countermeasures are not important or not in need of study. Resource and time constraints, however, preclude similar studies in these defensive areas. The basic methodology present in this report would also be used to study these other defensive warfare areas, however.

#### **1. Background Development**

Performance of ASMD analysis, the ability to defeat an attacking ASM, is normally expressed in terms of the ability to protect the defending ship from damage. The acceptable level of ship damage is not well defined yet, though for the RDS-2010, this is considered a severe constraint. Emphasis is placed on defeat of the ASM threat vice accepting resulting damage from a "leaker".

In general, the capability to defeat a target is expressed as:

$$P_{k} = P_{S} = P_{S/D} \cdot P_{D} + P_{S/ND}(1 - P_{D})$$
(4-1)

where:

 $P_k$  = probability of target kill (or defeat),  $P_S$  = probability of ship survival at the kill level of interest,

 $P_{S/D}$  = probability of ship survival given that the ASMD system causes damage to the target,

 $P_{S/ND}$  = probability that the ship will survive given that the ASMD system does not damage the target (i.e., the inherent survivability of the ship), and

 $P_D$  = probability that the target is damaged.

Clearly, (4-1) implies an assessment of the RDS-2010 ship survivability is inherent in quantifying a weapon's system capability to defeat the ASM threat. This is not included in this report, though a goal of "zero hits" for the RDS-2010 is desired in response to the *Requirements for Regional Deterrence Ship (RDS) 2010* (Section II.B).

The ASM defensive range can be roughly divided into three zones as depicted in Figure 4-1. The long range defensive system for the RDS-2010 is the SM-1/2 and associated Fire Control System (FCS). In the long range intercept game plan, the ability of the ASM to penetrate to the vicinity of the ship after intercept by the long range system is indicative of a lack of a kill. Indeed, standard practice criterion for long range system target defeat is not only ship protection, but damage to the ASM such that ship protection

is guaranteed to the point where no further weapons must be addressed to the target in question. This kind of damage requirement is used to conserve expensive and volume consuming long range weapons by allowing the FCS or kill assessment system to identify a target kill and address the next weapon to the next most threatening target.

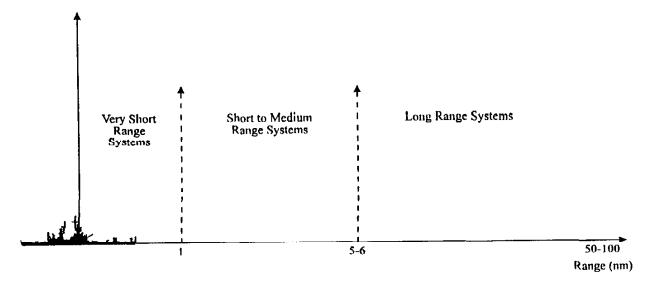


Figure 4-1. ASM Defensive Range

For short and medium range systems (SM-1/2 and RAM), the observable kill<sup>O</sup> criterion does not apply. Evaluation of systems tests versus flying targets indicate that five to fifteen seconds are required in many cases to allow positive identification of a target kill, even under the classic catastrophic kill level. This means that for medium to short range systems, this time delay in kill identification may defeat the purpose of requiring observable kills. The defensive missile time-of flight (TOF), when coupled with the target speed, results in a very short second encounter requirement. Clearly, a shoot-shoot-look

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<sup>&</sup>lt;sup>a</sup> An observable kill is any damage to the ASM. Note that the characteristics of target reaction which is *observable* to the FCS or weapons assessment system is a function of the system performance criteria. For this reason, a more conservative evaluation of the required target damage observable to the kill assessment system is the *catastrophic kill* level (described as the classic nearly instantaneous breakup of the target).

engagement scenario is required in this situation. The required level of target damage produced for medium-to-short range encounters is considered to be at the catastrophic kill level.

For very short range ASMD (often known as "last-ditch" effort), the RDS-2010 employs the MK15 Phalanx system. In this scenario, even catastrophic target damage may not always protect the ship. Issues such as target speed, mass, and ship-to-target geometry at ranges under one nautical mile often couple to result in some level of ship damage from the debris of the destroyed ASM. Indeed, for very short range systems, the assessment of likelihood of own ship survival takes on a new meaning. The system must damage the incoming ASM such that either (1) it misses the defending ship by such a distance that upon water impact the air and water shocks produced by detonation of the warhead result in low probability of ship damage; or (2) target breakup occurs at such a range that the resultant particles either can not reach the ship or do not have a significant capability to produce ship damage upon impact.

The focus of this section of the report is the determination of *hit* and *kill* probabilities of incoming threats with the weapons systems employed on RDS-2010. The probability of hit,  $P_{H}$ , implies the likelihood that the kill mechanism or damage producing agent(s) employed by the defensive system interact with the target at some level of intensity. The actual methods to determine  $P_H$  by determining this level of intensity is beyond the scope of this discussion. Realize, however, that determination of  $P_H$  is comprised of inputs from such varied areas as target detection, tracking, fire control characteristics, pointing accuracy, weapon characteristics (ballistics, aerodynamics, etc.), reliability, maintainability, fuse characteristics, ECM environment, weather, target performance, and warhead characteristics. Fortunately, seldom do all these factors have to be considered simultaneously.

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For the analysis conducted in this section, many gross simplifications are employed to allow solution of the problem with available data and techniques. The purpose of this phase of the design process is to delineate the basic analysis technique which is used for a "first-order" evaluation of the RDS-2010 combat system effectiveness against proposed scenarios. The remainder of the section is organized with a general procedural and calculation summary used for the analysis, followed by specific analysis of four threat scenarios. These scenarios were chosen to be representative of a diverse range of ASM threat situations that could likely be encountered based on the guideline contained in the *Requirements for Regional Deterrence Ship (RDS) 2010* (Section 11.B). Finally, a summary of the results is presented with recommended weapon types and load out with supporting combat systems elements.

#### a. Assumptions

Of general note, the inbound target is assumed to be non-maneuvering, with exception of the terminal flight phase prior to impact. Also, a target hit is considered a kill.

# (1) Radar Horizon

For the scenarios considered a conservative assumption is made that the radar horizon is 15 nautical miles at the surface. The radar horizon equation is given by:

$$rh = 1.667 \left( \sqrt{H_{target}} + \sqrt{H_{radar}} \right)$$
(4-2)

where: rh = radar horizon in nm,

 $H_{target}$  = height of target above surface in feet, and  $H_{radar}$  = height of own radar above surface in feet.

Assuming a target height of zero feet and a 15 nautical mile radar horizon, (4-2) is solved for an own ship radar height of 81 feet. This is the minimum height for the surface search radar. (2) Operational Arcs.

The ship's weapon and sensor systems are assumed to have a 360° clear arc of fire and detection capability°.

(3) Combat System Readiness

It is assumed that the combat system is in a full readiness condition.

## b. General Scenario Rules

To ascertain whether a particular threat can be engaged, the following ground rules are used:

(1) A minimum ten second time delay is assumed from time of detection to time of engagement. This time delay accounts for the lag in:

(a) processing and passing information from the search radar to the Fire Control System (FCS);

(b) the illuminator locating the target and passing information to the FCS; and

(c) the operator intervention occurring prior to the Weapon Control System (WCS) automatically launching the long range engagement weapon. If the operator fails to intervene within the allotted ten seconds, the ship can still command destruct the weapon.

(2) A delay of four seconds is used from the time-of-kill assessment to the time of weapon re-engagement.

c. Analysis.

The following assumptions, equations, and values were used to calculate the probabilities of kill, the probabilities of hits, and the expected number of hits.<sup>o</sup>

<sup>1</sup> It is understood that the 360° clear arc of fire and detection, and the 15 nm radar horizon are assumptions that will require modification once the ship's superstructure has been defined.

<sup>&</sup>lt;sup>o</sup> The methodologies employed in this portion of the report are taken from a MIT Professional Summer Course entitled Surface Ship Combat System Design Integration, presented August 5-9 1991 at the Draper Laboratories in Cambridge, Mass.

(1) General

ship:

defined:

(a) Assume three basic self-defense systems are integral to the

- (i) missiles,
- (ii) guns, and
- (iii) jammers/decoys.

(b) Assume an incoming missile will **not** hit the ship if and only if at least one of the defensive systems is successful (i.e., the threat weapon will function as designed and will hit the ship unless explicitly defeated by own ship defensive systems).

(c) For the probability formulations, the following events are

Let A be the event that the defensive missile is successful.

• Let B be the event that a gun system is successful.

Let C be the event that the incoming missile is decoyed/jammed.

(d) The cumulative probability that at *least* one system is successful against each incoming missile is described in general by the cumulative probability formula given by:

$$P(CUM) = 1 - \prod_{i=1}^{n} (1 - P_k(i))$$
 (4-3a)

where: P(CUM) = cumulative probability of a kill by *n* kill mechanisms, and

 $P_k(i)$  = probability that the *i*<sup>th</sup> kill mechanism succeeded.

For the specific cases presented in this report with three kill-systems, the cumulative kill probability is given by:

$$P_{kill,threati} = 1 - [1 - P(A)][1 - P(B)][1 - P(C)]$$
(4-3b)

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where:  $P_{kill,threat i}$  = cumulative probability of defeating the *i*<sup>th</sup> threat,

P(A) = probability that a defensive missile is successful,

.

P(B) = probability that a gun is successful, and

- P(C) = probability that a jammer/decoy is successful.
  - (e) The probability that the ship will take a hit is given by:

$$P(hit) = 1 - \prod_{i=1}^{n} P_{kill, drest i} .$$
(4-4)

(f) The expected number of hits is given by:

$$HT_{exn} = P(hit) \cdot m \tag{4-5}$$

where: m = the number of incoming threat missiles.

(2) Defensive Missile System Model

To determine the overall kill probability of the defensive missile system:

- (a) assume one incoming missile;
- (b) assume the defensive missile system has n chances (shots) at the incoming missile; and
- (c) assume each shot has a kill probability of p.

In this case, a kill is assumed if intercept occurs. The overall kill probability of the defensive missile is given by:

$$P_{kill}(A) = 1 - (1 - p)^{n}.$$
(4-6)

(3) Defensive Gun System Model

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To determine the overall kill probability of the defensive gun systems (Mk45 5"/54 and Mk15 Phalanx), the following general formulation is employed:

$$E_{L} = P_{kill}(A) = a \left\{ 1 - \prod_{i=1}^{N} [1 - P_{L}(i)] \right\}$$
  
where:  
$$E_{L} = \text{engagement effectiveness}, \qquad (4-7)$$
  
$$a = \text{System availability},$$

- N = number of rounds or bursts fired, and
- $P_L(i) = \text{ single round or burst effectiveness of the } i^{th} \text{ round or burst}$ .

In this report, the engagement effectiveness is assumed to be the same as the kill probability, though it really only implies that the fire control solution was adequate to place the round where it was needed, not that it actually got there. Additionally, system availability, a, is assumed 100% when needed.

(a) Overall kill probability of the defensive gun system is range

dependent.

- (b) Number of rounds fired is a function of:
  - 1) firing rate (FR);
  - 2) burst duration  $(T_{burst})$ ;
  - 3) size of magazine (number of rounds available);

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4) maximum pre-programmed burst duration.

Overall kill probability of the Mk 15 Phalanx Close In Weapons System (CIWS) is dependent on the specific target. Variables such as attack profile, speed, and Radar Cross Section (RCS) impact the kill probability. No easy analytic solution exists that reasonably approximates the kill probability for a general case. Based on physical flight parameters and profiles, the RDS-2010 ASM threats listed in Table 4-1 are assigned the kill probabilities listed in Table 4-2.

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ASM Designation	Phalanx P <sub>kill</sub>
TRASHER	0.3
TAKEOVER	0.85
SEAGULL	0.7
SUNSTROKE	0.5

#### TABLE 4-2. ASM THREAT PHALANX PKILL.

These probabilities assume the target is engaged the entire effective range of Phalanx (0.81 to 0.05 nm).

The 5"/54 Mk 45 Naval Gun Mount with Mk 86 Gun Fire Control

System (GFCS) firing an IR fused round has a single shot kill probability against a missile that is approximated by:

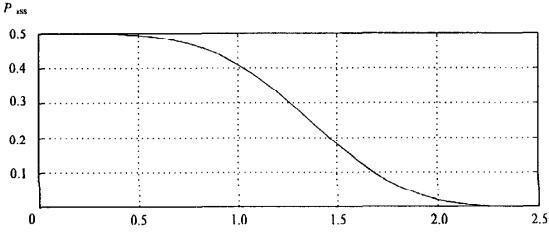
$$P_{kSS} = 0.5 \exp\left\{\frac{-R^{4}}{5}\right\}$$
where:
$$P_{kSS} = \text{ single - shot kill probability , and}$$

$$R = \text{ target range in nm .}$$
(4-8a)

A plot of (4-8a) is shown in Figure 4-2, which shows there is little reason to engage the 5"/54 gun on a missile target in excess of 2.5 nm range.

The engagement kill probability for the 5"/54 gun system would be given by:

$$P_{kill}(B) = 1 - \prod_{i=1}^{n} (1 - P_{kSS}(n))$$
  
where  
$$P_{kill}(B) = \text{ overall gun engagement kill probability}$$
(4-8b)  
$$P_{kSS} = \text{ single shot kill probability}$$
  
$$n = \text{ number of rounds shot during engagement}$$





#### Figure 4-2. PkSS of 5"/54 Mk 45 Gun System with IR fused round.

(4) Jammer/Decoy System

The overall kill probability of the jammer/decoy systems onboard, P(C), is a function of several variables, including:

- (a) equipment technical capabilities (hardware and software);
- (b) tactical employment of both jammer and decoy systems; and

(c) environmental factors such as atmospheric conditions including wind currents, air density, particulate content, humidity, etc.

For the purpose of this analysis the probability of the jammer/ decoy systems obtaining a kill of the incoming threat missile is:

$$P(C) = 0.4$$
 . (4-9)

The actual analysis to derive the number given by (4-9) is quite involved and beyond the scope of this report.

The scenarios are presented in a time line format, starting with time, t = 0 as the threat launch time, and positive values of time being the time of flight (TOF). The time line is run until all threats have theoretically impacted the ship. This method allows analysis or weapon system capabilities in terms of reaction times and capability of engaging all threats until time of impact. In reality, this gives a worst case scenario, since running the problem to impact assumes no defensive system defeated the inbound threat. Sizing the number of weapons/launchers/guns and FCS supporting hardware on this figure would lead to an overly conservative design.

A more realistic evaluation is accomplished using the cumulative kill probabilities as TOF increases. This gives a kill probability for each threat for each defensive event undertaken in time. Using this technique, assessment can be made of reasonable kill probability as the threat event progresses; e.g., a 99.9% kill probability will be achieved with six defensive missiles launched. These time-event cumulative probabilities are included on the timelines. This methodology will lead to a more realistic weapon loadout requirement.

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# 2. SCENARIO I: Simultaneous launched high-altitude and sea skimming missiles

This scenario involves simultaneous launch of two threat missiles:

- Takeover (high altitude, terminal dive) missile launched at a range of 135 nautical miles on a relative bearing of 060°. This missile is designated Threat A.
- Sunstroke (10 meter sea skimmer) missile launched at a range of 40 nautical miles on a relative bearing of 120°. This missile is designated *Threat B*.

The launching platforms are two different air contacts which displayed no hostile intent prior to missile launch. Figure 4-3 depicts the scenario graphically along with missile flight profiles.

Using the formulations presented in the analysis section and the timeline Table 4-3, the following results are given:

- a. Threat A encounter:
  - (1) Missile engagement (9 missiles 6 SM-1/2, 3 RAM) -

by using (4-6) with n = 9 missiles and p = 0.7 (a typical value for defensive missile system against incoming missile threat):

erensive missile system against incoming missile in ear).

$$P_{kill}(\mathbf{A}) = 1 - (1 - 0.7)^{9} = 0.999980$$
(4-10)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the

Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.85$$

- (3) Mk 45 5"/54 Medium Caliber gun encounter not used.
- (4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat A* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill, Threat A} = 1 - [1 - 0.999980][1 - 0.85][1 - 0.4]$$
(4-11)  
= .9999982

Note the running cumulative probabilities in the right hand column of the *Threat A* encounter time line. The final value of 0.999997 does not include the Jamming and Decoy kill probability.

#### b. Threat B encounter:

(1) Missile engagement (6 missiles - 2 SM-1/2, 4 RAM) -

using (4-6) with n = 6 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^{\circ}$$

$$= 0.99927$$
(4-12)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.5$$

(3) Mk 45 5"/54 Medium Caliber gun encounter - not used.

(4) Jamming and Decoy P<sub>kill</sub>(C) is given as 0.4 by (4-8).

The overall kill probability of *Threat B* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{klll, Threat B} = 1 - [1 - 0.99927][1 - 0.5][1 - 0.4]$$

$$= 0.999978$$
(4-13)

Note the running cumulative probabilities in the right hand column of the *Threat B* encounter time line. The final value of 0.99964 does not include the Jamming and Decoy kill probability.

The probability that the ship will take a hit during this scenario is

found using (4-4):

$$P(hit) = 1 - [P_{kill,Threat A} ] P_{kill,Threat B}]$$
  
= 1 - (0.9999982)(0.999978). (4-14)  
= 23.8x10<sup>-6</sup>

The expected number of hits is found using (4-5):

$$HT_{exp} = P(hit) \cdot m$$
(4-15)  
= (23.8 x 10<sup>-6</sup>) · 2  
= 47.6 x 10<sup>-6</sup> .

# c. Summary

To achieve a 99.9% kill probability of each threat indicates that the minimum combat system required is:

- (1) 6 SM-2(ER)
- (2) 2 SM-I(ER)
- (3) 2 independent illuminators
- (4) 4 RAM
- (5) 1 CIWS mount

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(6) ECM system

Additional requirements include a long range air search radar, a surface search radar, a missile FCS, and an integrated combat system.

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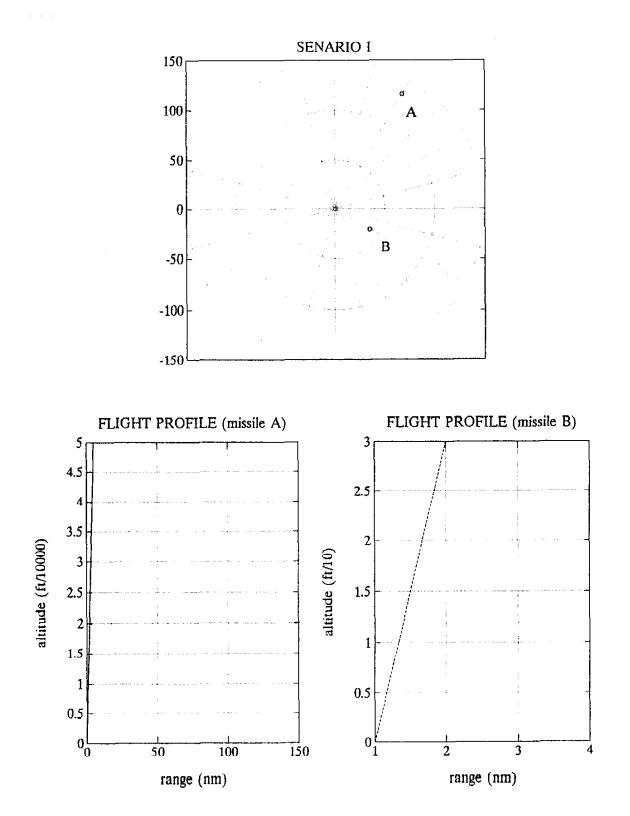


Figure 4-3. Scenario I.

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# TABLE 4-3. SCENARIO I.

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	1	hreat A, Takeov			. Diver			1	hreat B, 'Sunstro				skimmer	
Time	Range		ASMD W	eapon		Cumulativ <del>e</del>	Time	Range		ASMD V				Cumulative
(sec)	(nm)	SM-1/2	RAM	CIWS	5"/54	Kill Prob.	(sec)	(nm)	SM-1/2	RAM	CI	WS	5"/54	Kill Prob.
0	135	Detect					0	40						
10	129.3	Lnch SM-2				0.7	10	35.8			_			
14	127.1	Lnch SM-2		_		0.91	14	34.2						
60	101.0						60	15.0	Detect					
70	95.3						70	10.8	Lnch SM-1					0.7
74	93.L						74	9.2	Lneh SM-1					0.91
76	91.9						76	8.3		Lnch				0.97300
79	90.2						79	7.1		Lach				0.99190
83	88.0				{		83	5.4	Asscas					
85	86.8						85	4.6	Assess					
87.1	85.6						87.1	3.7		Assess				
88.4	84.9			-			88.4	3.2		Assess				
89.5	84.3						89.5	2.7			Eng	z 6.5s		0.99595
91.4	83.2						91.4	1.9		Lnch		l		0.99879
93.9	81.8						93.9	0.9		Assess				
94.4	81.5						94.4	0.7		Lneh				0.99964
95.2	81.1						95.2	0.3		Альсан				
96	80.6						96	0.0	Impact		_	¥		
91	83.4							-	-					
92	82.9				1		1							
93	82.3				T									
96	80.6				T		1							
141	55.1	Assess					1							
143	54.0	Assess					]							
147	51.7	Lnch SM-2				0.973	]							
150	50.0	Lnch SM-2				0.9919								
199	22.2	Assess												
200	21.7	Азэсза												
204	19.4	Lnch SM-2				0.997570								
208	17.1	Lnch SM-2				0.9992710	]							
214	13.7	1	Lnch			0.9997813	]							
217	12.0	1	Lnch	1	1	0.999934	1							
224	8.1	Assess	1	1	1		1							
225	7.5	Assess	1		1		1							
229	5.2		Asacas	1		1	1							
229	4.7	<u> </u>	Assess			1	1							
230	3.5	1		Eng 6.5 s		0.999990	1							
233	3.0		Lnch			0.999997	1							
233	1.3	-	Assess		1		1							
236														

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#### 3. SCENARIO II: Simultaneous launched sea skimming missiles

This scenario involves simultaneous launch of three threat missiles:

- Sunstroke (10 meter sea skimmer) missile launched at a range of 65 nautical miles on a relative bearing of 090°. This missile is designated Threat A.
- Seagull (15 meter sea skimmer) missile launched at a range of 15 nautical miles on a relative bearing of 210°. This missile is designated Threat B.
- Sumstroke (10 meter sea skimmer) missile launched at a range of 50 nautical miles on a relative bearing of 330°. This missile is designated Threat C.

The launching platforms are three different surface contacts which displayed no hostile intent prior to missile launch. Figure 4-4 depicts the scenario graphically along with missile flight profiles. Using the formulations presented in the analysis section and the timeline Table 4-5, the following results are given:

# a. Threat A encounter:

.

(1) Missile engagement (6 missiles - 2 SM-1/2, 4 RAM) -

using (4-6) with n = 6 missiles and p = 0.7 (a typical value for defensive missile system against incoming missile threat):

$$P_{kill}(A) = 1 - (1 - 0.7)^{\circ}$$

$$= 0.99927$$
(4.16)

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(2) Mk 15 Phalanx CIWS engagement -

one 4.0 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.5$$
 .

(3) Mk 45 5"/54 Medium Caliber gun encounter -

three rounds at ranges indicated on the time line giving a kill probability using (4-8) of:

$$P_{kill} = 0.52$$

(4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat* A is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill,ThreatA} = 1 - [1 - 0.99927][1 - 0.5][1 - 0.52][1 - 0.4]$$
(4-17)  
= 0.99989

Note the running cumulative probabilities in the right hand column of the *Threat A* encounter time line. The final value of 0.9998 does not include the Jamming and Decoy kill probability.

# b. Threat B encounter:

(1) Missile engagement (12 missiles - 4 SM-1/2, 8 RAM) using (4-6) with n = 12 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^{12}$$

$$= 0.9999995$$
(4-18)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.7$$
 .

(3) Mk 45 5"/54 Medium Caliber gun encounter -

38 rounds, with approximately one round fired every 3 seconds starting at a range of 13.8 nm as indicated on the time line. The kill probability using (4-8) is:

$$P_{kill} = 0.934$$
 ,

# (4) Jamming and Decoy $P_{kill}(C)$ is given as 0.4 by (4-8).

The overall kill probability of *Threat B* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill,ThreatB} = 1 - [1 - 0.99999995][1 - 0.7][1 - 0.934][1 - 0.4]$$
(4-19)  
= 0.9999999993

Note the running cumulative probabilities in the right hand column of the *Threat B* encounter time line. The final value of 0.99999988 does not include the Jamming and Decoy kill probability.

# c. Threat C encounter:

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(1) Missile engagement (5 missiles - 1 SM-1/2, 4 RAM) - using (4-6) with n = 5 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^{5}$$

$$= 0.9976$$
(4-20)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{klll} = 0.5$$

(3) Mk 45 5"/54 Medium Caliber gun encounter - not used.

(4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat* C is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill,ThreatC} = 1 - [1 - 0.9976][1 - 0.5][1 - 0.4]$$

$$= 0.99927 .$$
(4-21)

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Note the running cumulative probabilities in the right hand column of the *Threat* C encounter time line. The final value of 0.9988 does not include the Jamming and Decoy kill probability.

The probability that the ship will take a hit during this scenario is

found using (4-4):

$$P(hit) = 1 - [P_{kill,Threat A} ] [P_{kill,Threat B} ] [P_{kill,Threat C}]$$
  
= 1-(0.99989)(0.99999993)(0.999927)  
= 840x10<sup>-6</sup> (4-22)

The expected number of hits is found using (4-5):

$$HT_{exp} = P(hit) \cdot m$$
(4-23)  
= (840 x 10<sup>-6</sup>) · 3  
= 2.52 x 10<sup>-3</sup>.

d. Summary

To achieve a 99.9% kill probability of each threat indicates that the minimum combat system required is:

- (1) 7 SM-l(ER)
- (2) 2 independent illuminators
- (3) 10 RAM
- (4) 2 CIWS mount
- (5) 1 5"/54 gun mount
- (6) ECM system

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Additional requirements include a long range air search radar, a surface search radar, a missile FCS, and an integrated combat system.

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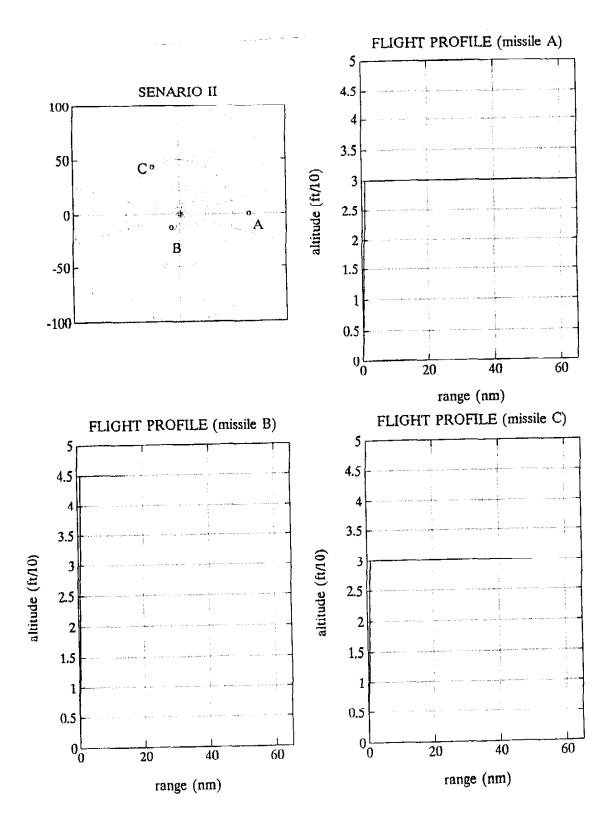


Figure 4-4. Scenario II. 61

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(mr)	La	SM-1/2	RAM	CIWS	5-/54	Kill Probability	9	(mai)	5M-1/2	RAM	CIWS	5":54	Kill Probability	(Sec)	(mn)	2/1-WS	RAM	CIWS	51/54	Kill Probability
•	ž						•	2	Detect					0	50					
<u> </u>	8.08						10	13.8	Luch SM-1			10 mds	0.7	10	45.8					
4	59.2						-	13.4	Lnch SM-1				16.0	4	44.2					
35	50.4						ž	10.9	Asses					2	35.4					
66	42.8						5	10.5	Amere			- 1	Í	8	33.8					
4	1.12						Ş	10.0	Lach SM-1			PE	0.973	ę	32.1					
4	45.4						47	9.5	L-MCh SM-1				0.9919	74	30.4		-			
8	42.9						8	8.8				PE I		5	27.9					
57	11						51	8.4	Assess					57	26.3					
59	110						ŝ	4.7		Lach			9266-0	65	22.9					
5	4.34						3	17		Lach			6666'0	89	31.7				ļ	
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8	1						8	2						<b>0</b> 01	6.8					
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2	- 14						ā	39		ţ		P	0.999994	ğ	6.7					
8	20.8						18	2.6		Assess				901	5.8					
1.901	506						106.7	3.6				Pe -	0.999944	106.7	5.5					
6	20.4						ē	2.5						107	5.4					
801	20.0						108	7.4				- 1		801	<u>ی</u>		Anten			
601	19.6						5	2		Andu		PE	0.999994	8	4		Aucs			
109.3	19.5						10.1	2						5	<u>*</u>					
110	19.2						91	22				1		110	7					
122.6	6.61	Detect					Ξ	5				Z	166666		<b>R</b> : 6					
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ž	16.7							2		T			******						T	
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							9	1						8	0.0	Impact		,		
1							12.5	80		Asses		PHE T	0.9999915			•	_	•		
2							5	3.0			Eng 6.5s		96666660							
121.5	14.4						122.5	0.7		Lach		) md	8666666.0							
124.5	13.1						124.5	6.5		And		ł	88666666.0							
128.5	113						128.5	11	Tmpact		•									
3.161	10.1	Luch SM-1	Linch Linch			0.9.														
134.6	8.9		55			6.973														
135.6	8.5	Luch SM-1				6:66'0														
144.6	4.8	Assess																		
145.6	54		And																	
148.5		ABCES	Assess	-	P	0.99.9														
5.161	-		5	Eng 4.05	-	8366-0														
			ABCS		1	0048					S									
134.5		TANDACT	1								10									
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# 4. SCENARIO III: Two simultaneous launched mobile sea skimming missiles and a delay launched sea skimming missile

This scenario involves simultaneous launch of three threat missiles:

- Seagull (15 meter sea skimmer) missile launched at a range of 15 nautical miles on a relative bearing of 030° at time t = 0s. This missile is designated Threat A.
- Seagull (15 meter sea skimmer) missile launched at a range of 10 nautical miles on a relative bearing of 150° at time t = 0s. This missile is designated Threat B.
- Sunstroke (10 meter sea skimmer) missile launched at a range of 20 nautical miles on a relative bearing of 320° at time t = 10s. This missile is designated Threat C.

The Seagull launching platforms are two different surface contacts (fishing craft) which displayed no hostile intent prior to missile launch. These fishing craft were hidden amongst other fishing craft, making them impossible to distinguish. The Sunstroke missile is launched ten seconds after the two Seagull missiles from a surface contact which was being closely monitored. Figure 4-5 depicts the scenario graphically along with missile flight profiles.

Using the formulations presented in the analysis section and the timeline Table 4-6, the following results are given:

### a. Threat A encounter:

(1) Missile engagement (12 missiles - 4 SM-1, 8 RAM) -

using (4-6) with n = 12 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^{12}$$
  
= 0.999999946 (4-24)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the

Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.7$$

(3) Mk 45 5"/54 Medium Caliber gun encounter - not used.

(4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat* A is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill, Threat A} = 1 - [1 - 0.999999946][1 - 0.7][1 - 0.4]$$
(4-25)  
= 0.999999990.

Note the running cumulative probabilities in the right hand column of the *Threat A* encounter time line. The final value of 0.999999841 does not include the Jamming and Decoy kill probability.

### b. Threat B encounter:

(1) Missile engagement (10 missiles - 2 SM-1, 8 RAM) – using (4-6) with n = 10 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^{10}$$

$$= 0.999994$$
(4-26)

(2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.7$$

(3) Mk 45 5"/54 Medium Caliber gun encounter -

7 rounds, with approximately one round fired every 3 seconds starting at a range of 2.5 nm as indicated on the time line. The kill probability using (4-8) is:

$$P_{kill} = 0.8749$$

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(4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat B* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill,ThreadB} = 1 - [1 - 0.999994][1 - 0.7][1 - 0.8749[1 - 0.4]$$
(4-27)  
= 0.99999999

Note the running cumulative probabilities in the right hand column of the *Threat B* encounter time line. The final value of 0.9999998 does not include the Jamming and Decoy kill probability.

### c. Threat C encounter:

(1) Missile engagement (4 RAM) -

using (4-6) with n = 4 missiles and p = 0.7:

$$P_{kill}(A) = 1 - (1 - 0.7)^4$$
  
= 0.9919 (4-28)

### (2) Mk 15 Phalanx CIWS engagement -

one 6.5 second burst that covers the entire effective range of the Phalanx yields, using Table 4-2, a kill probability of:

$$P_{kill} = 0.5$$

(3) Mk 45 5"/54 Medium Caliber gun encounter - not used.

(4) Jamming and Decoy  $P_{kill}(C)$  is given as 0.4 by (4-8).

The overall kill probability of *Threat* C is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill,ThreatC} = 1 - [1 - 0.9919][1 - 0.5][1 - 0.4]$$
(4-29)  
= 0.9976

Note the running cumulative probabilities in the right hand column of the *Threat B* encounter time line. The final value of 0.99595 does not include the Jamming and Decoy kill probability.

The probability that the ship will take during this scenario is found using (4-4):

$$P(hit) = 1 - [P_{kill, Threat A} [P_{kill, Threat B}] P_{kill, Threat C}]$$
  
= 1 - (0.99999990)(0.9999999)(0.9976) (4-30)  
= 2.4x10<sup>-3</sup>

The expected number of hits is found using (4-5):

$$HT_{exp} = P(hit) \cdot m$$
(4-31)  
= (2.4 x 10<sup>-3</sup>) · 3  
= 7.2 x 10<sup>-3</sup>

### d. Summary

A 99.9% kill probability of each threat is not possible due to *Threat C* kill probability of only 99.76%. To achieve 99.9% kill probability on *Threat A* and *Threat B*, and a 99.76 kill probability on *Threat C* indicates that the minimum combat system required is:

- (1) 6 SM-1(ER)
- (2) 2 independent illuminators

- (3) 11 RAM
- (4) 1 CIWS mount
- (5) ECM system

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Additional requirements include a long range air search radar, a surface search radar, a missile FCS, and an integrated combat system.

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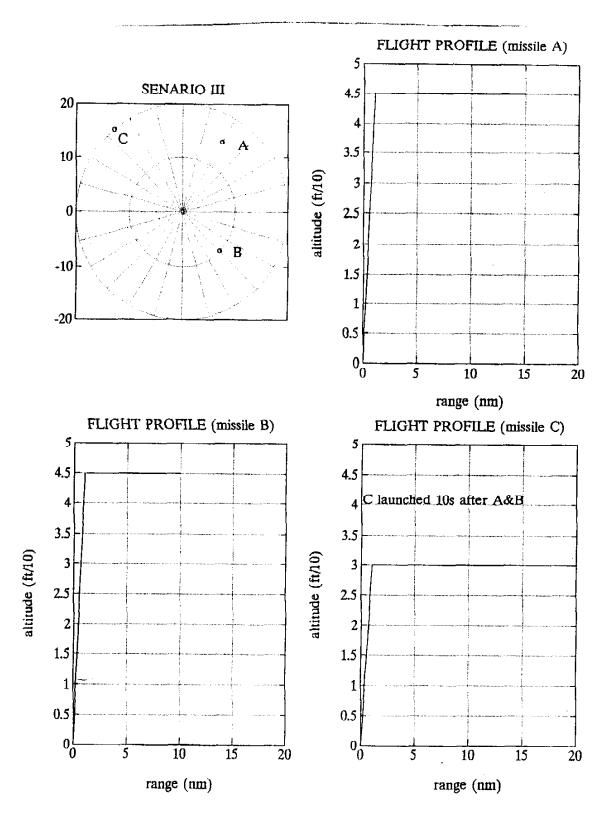


Figure 4-5. Scenario III. 67

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Ĕ	Range		ASMD Weapon	/eapon		Cumulative	Ţ	Range		ASMD Weapon	capon	Γ	Cumulative	j.	Rue		ASMD Weapon	Canon	╞─	Constants
									Γ							1			T	
	(uu) 62	7/1-WS	N S			All Distance in the	0		Detect	ş						2/1-WS	Š	CIMS	2.24	Kul Probability
0	60.8						0	3.61	Lech SN-1			10 mds	0.7	10	15.8				╞	
4	59.2							134	Lact SN-1			_	16.0	2	44.2					
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#### 5. SCENARIO IV: Simultaneous launch of shoulder missiles

This scenario involves simultaneous launch of two shoulder fired threat missiles:

- Stinger (shoulder mounted, IR home) missile launched at a range of 1.5 nautical miles on a relative bearing of 300°. This missile is designated Threat A.
- Stinger (shoulder mounted, IR home) missile launched at a range of 2.0 nautical miles on a relative bearing of 130°. This missile is designated Threat B.

The Stinger launches occur simultaneously from two different pleasure craft which displayed no hostile intent prior to missile launch. Figure 4-6 depicts the scenario graphically along with missile flight profiles.

Using the formulations presented in the analysis section and the timeline Table 4-6, the following results are given:

- a. Threat A encounter:
  - (1) Missile engagement none
  - (2) Mk 15 Phalanx CIWS engagement -

one 3.5 second burst that covers the entire effective range of the Phalanx. A kill probability for the *Stinger* is estimated to be about 0.3 due to the small size of the missile and short reaction time:

$$P_{kill} = 0.3$$

(3) Mk 45 5"/54 Medium Caliber gun encounter - not used.

(4) Jamming and Decoy Pkill(C) is considered ineffective for this scenario.

The overall kill probability of *Threat A* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill, Threat A} = 1 - [1 - 0.3]$$
(4-11)  
= 0.3 .

#### b. Threat B encounter:

- (1) Missile engagement not used.
- (2) Mk 15 Phalanx CIWS engagement -

one 5.0 second burst that covers the entire effective range of the

Phalanx. A kill probability for the *Stinger* is estimated to be about 0.4 due to the small size of the missile, but there is slightly longer reaction time as compared to Paragraph IV.B.5.a above:  $P_{kill} = 0.4$ .

- (3) Mk 45 5"/54 Medium Caliber gun encounter not used.
- Jamming and Decoy P<sub>kill</sub>(C) is considered ineffective for this scenario.

The overall kill probability of *Threat B* is found by using (4-3) and the values found in (1) through (4) above:

$$P_{kill, threat a} = 1 - [1 - 0.4]$$
(4-13)  
= 0.4

The probability that the ship will take a hit during this scenario is found using (4-4):

$$P(hit) = 1 - [P_{kill,Threat A}] [P_{kill,Threat B}]$$
  
= 1 - (0,3)(0.4)  
= 0.88

The expected number of hits is found using (4-5):

$$HT_{exp} = P(hit) \cdot m$$
 (4-15)  
= (0.88) · 2  
= 1.76 .

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### c. Summary

The minimum combat system required is:

### (1) 2 CIWS mount

Additional requirements include a surface search radar and an integrated combat system.

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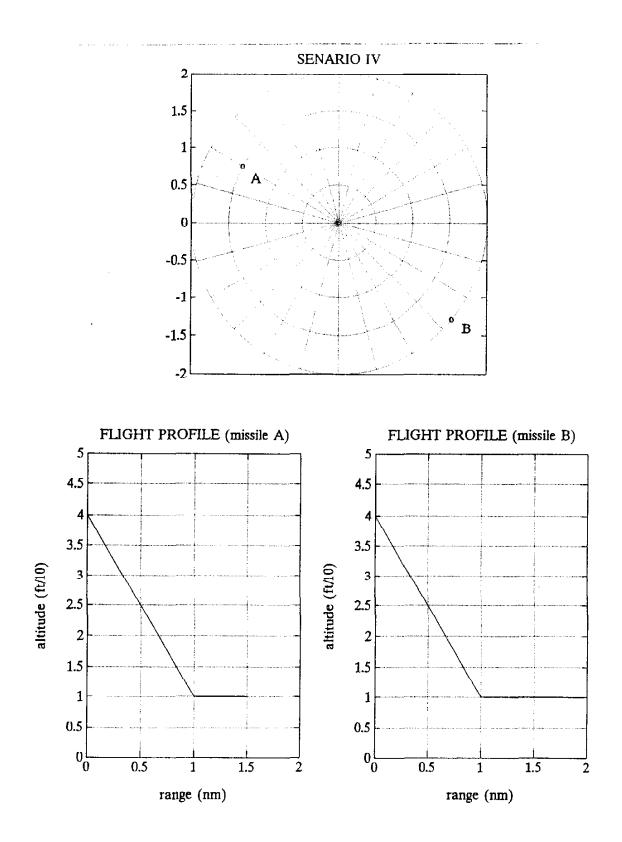


Figure 4-6. Scenario IV. 71

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	TI	areat A, 'Sti	nger', v =	2.0 Ma, He	at seeke				Threat B, "	Stinger', v	= 2.0 Ma, Hea	t seeker	
Time	Range	A	SMD \	Neapon		Cumulative	Time	Range		ASME	Weapon		Cumulative
(sec)	(nm)	SM-1/2	RAM	CIWS	5"/54	Kill Prob.	(sec)	(nm)	SM-1/2	RAM	CIWS	5"/54	Kill Prob.
0	1.5						0	2					
1	1.2			Eng 3.5s		0.3	1	1.7			Eng 5.0 s		0.4
2	0.8						2	1.3				Ĺ	
3	0.5						3	1.0					
4	0.2						4	0.7					
4.5	0.0	Impact		↓			5	0.3					
	•	•					6	0.0	Impact		¥		

Table 4-6. Scenario IV.

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### 6. SUMMARY:

Based on the four outlined scenarios, the following minimum number of systems and items will be incorporated into the initial design of the RDS-2010:

a. A combat system consisting of the following engagement elements will be used:

- 24 cell VLS (VLS loadout as required by mission)

- 2 RALS (Ram Alternate Launcher System)

- 2 MK 15 PHALANX

- 1 5"/54 MK 45 GUN MOUNT w/ FCS

- 2 SPG-XX ILLUMINATORS
- 1 SLQ-32(V3) w/ 2 DECOY LAUNCHERS
- I LONG RANGE AIR SEARCH RADAR
- 1 SURFACE SEARCH RADAR

b. The ship must be able to sustain a hit from a STINGER size missile and maintain mission capabilities.

c. Although the scenarios, as presented, would imply no requirement for the SAR-8 IR sensing system, the weakest defensive capability lies in the short range, handlaunched missile system (STINGER types). Research needs to be accomplished in the area of quick-reaction detection of a missile launch and autonomous defeat of the weapon. This is envisioned as some type of automatic flare system coupled to a sensor like the SAR-8. Immediately on detection of missile launch, a flare-type decoy would be deployed to draw the missile away from the ship. This flare will have to be propelled along a predetermined flight path to allow the missile to lock-in on it and then be drawn away from the ship. Another area in which research is required is active IR emissions for disabling the missile seeker, by overload or deception.

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### C. COMBAT SYSTEM DESCRIPTION AND ARCHITECTURE

### 1. Design Statement

The RDS-2010 Combat System and supporting elements are designed to meet the requirements delineated in Section II.B. Specifically, the combat system must:

- a. provide AAW self-defense against limited intensity/direction threats;
- b. provide ASUW against third-world surface naval forces;
- c. provide ASW in deep and shallow water while employed independently;
- d. support amphibious assaults;
- e. attack high value land based military targets;
- f. receive real time targeting information from diverse sources; and
- g. operate in mine infested waters.

These requirements and the evaluation of threat scenarios (Section IV.B) confirmed and refined the combat system element selection (Section III.C.4).

### 2. Top Level Design Goals

Based on the above requirements, the top level combat system design goals are:

- a. self-defense;
- b. discriminate targets to minimize unwanted damage;
- c. fight hurt--minimize damage by effective assessment and rapid restoration;
- d. continuous high readiness for extended periods;

e. self-sufficient-capable of independent or small group operations;

- f. improved anti-terrorist security;
- g. improved counter targeting through decoys and deception devices;

h. built in automatic reconfigurability of ship's systems based on evolving threat scenario/condition;

- i. built in fault identification with rapid repair capability; and
- j. combat system automation with preset options for layered self-defense.

### 3. Combat System Description and Capability

Figure 4-7 depicts the functional arrangement of the RDS-2010 combat system, including major data flow connectivity. General design attributes include:

a. Primary connectivity between elements is provided by a multi-channel, multi-redundant fiber optic ring bus. Envisioned is a minimum of five functionally redundant data buses geographically separated within the ship to decrease vulnerability. Each system has multiple channel capacity and each channel has the capability to carry multiplexed data. Determination of data types and flow that allow use of multiplexing vice dedicated channels must be determined during detailed combat system design. As a minimum, each ship enclave contains one *bus manager* to ensure surviving enclaves have data bus capability. The application of the Fiber Optic Data Multiplexing System (FODMS) and Fiber Optic Interior Voice Communications System (FOIVCS) improves capability and enhances survivability while reducing ship acquisition cost, primarily via the associated weight and volume savings.

b. Two manned Command and Decision (C&D) elements (i.e., Combat Information Center - CIC) are provided, one acting as the ship's primary CIC (CIC #1) and the other an alternate CIC (CIC #2). Functional redundancy is provided between these two C&D elements, though actual hardware, layout, and number of operator stations is scaled down in CIC #2. The two CICs are located in separate enclaves. The C&D element utilized the available sensors and external information data stream to provide the necessary information to create a complete tactical picture. The computer processing power required by all modules of the C&D element is distributed amongst the modules providing redundant capacity and eliminating processing bottlenecks. There will be no "central computer" in the traditional sense. The tactical picture created must be complete and coherent enough to provide necessary reaction time for ship defense. The major modules of the C&D element are:

(1) Detect and Track. This module determines contact detection and develops track files on contact data received from various ship's sensors. The module exports the track files to the correlate module and ring bus for use by the other C&D correlate module.

(2) Correlate. This module develops correlation of data from various detection elements on and off the ship and Detect & Track module to develop a central track file. This provides precise localization and identification of all contacts. The central track file is exported to the C&D control element and ring bus for use by the other C&D clement's C&D module.

(3) Command and Decision Module. This performs assessment of detection tracks as friendly, neutral, or enemy. It makes engagement decisions and sets the engagement priorities. Additionally, it coordinates own ship operations with the operations of other ships or aircraft in the task force. The decision to engage or not is made in this module. Capable of fully automated ship self-defense operation, the level of automation employed is determined by the responsible person in charge.

(4) *Multipurpose Consoles*. These represent generic, programmable operator interface consoles that provide the man/machine interface with all modules of the C&D element. These consoles are militarized versions of modern, commercial workstations. Additionally, there is a large screen multifunctional display for large area geographic display of tactical situations.

(5) Weapons Control Module. The actual weapons selection and engagement coordination is performed by this module. It also maintains an inventory of available ordnance and carries out engagement planning needed for each weapons release. The module coordinates the use of individual weapon elements to prevent interference between own ship weapons and damage to friendly forces. Finally, the module provides the kill assessment for each individual engagement.

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c. The *power interface module* provides the interface management function between the ship's engineering plant electric plant control module and the combat system with regards to load shed command and coordination. On loss of electrical generation capacity due to casualty, the electric plant control module sends a load shed command to the combat system, essentially conveying available generating capacity and bus configuration. The interface module communicates with the C&D element to determine combat system needs commensurate with tactical situation. With a balance between power requirements (demand) versus generating capacity, the power system interface module transmits shut down<sup>o</sup> commands to appropriate combat system elements and also communicates electric plant reconfiguration requests to the electric plant control module.

d. Readiness assessment, fault detection and localization. The survivability management and readiness assessment (SM/RA) module works in conjunction with the various combat system element's built-in test and evaluation (BITE) capabilities to provide an integrated system readiness assessment. All the combat system elements must have this BITE capability. The survivability management sub-module uses the system status (readiness assessment) and tactical situation (C&D element) to direct combat system reconfiguration to employ alternate functionality during casualty situations. An additional BITE feature is the requirement that all combat system elements provide automated troubleshooting capability. This enhances fault localization and subsequent repair to place equipment fully operational in as short a time as practical. The readiness assessment submodule provides the commanding officer and tactical action officer with a real-time comprehensive assessment of the ship's ability to continue fighting. Additionally, it enables the combat system officer of the watch and engineering officer of the watch to better coordinate efforts to maintain/recover mission readiness prioritized to current mission

<sup>&</sup>lt;sup>a</sup> a shut down command will cause a device specific action ranging from total device shutdown to placing the device in a power savings (standby) mode

needs. The readiness data includes current status of mission capabilities, times to failure and times to recovery. Readiness data is obtained from all systems including auxiliaries that supply the individual combat systems.

e. Survivability and reconfigurability. System survivability is enhanced by a number of design features, including:

(1) dual C&D element functionality which is geographically separated in CIC #1 and CIC #2;

(2) alternate sensor capability in all spectrums except IR detection;

(3) multiple, redundant connectivity between combat system elements;

(4) graceful degradation of overall system capability upon partial power loss through smart load shed management.

With the available redundant/alternate functional capabilities, system reconfiguration is practical to optimize combat system employment during casualty conditions. This feature is addressed in Section IV.C.3.d above.

f. Embedded training. The integrated combat system includes an embedded training module to allow realistic threat scenario engagement exercises. These training scenarios will exercise the C&D element and watchstanders. Essentially, this entails the capability to run pre-programmed engagement scenarios by injection of track and other necessary data directly onto the data bus.

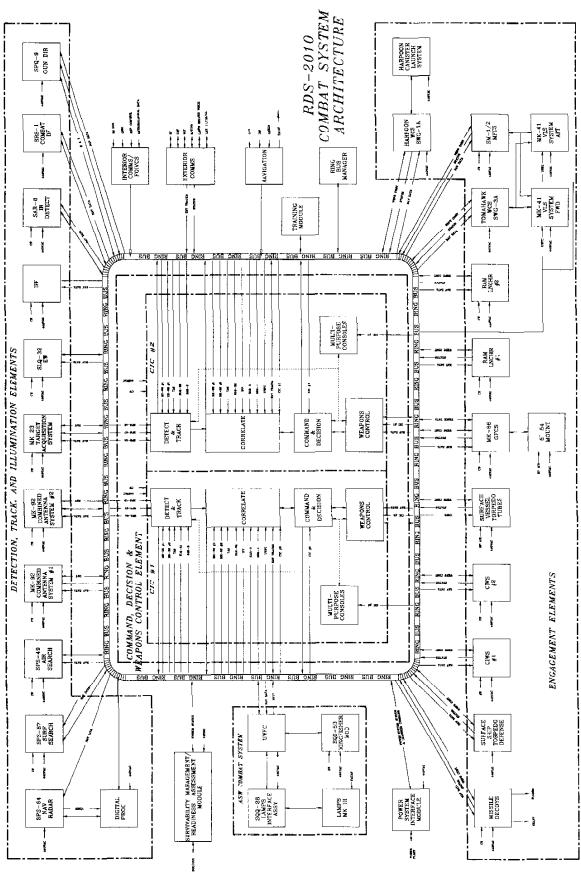
g. Embedded support service management. Primary support services for the combat system are electrical, chilled water, sea water, ambient space cooling and dehumidification, and high pressure air. With the enclaving scheme, each enclave has fully self-contained capability with the exception of electrical power generation. Electrical power generation is limited to the three enclaves containing the two engine rooms and one auxiliary machinery space aft. Status of these systems is maintained by Damage Control Central (DCC)/Central Control Station (CCS) and the engineering plant status module.

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Support service configuration is coordinated with required combat system capability as determined by the tactical situation during casualty situations. Maximum capability will be maintained consistent with available capacity remaining during casualties. With input to/from the survivability management system, certain automatic damage control actions can be accomplished before a weapons hit occurs. For instance, upon detection of appropriate heat and smoke levels following a detonation within a compartment, the pertinent fire sprinklers can be started to douse the fire and cool adjacent compartment's bulkheads and ventilation dampers can be automatically closed. Also, the electric plant can be shifted before fire removes distribution capability that is routed through the scene of the fire.

h. Automated Communications Suite. To provide manning reduction and increase external communication throughput, the external communications suite is automated. This automation allows incorporation of the external communications function as an integral part of the integrated combat systems suite. Features such as automated electronic message routing with dispersed remote terminals streamline message dissemination. Automated external connectivity allows integration of this ship in a task force/battle group scenario. Export of sensor data and import of weapons command functions extends the integrated fighting power of the task force/battle group. Import of real time data from outer sources provides a coherent, integrated picture of the battle space. With continuously updated information the ship could support or be supported by other ships, shooting targets its own sensors cannot detect.

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### D. BATTLE ORGANIZATION AND BATTLE STATION LOCATIONS

The manning requirements for the ship drive many design parameters, especially in the H, M & E areas. Manning is primarily driven by watchstation requirements during battle conditions, and driven to a lesser extent by normal ship operations. For this reason, the Battle Organization and Battle Station Locations, along with the envisioned manning plan for the RDS-2010 are included in this chapter.

The RDS 2010's Condition I and Condition III Battle Organizations are given in Figures 4-8 and 4-9, respectively. The connectivity of the watch organization is for supervisory functions only, and has nothing to do with the flow of information to each watch station. Since each watch station will be connected to the data multiplexed ring bus, all watch stations will have access to any desired information. The watch stations that require consoles will be established with either one of three different types;

1. a multi-purpose console capable of performing any watch station function,

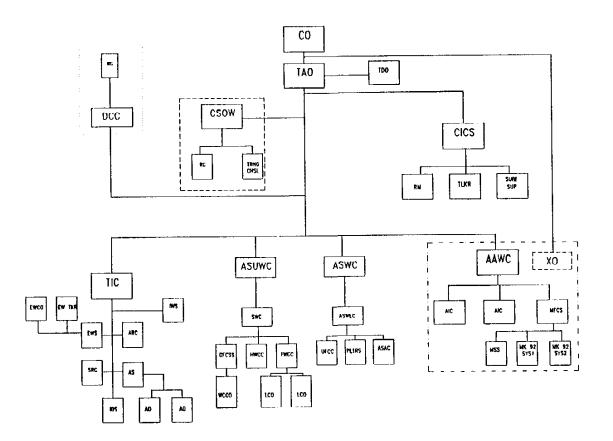
2. an Aegis-type large screen multi-purpose Command and Display console,

3. or a watch station specific console used only for local equipment control and specific functions.

The desired capability of the combat system watch team during Condition III is that it can fight the ship in a short duration, limited capacity until the ship can man Condition I watch stations. The RDS 2010's manning will allow, with minor exceptions, all watch stations to be stood in a three section, 4 hours on/8 hours off, watch rotation. This will allow ample time for the off watch sections to conduct training, maintenance and housekeeping. The envisioned manning and departmental organization of the RDS 2010 is shown in Table 4-7 and Figure 4-10, respectively. It is understood that this is not a formal manning document, but an attempt by the team to determine the number of personnel required to man the ship. Additionally, it is useful for analyzing whether this number supports the reduced manning goal.

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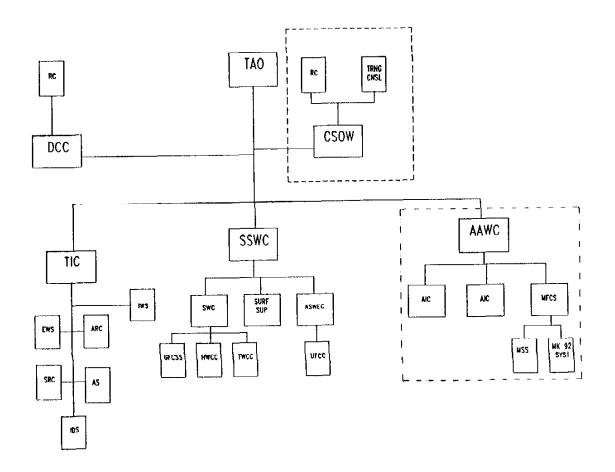
### LEGEND

TAO CICS TIC ARC SRC IDS RC SWC TWCC SURF SUP ASWEC AAWC ASAC WCCO EWCO MK 92 SYS MSS MFCS	TACTICAL ACTION OFFICER CIC SUPERVISOR TACTICAL INFORMATION COORDINATOR AIR RADAR COORDINATOR SURFACE RADAR COORDINATOR IDENTIFICATION SUPERVISOR READINESS CONSOLE SURFACE WEAPONS COORDINATOR TOMAHAWK WEAPONS CONTROL CONSOLE SURFACE NAY SUPERVISOR ANTI-SUBMARINE WEAPONS COORDINATOR ANTI-SUBMARINE AIRCRAFT CONTROLLER WEAPONS CONTROL CONSOLE OPERATOR ELECTRONIC WARFARE CONSOLE OPERATOR ELECTRONIC WARFARE CONSOLE OPERATOR MISSILE SYSTEM SUPERVISOR MISSILE FIRE CONTROL SUPERVISOR	DCC TDO EWS IWS AS AS GFCSS HWCC GFCSS HWCC ASWC UFCC LCO XO RM CSOW EW TKR AIC	DAMAGE CONTROL COORDINATOR TACTICAL DISPLAY OPERATOR ELECTRONIC WARFARE SUPERVISOR INTELLIGENCE WATCH SUPERVISOR ACOUSTIC SUPERVISOR ACOUSTIC OPERATOR ANTI-SURFACE WARFARE COORDINATOR GUN FIRE CONTROL SYSTEM SUPERVISOR HARFOON WEAFON CONTROL CONSOLE ANTI-SUBMARINE WARFARE COORDINATOR UNDERWATER FIRE CONTROL COORDINATOR LOCAL CONTROL OPERATOR EXECUTIVE OFFICE RADIOMAN COMBAT SYSTEM OFFICER OF THE WATCH ELECTRONIC WARFARE TALKER AIR INTERCEPT CONTROLLER
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### Figure 4-8. Condition I Battle Organization.

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TAOTACTICAL ACTION OFFICERTICTACTICAL INFORMATION COORDINATORARCAIR RADAR COORDINATORSRCSURFACE RADAR COORDINATORIDSIDENTIFICATION SUPERVISORRCREADINESS CONSOLESSWCSURF-SUBSURFACE WEAPONS COORDINATORTWCCTOMAHAWK WEAPONS CONTROL CONSOLESURF SUPSURFACE NAV SUPERVISORASWECANTI-SUBMARINE WEAPONS COORDINATORAAWCANTI-AIR WARFARE COORDINATORMK 92 SYSMK 92 SYSTEM COORDINATOR	DCC EWS IWS AS SWC AIC GFCSS HWCC MSS UFCC CSOW MFCS	DAMAGE CONTROL COORDINATOR ELECTRONIC WARFARE SUPERVISOR INTELLIGENCE WATCH SUPERVISOR ACOUSTIC SUPERVISOR SURFACE WEAPONS COORDINATOR AIR INTERCEPT CONTROLLER GUN FIRE CONTROL SYSTEM SUPERVISOR HARPOON WEAPON CONTROL CONSOLE MISSILE SYSTEM SUPERVISOR UNDERWATER FIRE CONTROL COORDINATOR COMBAT SYSTEM OFFICER OF THE WATCH MISSILE FIRE CONTROL SUPERVISOR
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Figure 4-9. Condition III Battle Organization.

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DEPARTMENT	OFFICERS	CPO'S	ENLISTED	TOTAL
SHIP SUPPORT	CO, XO, SUPPO	HMC, MSC,	HM, YN (2),	30
	(3)	SKC	PN (2), PC	
		(3)	SH (2), SK(6)	
			DK, MS (9)	
			(24)	
SHIP CONTROL	OPS, CICO	OSC, RMC,	RM (4),QM (2)	42
	СОММО	BMC, QMC	SM (2), BM (13)	
	(3)	(4)	OS (14)	
			(35)	
COMBAT SYSTEM	CSO, FCO, EMO,	ETC, EWC,	EW (4), ET (4)	52
	ORDO	FCC (3),	ST (5)	
	(4)	GMC, STC	FC (16), GM (8)	
		(7)	IC (4)	
			(41)	
ENGINEERING	CHENG, MPA,	GSC (2), ENC,		39
	DCA, A+E	EMC, DCC	HT (2), DC (5)	
	(4)	(5)	EN (5)	
			(30)	
INTELL DET	(0)	СТС	CT	5
		(1)	(4)	
MED DET	SURGEON, P.A.	(0)	HM (2)	5
	NURSE		(2)	
	(3)			
AIR DET	PILOTS	ATC	AIR CREW,	19
	(4)	(1)	AIR TECHS,	
			METEROLOGIC	
			(14)	
FLAG/STAFF	(0)	(0)	(0)	(0)
AVAILABLE	21	21	150	192
MANNING				

### Table 4-7. MANNING FOR THE RDS 2010.

### **NOTES:**

- 1. The Suppy Officer, Suppo, will handle supply and administrative matters.
- 2. The entire ship's company will have their food prepared in the ship's galley.
- 3. The FC's will handle all maintenance, repair and operation of the fire control and data transfer systems.
- 4. The listed ratings include designated and non-designated personnel.

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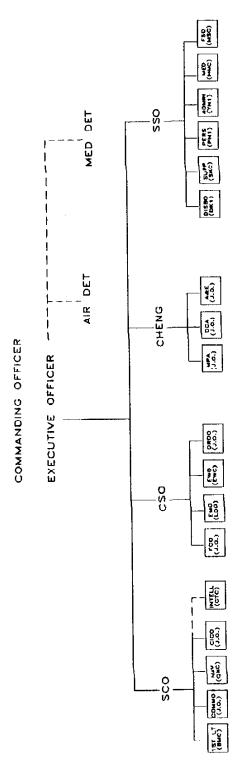


Figure 4-10. Departmental Organization.

### V. HULL, MECHANICAL, AND ELECTRICAL FEASIBILITY STUDIES

Once the ship's major payload, the combat system, is determined in terms of specific elements and their quantities, then the element's size, weight, power and service requirements can be used as a starting point for determining the ship's hull, mechanical, and electrical characteristics required to support the payload. This next phase of the feasibility studies uses a computer based ship design tool, supplied by NAVSEA, known as the Advanced Surface Ship Evaluation Tool (ASSET). Within ASSET there exists a series of computational modules which address a specific domain of ship design, such as hull geometry, hull structure, resistance, propulsion, machinery, weight, space, hydrostatics, seakeeping, manning, or cost. Through a unique command language, the user directs the execution of the modules. In using the input support module, essentially all ship characteristics which are known a priori (i.e., such as the above mentioned payload characteristics and the defined ship performance characteristics) are entered into and stored in this ASSET program's data bank. The designer then, through various commands, directs the program to iteratively calculate the major ship's characteristics until the data converges on a solution. The modules of the ASSET program have been designed in such a way as to provide the capability of design synthesis and analysis. The converged solution, however, may or may not meet all the desired characteristics. It is at this point that the ship design team must begin tradeoff decisions in an attempt to gain a balanced ship with as many of the desired characteristics that are economically and technically feasible.

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### A. INITIAL CONVERGENCE

Table 5-1 summarizes the major ship's characteristics attained during the first convergence of the ship RDS 2010 using the Monohull Surface Combatant version of the ASSET program. Since the design has not been optimized, the complete and voluminous output reports of ASSET are not included with this report. The primary goal at this stage of the feasibility studies was to gain enough experience and confidence with the ASSET program to obtain a converged design. The next stage of feasibility studies will be to iterate, using ASSET, and attempt to optimize the design using the top level design goals and performance characteristics for guidance. This process will entail making design decisions, attempting to balance numerous competing design goals until a ship is obtained which reasonably meets the set design requirements and constraints. The ability to meet all design goals simultaneously is in no way guaranteed.

Portions of this feasibility study use alternative elements to those selected in carlier phases of the design. This was necessary because of the inability of this computer program to successfully accommodate electric drive with electric power generation. When the design team attempted to use the electric propulsion generators, each main machinery room was required to be 114 feet in length. This is another area requiring modification in future versions of the ASSET series of programs.

In general the size of the ship is too large for the present payload. Some of the excess volume and length is due to the use of the double hull which this ASSET program currently docs not incorporate. It also appears that the ASSET program is heating and ventilating the volume in the double hull. A decision was made to use the portion of the double hull volume below the water line for tankage, so this also needs to be adjusted.

87

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TABLE 5-1.	ASSET SHIP'S DESIG	N SUMMARY, INITIAL	CONVERGENCE.
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PRINTED REPORT NO HULL OFFSETS IND-	GENERATE	MIN BEAM, FT	60.00
	B+T	MAX BEAM, FT	110.00
	CALC	HULL FLARE ANGLE, DEC	
	OPTIMUM	FORWARD BULWARK, FT	4.00
	GIVEN		
HUL	L PRINCIPAL DI	MENSIONS (ON DWL)	
#LBP, FT	450.00	<pre>#PRISMATIC COEF</pre>	0.650
#LOA, FT	467.82		0.950
#BEAM, FT	63.78		0.787
#BEAM @ WEATHER DECK,	FT 63.78		0.506
#DRAFT, FT	15.01	HALF SIDING WIDTH, FT	1.00
#DEPTH STA 0, FT	52.95	BOT RAKE, FT	0.00
#DEPTH STA 3, FT	47.02	RAISED DECK HT, FT	0.00
#DEPTH STA 10, FT	38.50	RAISED DECK HWD LIM, STA	
#DEPTH STA 20, FT	39.25	RAISED DECK AFT LIM, STA	7600.69
#FREEBOARD @ STA 3, FT			43.39
#STABILITY BEAM, FT	63.78	AKEA DEAM, FI	<b>~</b> <i>J</i> . <i>J</i> .
BARE HULL DATA		STABILITY DATA ON LW	
#LGTH ON WL, FT	450.00	KB, FT	8.17
#BEAM, FT	63.78	BMT, FT	22.53
#DRAFT, FT	15.00	KG, FT	24.30
#FREEBOARD @ STA 3, FT		#FREF SURF COR, FT	
<b>#PRISMATIC COEF</b>	0.650	#SERV LIFE KG ALW, F	
#MAX SECTION COEF	0.951	WATERPLANE COEF	0.787
GMT, FT	6.39	WATERPLANE AREA, FT	
GML, FT	972.40	WETTED SURFACE, FT2	
#GMT/B AVAIL	0.100	GMT/B REQ	0.100
BARE HULL DISPL, LTON			
APPENDAGE DISPL, LTON			
FULL LOAD WT, LTON	7844.38		

## **B. FINALIZATION OF MAJOR SHIP CHARACTERISTICS AND COMBAT SYSTEMS ELEMENTS**

The previous section addressed work accomplished during the first academic quarter, when the RDS 2010 was modeled computationally and the synthesis portion of ASSET used in order to ensure convergence. However, at that time the cost did not come within the limit of \$350 million. The first order of business in the second academic quarter was to lower the cost. To make the design economically feasible and acceptable, many factors were adjusted to bring the cost within a workable range. Table 5-2 summarizes the major ship's characteristics attained during the final convergence of the ship RDS 2010 using the Monohull Surface Combatant version of the ASSET program.

TA	BLE 5-2. A	SSET SUMMARY, FINAL	RUN.	<u> </u>					
PRINTED REPORT NO.	1 - HULL	GEOMETRY SUMMARY							
MIN BEAM, FT MAX BEAM, FT	40.00								
	55.00								
HULL FLARE ANGLE, DEG	7.00								
FORWARD BULWARK, FT	4.00								
	RINCIPAL DI	MENSIONS (ON DWL)							
L8P, FT L0A, FT	390.00	PRISMATIC COEF	0.650						
LOA. FT		MAX SECTION COEF	0.919						
BEAM. FT	55.00	WATERPLANE COEF	0.787						
REAM & WEATHER DECK. ET	60.27	LCB/LCP	0.515						
DRAFT, FT	15.01	HALF SIDING WIDTH, FT DEPTH STA 3, FT DEPTH STA 20, FT	1.00						
DEPTH STA 0, FT	45.00	DEPTH STA 3, FT	41.46						
DEPTH STA 10, FT	36.50	DEPTH STA 20, FT	37.40						
FREEBOARD @ STA 3. FT	30.46	BARE HULL DISPL, LTON	5493.55						
STABILITY BEAM, FT	55.00	AREA BEAM, FT	54.17						
BARE HULL DATA ON	BARE HULL DATA ON LWL STABILITY DATA ON LWL								
	389.99								
LGTH ON WL, FT BEAM, FT DRAFT, FT	55.00	KB, FT BMT, FT KG, FT PRISMATIC COEF	16.92						
DRAFT. FT	14.99	KG. FT	19.59						
FREEBOARD @ STA 3, FT	30.48	PRISMATIC COEF	0.649						
FREEBOARD @ STA 3, FT MAX SECTION COEF	0.921								
WATERPLANE COEF	0.788	GMT, FT GML, FT	5.51						
WATERPLANE AREA, FT2	16904.38	GML, FT	763.36						
WETTED SURFACE, FT2	22804.14	BARE HULL DISPL, LTON	5496.68						
APPENDAGE DISPL, LTON	225.04	FULL LOAD WT, LTON	5721.71						

The cost was significantly reduced through various adjustments of hull material, stiffener spacing, deckhouse structure, and principal dimensions. The hull and structural material was changed to a steel with a higher strength-to-weight ratio, HY-80, resulting in a significant savings weight (200 tons). This in turn reduced the powering requirement, shrinking the length and displacement further because of the decrease in fuel required for endurance. Although this provided a significant cost savings as predicted by the ASSET cost module, it is surmised that the cost reduction in the real world might not have been as grand because of the added labor and quality assurance procedures associated with welding HY-80 steel.

Stiffener spacing was adjusted from a maximum allowed spacing of 24 inches to 48 inches, permitting the Huil Structures module of ASSET to better optimize the sizing and placement of stiffeners considering the complex relationship between the stiffeners and the plating to which they are welded. The use of enclaved auxiliary systems and fiber optic cabling will minimize the amount of space needed in the overhead. The hull average deck height was lowered from 10.5 feet to 9.95 feet to minimize the internal volume of the ship and permit the addition of another deck. The prismatic coefficient was adjusted in order to attempt a positive reduction in the size of the hull, but there was no apparent cost or volume savings. Apparently, the initial value of Cp = 0.65 was near optimum. The maximum section coefficient was adjusted downward as far as possible within the constraints of the hydrostatic limitations. This brought about savings in fuel usage and a higher sustained speed as a result of lowered resistance.

At the time of initial convergence the deckhouse size indicator had been set at "max", causing the deckhouse to extend over 50% of the ship at a three deck height. This was changed to "min" so that only the volume and area required for equipment and personnel would be generated, reducing the deckhouse weight by about 400 tons. Additionally, the

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hull flare angle and the deckhouse side angle offset were changed from zero to seven degrees in order to reduce the effective radar cross-section and improve appearance. We removed the forward auxiliary machinery room after assessing the machinery requirements recommended by the initial convergence. Removal of this space which was nearly empty returned approximately 10,000 ft<sup>3</sup> of internal arrangeable volume.

The double hull posed some challenges because the ASSET program is unable to deal directly with this concept. In order to have a double hull volume which is not lighted, heated nor air conditioned, it was necessary to make data base adjustments in the endurance range and payload to account for the extra volume available for tankage. By not lighting, heating nor air conditioning the double hull void, a significant reduction in electrical power was realized. The double hull volume below the waterline is used for endurance fuel tankage, while the volume above the waterline is reserved for buoyancy and for increasing internal blast resistance against anti-ship missile explosions. The issue of whether to fill these spaces with an energy absorbing material or to leave them void must be resolved during subsequent design iterations.

The helicopter hangar area was reduced by half as the helicopter compliment was reduced from two to one for cost reasons. The associated helicopter payload items were also reduced as required to support only one helicopter. The reinforced helicopter deck remains capable of supporting the larger CH-53 Sea King which is used to tow a mine clearing sled and could be used for evacuation of U.S. citizens from political hot spots.

These changes allowed a decrease in bare hull displacement of approximately 2000 tons to the current design displacement which is slightly under 5500 tons. While revisiting the subject of heating, we determined that it would be more cost effective to use a waste heat boiler to carry some of the ship hotel heating requirements. With a smaller ship, the

lighting, heating and ventilation requirements were also reduced, allowing a smaller ship service gas turbine generator set.

The use of integrated electric drive was abandoned during feasibility studies. Designing the RDS 2010 with this developing technology was unacceptable on the basis of the technical risk and cost involved, because the larger machinery rooms needed for the current generation of propulsion generators drove the ship length beyond 500 feet. Instead, the team chose four propulsion gas turbines (two per shaft), driving a standard mechanical reduction gear drive train, as the propulsion plant. Two of the three ship's service generators are powered from power take-off units attached to the reduction gears. one per shaft, to meet power requirements during cruising and battle conditions. The remaining ship's service generator is for standby use and is powered by a dedicated gas turbine. The four main gas turbines, which are currently the smallest available commercially, are larger than required for the ship's propulsion and electrical power needs. Use of even smaller propulsion turbines is preferable, since the mission speed requirements have been exceeded, but they are not presently available in production models. The option of going from the four small gas turbines to two larger gas turbines was not taken because of factors affecting machinery plant survivability and reliability. The fixed pitch propeller had to be replaced with a controllable pitch propeller to remain compatible with this propulsion train. This is a major disadvantage for shallow water operation because of the CRP complexity which makes it less robust than a fixed pitch propeller.

To minimize the technical risk involved in the development of the new mortar system, the first flight is designed to have both the new mortar system and the current version of the vertically launched ASROC.

### C. COST REDUCTION SUMMARY

After many major and minor changes, we came to the point of diminishing returns on ship modifications for the sole purpose of cost reduction. The ship cost had been nearly halved from \$850M, yet it did not come within the stringent \$350M requirement. There comes a point in many phases of design at which one phase of design must end before the next phase can begin. This point had arrived since for educational purposed we needed to proceed to the next phase of preliminary design. It was at that time the following request for an adjustment to the cost ceiling was made.

### D. REQUEST FOR ADJUSTMENT TO COST CEILING

During the first academic quarter, the RDS 2010 was modeled to be technically feasible, however, the follow-on ship cost did not come within the limit of \$350 million. To make the design economically feasible and acceptable, many factors were adjusted to bring the cost within a workable range. Currently, the projected cost from the ASSET Cost Analysis Module is \$809/476M for the first/follow-on ships respectively. The projected cost as determined using the Gibbs and Cox two digit cost estimating scheme was \$290M. To meet the mission requirements and provide adequate self-defense, the cost ceiling per follow-on ship should be raised to \$475M. This is strongly recommended in order to meet the mission requirements without degradation.

Certain features of the vessel could be modified in order to come closer to the present \$350M cost limit. Two likely options are: 1) removal of the LAMPS III system, or 2) reversion to a single hull. The drawback to removal of the LAMPS III system is a major degradation of the ASW mission area. Additionally, a single hull ship would be considerably more vulnerable to missile hits and mine explosions. If capability must be removed to remain within cost constraints, the options are recommended in the given

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order because the likelihood of being targeted by a missile is higher than being stalked by a submarine at long range.

In the current political environment it is entirely possible that no new class of ship will ever be built. As shipyards and defense contractors recognize this fact they may consider a reduction in profits in order to keep the production lines operating. This may serve to ameliorate the problem. It is recommended that the cost ceiling be raised to \$475 million dollars for follow-on ships.

### E. RESULT OF COST CEILING ADJUSTMENT PROPOSAL

The above proposal was approved and the cost ceiling extended to \$500 million.

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### VI. THE ENCLAVED SHIP

Ship's survivability is high on the list of design priorities. This is due to the emphasis in the "CNO Tentative Requirement Statement" (Section II.A.3) that this ship be highly survivable and minimize crew casualties. The design team considered a major design attribute to enhance the survivability was to enclave the ship. Enclaving is a concept for reducing ship vulnerability by dividing the equipment associated with the ship's mission capabilities into subsets which can be located in different autonomous or semiautonomous regions within the ship. This minimizes the loss of mission critical functions caused by a hostile weapon hit and maximizes the ability to fight hurt. Enclaving is the synergistic zoning of the combat system and H, M & E systems into regions which can function independently as required to provide a subset of the ship's mission capability. Without the positive side effects of this synergism, the prospect of enclaving could be too costly based on the installation of duplicate system elements. In addition to duplication of functionality, the concept of alternate functionality of equipment is used to enhance the enclaving concept. By this we mean, for instance, the ability to use a surface search radar as a less capable, but backup air search radar. When survivability and cost are approached from the perspective of numbers of ships available to fight, a more survivable ship is a more valuable asset to the nation.

There are two types of decision making involved in designing an enclaved combatant. Major conceptual decision making is usually done by higher authorities while the actual engineering tradeoff decision making is performed by the shipbuilder's detailed design

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team. Additionally, since the combat weapon system, H, M & E support systems, propulsion systems and other necessary ship's systems are a complex total ship system package, the need exists for an iterative design approach in which the effects of certain decisions are monitored for overall effect and modified by the total system integrator (ship design management team). The design challenge is to *enclave* while minimizing the addition of duplicate equipment. As the art of interface engineering evolves and standards are narrowed, the ability to *enclave* is enhanced.

The goal is to enclave functionality and arrange associated support systems to allow the loss of a single enclave without reducing the support services required by the other enclaves to maintain their combat system equipment operational. A worthy goal is to ensure that support systems not included in an enclave are available from the adjacent enclave. Each enclave is provided with self-sufficient damage control capability. Electrical power will be available from the ship's service ring bus and interior communications data will be available from the fiber optic data bus. Although the central damage control console will be located in the Central Control Station, each enclave will get its automatic and real time human generated damage control commands via one of the five fiber optic data buses. For the sake of damage control and mission war fighting capability, it is desirable that the personnel be berthed within each enclave near their general quarters or damage control station.

For the sake of producibility and reduction in cost, *zones* have been established that often coincide with the *enclave* boundaries. The boundaries extend vertically from the keel to the weather deck and horizontally for two to four subdivisions (i.e. compartments).

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### A. FACTORS AFFECTING EQUIPMENT COMBINATIONS

There are a number of factors which affect the actual location and the combinational synergism of equipment placement. These factors are the major determinants in the design teams decision making process when it came to locating specific equipment onboard the ship:

1. constraints of topside arrangement;

2. collocation of interdependent or series combat system equipment;

3. separation of functionally parallel combat systems equipment by at least one weapon damage perimeter;

4. enclave boundaries determined by existing zones (collective protection, fire, flooding, etc.);

5. balance enclaving with other factors of the ship design via the design philosophy;

6. minimize the crossing of boundaries for ease of producibility;

7. armored cable ways protect fiber optic and power cables; and

8. loss of a single enclave will not degrade other enclaves.

### **B. ENCLAVE ARRANGEMENT**

Table 6-1 lists many of the major ship systems and equipment by enclave. Figure 6-1 illustrates the physical enclave boundaries overlaid on the ship.

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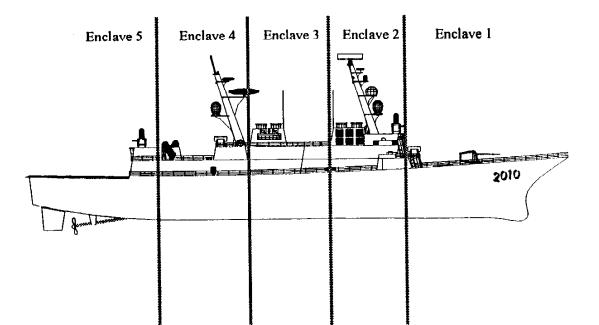
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ENCLAVE #5	ENCLAVE #4	ENCLAVE #3	ENCLAVE #2	ENCLAVE #1
AN/SLR-24 SSTD	Aft Mast:	SSES	Fwd Mast:	Sonar Equip room
Mk 16 CIWS	Mk 92 #2	LC #4	Mk 92 #1	Sonar SW pumps
LAMPS III interface	IFF	LC #5	SAR-8	UWFCS
SQQ-28 Lamps Mk	TACAN	FP #3	Furuno	Mk41 VLS Launcher
III elec	SPS-67 surf search	CIC	Mk-23 TAS	(16 celi)
Aviation Support	SPS-49 air search	Radio Group #1	SPQ-9	VLS magazine de-
HIFR	#2 SVTT	CW Plant #2	SPS-64 surf search/	watering system
Helo rearm and	Alt CIC	<b>Collective Protection</b>	nav	Combat Maintenance
magazine.	Harpoon CLS	Fans #2	Pilot house	Central
LC #7	Harpoon missile	#2 HPAC	Nav Center	Mk-86/5" 54
LC #8	storage	UUV	#1 SVTT	Gun mount
FP #5	HWCC	SRS-1 Combat df	SLQ-32 Mk36	Ammunition storage
Ammunition storage	SWG-1A Harpoon	Countermeasure	Mk 16 CIWS	#1 Mk 31 RAM
Hospital room	Mk41 VLS Launcher		DCC/CCS	PDMS
Pyro storage	(16 cell)	ER #2 w/ GT # 3 & 4	Mortar Launcher #1	RAM missile storage
JP5 Pump room	VLS mag dewatering	#2 VSCF Gen/	LC #3	LC#1
Steering room	system	cycloconverter	FP #2	LC#2
	#2 Mk 31 RAM	SWBD 2SG	IC SWBD FWD	FP #1
	PDMS	SWBD 2SA	CW Plant #1	SWG-3A Tomahawk
	RAM missile storage	SWBD 2SB	Collective Protection	
	Mortar Launcher #2		Fans #1	#1 HPAC
	IC SWBD AFT		Ammunition storage	
	Radio Group #2		#1 EX-35 25mm	
	LC #6		w/stinger	
	FP #4		#2 EX-35 25mm	
	CW Plant #3		w/stinger	
	<b>Collective Protection</b>		Countermeasure	
	Fans #3		launchers	
	#3 HPAC		ER #1 w/ GT # 1& 2	
	AMR w/SSGTG		#1 VSCF Gen/	
	SWBD 3SG	1	cycloconverter	1
I	SWBD 3SA	l	SWBD 1SG	
	SWBD 3SB		SWBD ISA	
			SWBD 1SB	

### TABLE 6-1. LOCATION OF MAJOR EQUIPMENT AND FUNCTIONS BY ENCLAVE..

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### Figure 6-1. Enclave Boundaries.

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#### VII. SHIP'S ELECTRICAL GENERATION AND DISTRIBUTION SYSTEM

The original vision of the ship's electrical generation and distribution system consisted of an integrated electrical drive plant with ship's service power derived from power converters. These power converters would change the unregulated (voltage and frequency) propulsion bus power to 60 Hz, 450 Vac standard shipboard power. This scheme had many merits in an enclaved ship due to the natural distributed ship's service power generation that results. As mentioned in Chapter 5, however, the integrated electric drive option had to be dismissed due to difficulties in manipulating the ASSET program.

We did maintain a form of propulsion derived ship's service power, however. The propulsion plant is a standard two gas turbine per shaft mechanical-reduction gear coupled system. There are power takeoff (PTO) units on each reduction gear coupled to high speed, high frequency generators. The output of these generators feed a solid-state power converter which conditions the power to regulated three-phase, 60 Hz, 450 Vac standard ship's service power. To achieve the required n-1 redundant capacity, a third ship's service gas turbine generator (SSGTG) is included in the plant design.

By using PTO fed generators, the need for dedicated prime movers for two of the three ship's service power sources is removed. This should decrease weight and increase available volume within the ship. In addition, high speed generators are smaller and lighter than equivalent power 60 Hz generators.

The distribution scheme chosen is a standard three power source ring bus configuration. Enclaving is enhanced by using a modified zonal distribution scheme off the ring bus with multiple load centers strategically placed throughout the ship. Figure 7-1 shows the ring bus structure. Figure 7-2 shows the geographic locations of the generators

and load centers. Figure 7-3 indicates the interconnectivity of the power distribution system and major ship's loads.

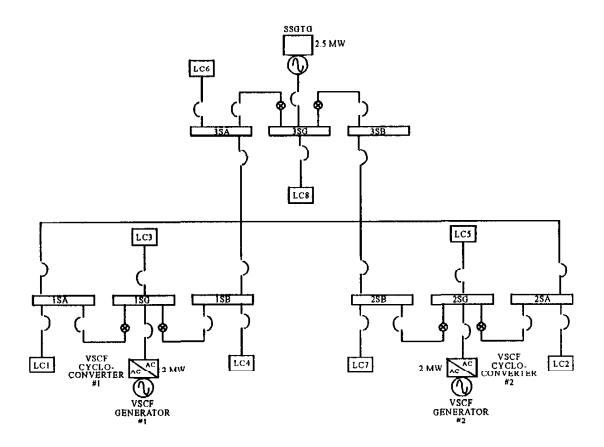


Figure 7-1. Bus Tie Diagram.

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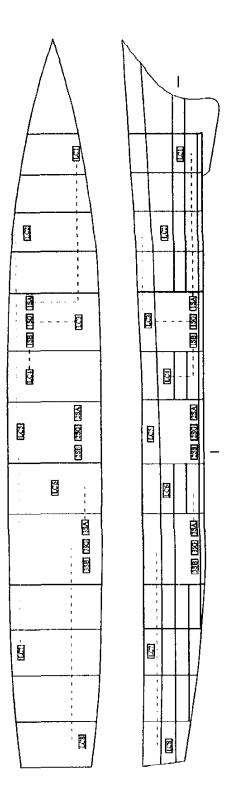
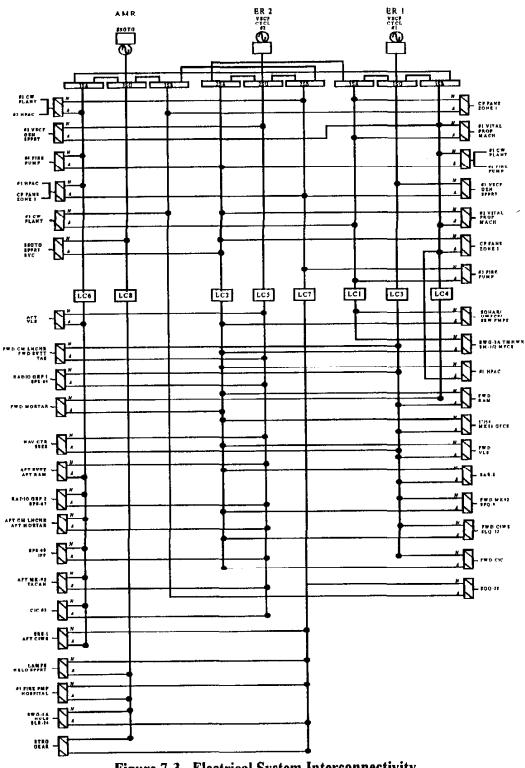
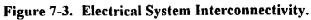


Figure 7-2. Load Center Locations.

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#### VIII. SHIP DESCRIPTORS

There is some overlap between the end of feasibility studies and the start of preliminary design. In some respects, all work performed after the first successful convergence of an ASSET run could be considered preliminary design. On the other hand, it could be argued that preliminary design began after the major modifications to the initial design concepts were completed and a revised cost ceiling was approved. One obvious departure from actual practice was our use of ASSET beyond the feasibility studies, into what traditionally is considered preliminary design. This adds to the "fog" which surrounds the delineation. Additionally, design aspects such as electrical plant design and combat system definition, which did not use ASSET in any substantial way, make it hard to say which work actions were feasibility studies and which were preliminary design.

At the completion of the design process, however, we have a ship design that would be typical of the work presented at completion of preliminary design. Clearly, the details and rigor of analysis is lacking due to the short time duration and minimal human resources available to complete the work. The previous chapters have shown some of the non-naval architectural design products from preliminary design. This chapter presents the naval architectural "ship descriptors". Some of these items were produced by ASSET whereas other were completed by members of the design team.

One of the many tasks, from the faculty, was to provide the following:

- 1) complete lines drawing, to include sheer, body and waterline plans;
- 2) displacement and other curves;
- 3) curve of static stability;
- 4) general arrangements drawings, showing arrangement for each deck;

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- 5) detailed compartment arrangement drawings for:
  - CIC and
  - pilot house;
- 6) discussion of hull damage length chosen (and why);
- 7) floodable length curve illustrating damage length criterion is satisfied;
- 8) structural report consisting of:
  - weight curve,
  - load curve for hull, and
  - midships section design.

#### A. NAVAL ARCHITECTURAL CURVES

#### 1. Hull Geometry

The ship's lines describe the form of the ship's hull, and are presented in a series of two-dimensional drawings refereed to as the lines drawing. The three basic projections are the sheer plan, the half-breadth plan, and the body plan. Figure 8-1 shows these projection of ships lines for the RDS-2010, without modifications made during preliminary design. These projections were produced manually, using data generated by the ASSET program. Note that ASSET did not include the hull mounted SONAR bow dome.

#### 2. Hull Coefficients

The form coefficients which apply to this ship's hull form were calculated by ASSET and plotted as a function of draft. Figure 8-2 shows the variation of the block coefficient ( $C_B$ ), prismatic coefficient ( $C_P$ ) and waterplane area coefficient ( $C_{WP}$ ) versus draft. Note the design draft was chosen to be 15 feet.

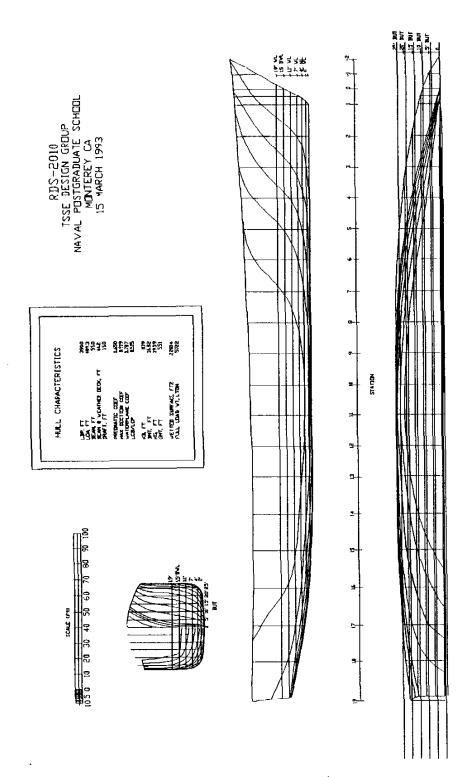
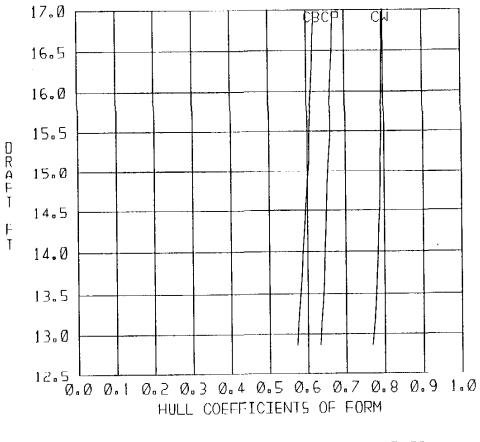


Figure 8-1. RDS-2010 Lines Drawing.

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STREET BREAKING OF



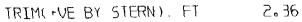


Figure 8-2. Hull Coefficients of Form.

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#### 3. Displacement and other curves

The hydrostatic curves, also known as the Curves of Form, were produced by ASSET for the RDS-2010 hull without the bow SONAR dome. These curves are shown in Figure 8-3 and include the following items as designated here:

- A Displacement in salt water (DISPL) (Note: the draft used for this and all the other curves is the mean draft to the bottom of the keel.)
- *B* Moment to trim one inch (MT1)
- C Tons per inch immersion (TP1)
- D Transverse metacentric radius (BMT)
- *E* Longitudinal metacentric radius (BML)
- F Center of buoyancy above bottom of keel amidships (KB)
- G Change in displacement per unit trim by stern (CID1TS)
- *H* Wetted surface area (WSURF)

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- *I* Longitudinal center of buoyancy (LCB)
- J Longitudinal center of flotation (LCF)

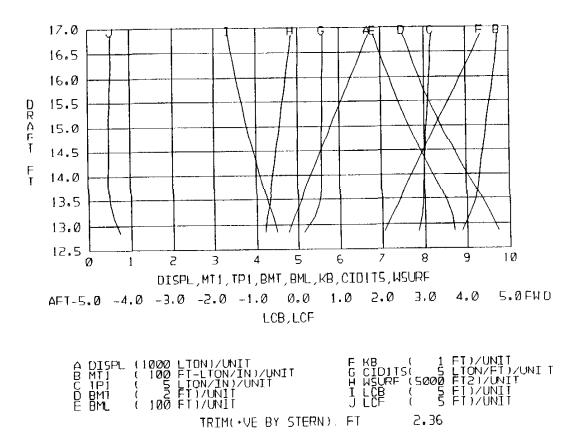


Figure 8-3. Displacement And Other Curves.

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#### 4. Static Stability

All ship designs require sufficient initial stability and buoyancy to enable the ship to withstand the effects of external influences and internal movements. *Intact criteria* consists of a number of requirements including withstanding the effect of beam winds, lifting of heavy weights over the side, towline pull, crowding of personnel to one side, high speed turning, and topside icing.

Beam wind, when combined with the ship's roll, is typically the governing case for intact stability. For this ship design, the ship must be expected to weather the full force of tropical cyclones. The criteria for adequate stability under adverse wind and sea conditions is based on a comparison of the ship's righting arm curve and the wind heeling arm curve. Figure 8-4 is the static stability curve and wind heeling arm curve produced by ASSET for the RDS-2010.

Stability is considered satisfactory if (1) the heeling arm at the intersection of the righting arm and heeling arm curves is not greater than 60% of the maximum righting arm; and (2) the area between the two curves to the right of their intersection is not less than 140% of the area between the two curves to the left of their intersection. Inspection of Figure 8-4 shows that both of these criteria are met.

To examine the high speed turn stability problem, the turn heeling arm curve is plotted on the same graph as the static stability curve. This is shown for the RDS-2010 in Figure 8-5. The following criteria must be satisfied to ensure adequate stability: (1) the angle of steady heel does not exceed 10 degrees, (2) the heeling arm at the intersection of the righting arm and heeling arm curves are not more than 60% of the maximum righting arm, and (3) the reserve of dynamic stability (area between the two curves to the right of their intersection) is not less than 40% of the total area under the righting arm curve. Examination of Figure 8-5 shows that all criteria are met.

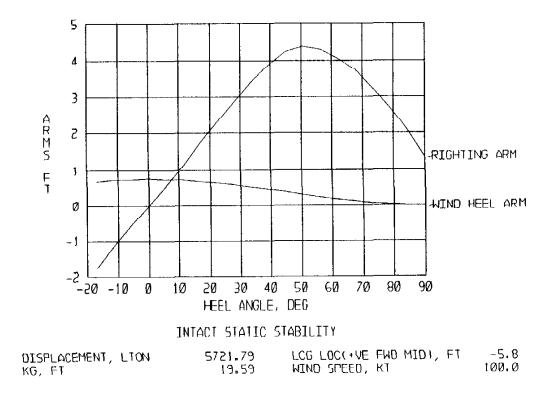


Figure 8-4. Static Stability Curve with Wind Heeling Arm.

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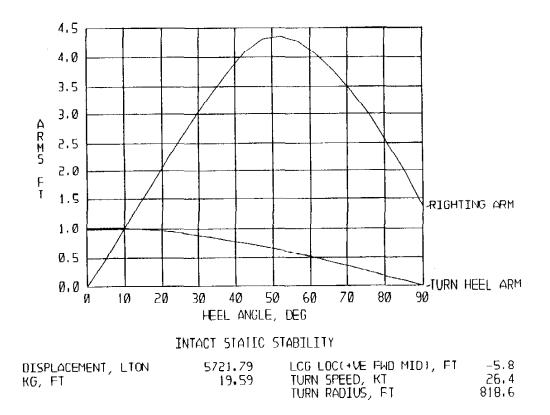


Figure 8-5. Static Stability Curve with Turn Heeling Arm.

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Additionally, the Damage (Underwater flooding) Criteria must be verified as satisfactory. For ships over 300 feet in length without a side protection system, such as the RDS-2010, the ship must be able to withstand flooding from a shell opening equal to 15% of the ship's length at any point fore and aft along the length. The following items must be met to satisfy this flooding criteria: (1) the static trimmed-heeled waterline after damage does not submerge the margin line; (2) the static heel angle without wind effects does not exceed 15 degrees; (3) adequate dynamic stability exists to absorb the energy imparted to the ship by moderately rough seas in combination with beam winds (this is the area between the righting arm curve and wind heel arm curve); (4) the righting arm curve is terminated at the 45 degree point. Figure 8-6 shows the righting arm curve and wind heel arm curve for the RDS-2010 as generated by the ASSET program.

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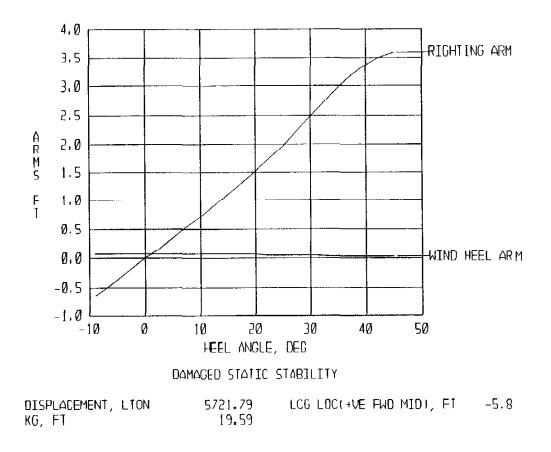


Figure 8-6. Damaged Static Stability Curve.

#### **B. ARRANGEMENTS**

The ship design team was tasked with completing some internal and topside arrangements. Internal space allocation level of detail arrangements were completed for all internal spaces. In addition, detailed compartment arrangements were completed for the primary Combat Information Center and the pilot house. Finally, the topside arrangements were completed, ensuring proper placement of combat system sensors and engagement elements to allow for maximum combat effectiveness.

#### 1. Internal Arrangements

Figures 8-7 through 8-13 show the general (space allocation) arrangements of the 03 through 01 deck levels, and the main through fourth deck levels, respectively. The goal here was to ensure that sufficient space was allocated for all functions as defined by the ASSET program and to ensure that the location of these spaces met the overall ship design goals. Specific emphasis was placed on ensuring the integrity of the enclaving philosophy.

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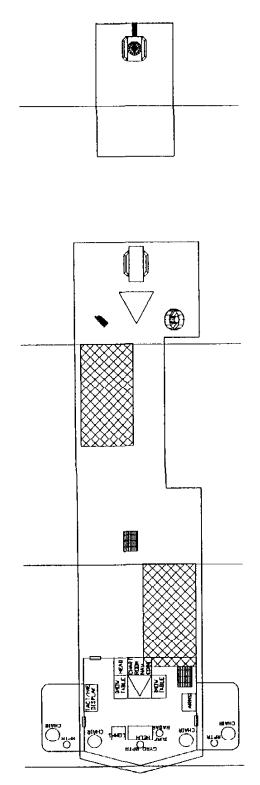


Figure 8-7. 03 Level General Arrangements.

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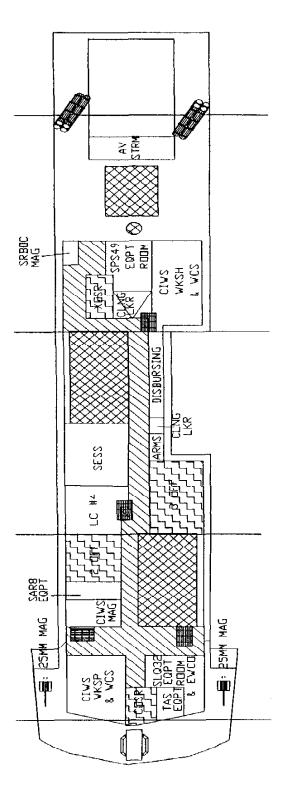


Figure 8-8. 02 Level General Arrangements.

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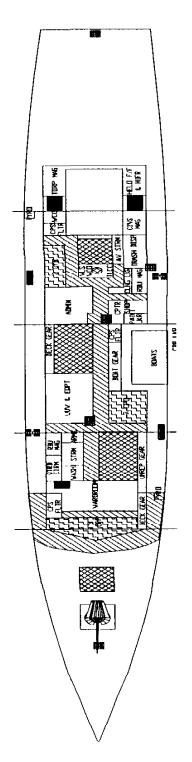


Figure 8-9. 01 Level General Arrangements.

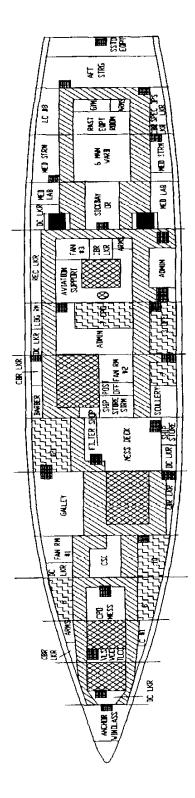


Figure 8-10. Damage Control Deck General Arrangements.

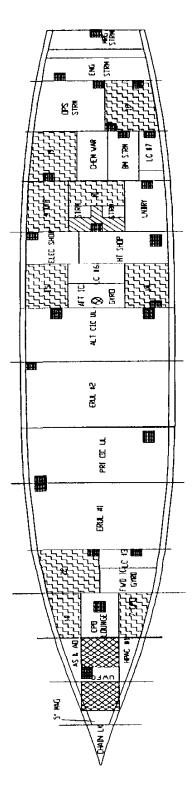


Figure 8-11. 2nd Deck General Arrangements.

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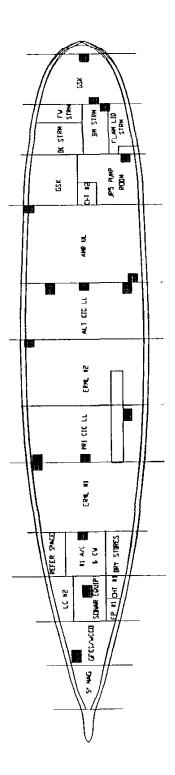


Figure 8-12. 3rd Deck General Arrangements.

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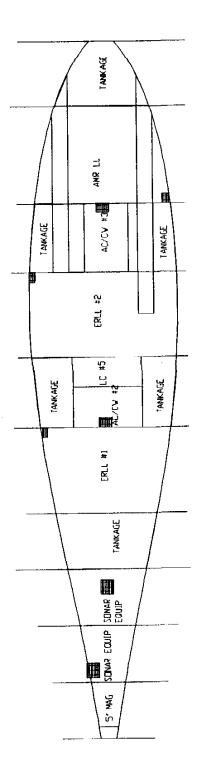


Figure 8-13. 4th Deck General Arrangements.

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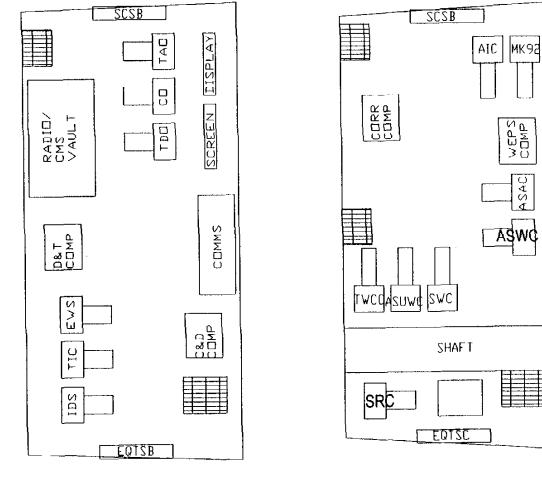
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#### 2. Detailed arrangement

Two spaces, the primary Combat Information Centers (CIC) and the pilot house, were arranged in detail. Figures 8-14 and 8-15 show these results.



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Figure 8-14. Primary CIC Detailed Arrangement.

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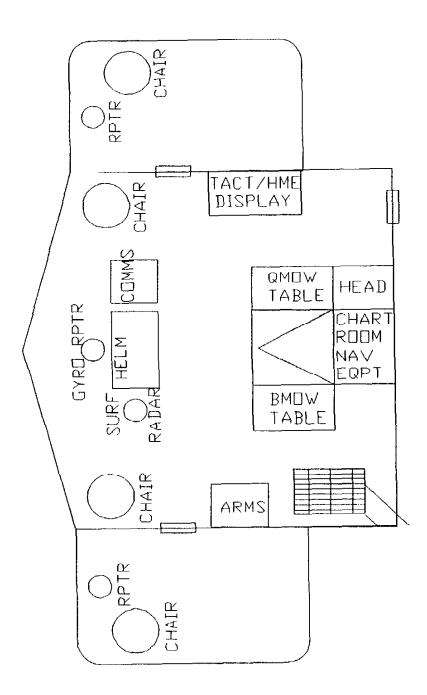


Figure 8-15. Pilothouse Detailed Arrangements.

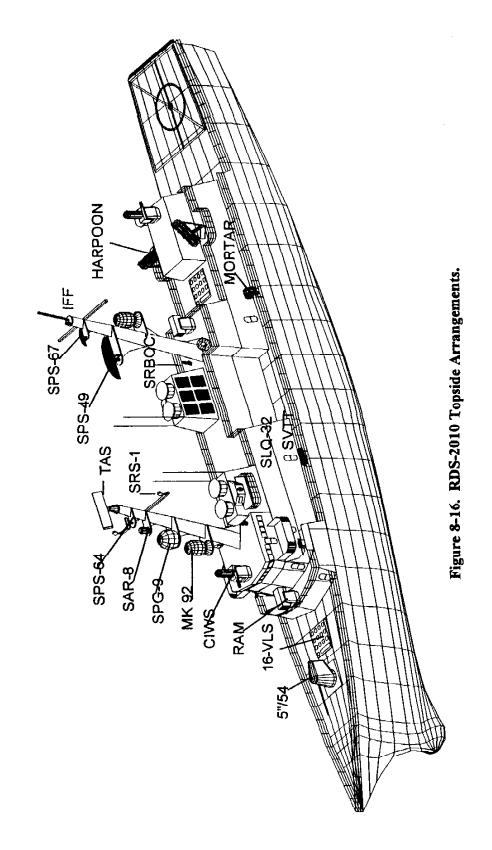
#### 3. Topside Arrangement

The goal in topside arrangements is to obtain a topside layout which maximizes combat system effectiveness and still allows for operational requirements. The design team felt that a need to follow a specific design process was required in order to support such a goal. The team agreed to use the following process:

- a. review mission requirements and design constraints,
  - (1) identifying elements needing to be high and
  - (2) identifying elements needing clear arcs of fire;
- b. identify required topside elements;
- c. prioritize need/satisfaction for elements;
- d. layout ship model;
- e. assess ship performance; and
- f. iterate until performance is acceptable.

Based on this process we felt that optimum locations were chosen for the topside components. Potentially competing requirements such as maintaining the enclaving scheme topside, ensuring adequate arcs of coverage for detection and engagement elements, while minimizing the overall impact on operational requirements, had to be reconciled. Figure 8-16 shows the location of the major topside components (primarily combat system detection, track and engagement elements).

During the topside arrangement phase, the arcs of coverage of the various weapons systems had to be checked for adequate coverage and minimal interference. This was done solely on a geometric scale and did not involve the use of any blockage assessment models.

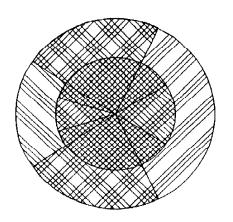


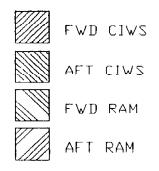
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# AAW SELF DEFENSE

RANGE (NM)

360 degree of coverage out to 65 nm with SM 1/2 missiles

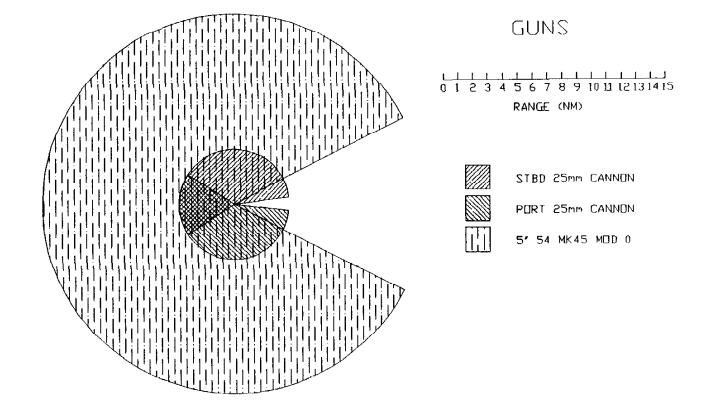




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Figure 8-17. Arcs of coverage for AAW self-defense weapons.



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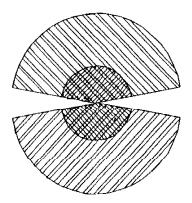
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Figure 8-18. Arcs of coverage for ship's guns.

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## ASW DEFENSE

## 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 RANGE (NM)



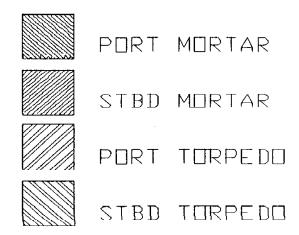


Figure 8-19. Arcs of coverage for ship's ASW defense weapons.

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#### C. HULL DAMAGE AND FLOODABLE LENGTH

Before a discussion of hull damage and floodable length can begin, several items must be defined for the purpose of clarity. These items are:

Bulkhead deck -- The bulkhead deck is the uppermost deck to which the transverse watertight bulkheads extend.

Margin line -- The margin line is a line drawn parallel to, and a minimum of three inches below, the bulkhead deck at the side.

*Permeability* -- Permeability is the percentage of volume in a space that can be flooded. It is expressed as the ratio of available volume to total volume.

Floodable length -- Floodable length is the maximum length that a given longitudinal position within a ship can be symmetrically flooded at the prescribed permeability without sinking below the margin line.

Factor of subdivision -- The factor of subdivision is an arbitrary factor applied to the floodable length to obtain the permissible length of compartments within a ship. The factor of subdivision is prescribed by national and international rules and conventions as a function of ship length and type of service. Generally, the factor of subdivision ensures that one, two or three compartments must be flooded before the ship settles to the margin line. Ships designed to these rules are sometimes called one-, two-, or three-compartment ships with reference to their damaged-stability capabilities.

*Permissible length* -- The permissible length of a compartment within a ship is obtained by multiplying the value of the floodable length at the center of the compartment by the factor of subdivision.

Curve of floodable length -- The curve of floodable length is a curve which at every point in its length has an ordinate representing the length of ship that may be flooded with the center of length at that point without submerging the margin line.

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1. Numerous considerations are involved in determining the optimum arrangement of subdivisions for a naval combatant, but the principal factors are:

- a. ability to survive underwater damage;
- b. protection of vital spaces against flooding;
- c. interference of subdivision with arrangements;
- d. interference of subdivision with access and systems;
- e. provision for carrying liquids;
- f. possibility of bow-collision damage; and
- g. possibility of stranding.

There are always conflicts among these various factors, hence their relative importance must be determined.

For the design of RDS-2010 the first four factors were considered to be most important thereby driving the design to have transverse bulkheads placed as shown in Figure 8-20. The standard rule used by the U.S Navy for floodable length calculations is that the ship be able to accept damage to the hull which results in an opening to the sea of fifteen percent of the length between perpendiculars without submerging the margin line. This value for the RDS-2010 is 58.5 feet. This means that the design must accept a damage length of 58.5 feet anywhere in the hull. This damage length requires that the RDS-2010 be a four-compartment ship.

2. Referring to Figure 8-20, it is seen that for a continuous permeability of 0.95 the design meets the required damage length and is in fact a four-compartment ship. If the permeability of each subdivision was updated to the actual value, the floodable length curve would move upward resulting in larger floodable lengths, improving the apparent survivability of the design. The plot of the floodable length curve shown in Figure 8-20

depicts the worst case scenario (total ship permeability equal to 0.95) to ensure that the design criteria were met.

Reference [5] provides more information on the construction of a floodable length curve.

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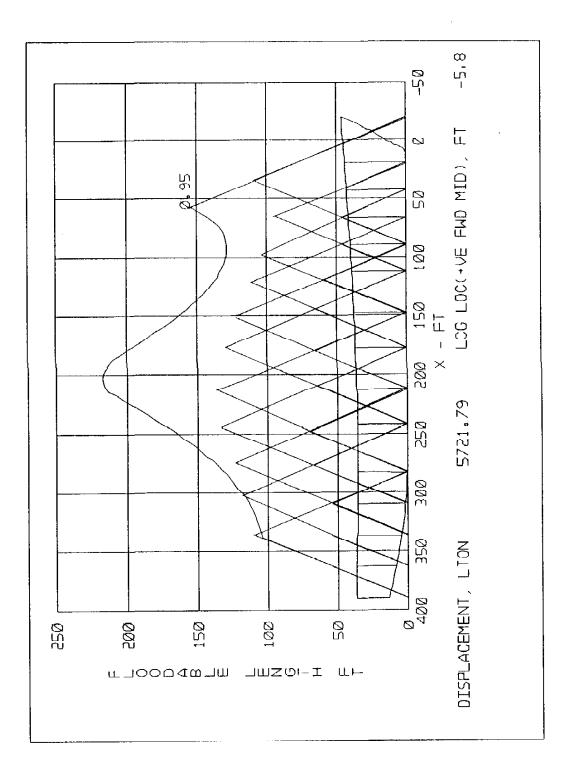


Figure 8-20. Floodable Length Curve.

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#### D. SHIP STRUCTURE REPORT

#### 1. Ship Structural Loads

The size and principal characteristics of a ship are determined primarily by its mission, intended service, and cost. In addition to basic functional considerations there are requirements such as stability, low resistance and high propulsive efficiency, good sea keeping, and navigational limitation on draft or beam, all of which influence the choice of dimensions and form. The ship's structure must be designed, within these and other basic constraints, to sustain all of the loads expected to arise in its seagoing environment. In contrast to land based structures, the ship does not rest on a fixed foundation but derives its entire support from buoyant forces exerted by a dynamic and ever changing ocean environment, which is both the friend and enemy of the ship.

The structural components of a ship are frequently designed to perform a multiplicity of functions in addition to that of providing the structural integrity of the ship. Furthermore, many strength members serve dual functions. For example, bulkheads that constitute substantially to the strength of the hull may also serve as watertight boundaries of internal compartments. Their locations are dictated primarily by the required tank volume or subdivision requirements.

The loads that the ship structure must be designed to withstand have many sources. There are static components which consist principally of the weight and buoyancy of the ship in calm waters. There are dynamic components caused by wave induced motions of the ship, and by slamming or springing in waves, as well as vibratory loads by the propeller and machinery, all of which range over different frequency ranges. An important characteristic of these load components is their variability with location and time (North Atlantic conditions in January are far from being the same as Mediterranean in July), and with the particular voyage (lightship versus fully loaded conditions). Furthermore, the loads imparted by the sea are random in nature, and therefore the ship's structural behavior can be expressed only in probabilistic terms.

a. Four principal mechanisms are recognized as causing most of the cases of ship structural failure, aside from collision or grounding. These modes of failure are as follows:

- (1) excessive tensile or compressive yield;
- (2) buckling due to compressive or shear instability;
- (3) fatigue cracking; and
- (4) brittle fracture.

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The problem of ship structural design then consists of the selection of material types, frame spacing, frame and stiffener sizes, and plate thicknesses, becoming an integrated part of the design spiral.

b. It is convenient to divide the loads acting on the ship structure into four main categories, based partly upon the nature of the load and partly upon the ship's response:

(1) Static loads are loads that change only when the weight of the ship changes. These include:

- (a) weight of the ship and its contents;
- (b) static buoyancy of the ship at rest or in motion;
- (c) thermal loads resulting from temperature gradients within the hull; and
- (d) concentrated loads caused by dry docking or grounding.

(2) Low frequency dynamic loads are loads that vary in time with periods ranging from a few seconds to several minutes, therefore they do not result in any

periods ranging from a few seconds to several minutes, therefore they do not result in t

appreciable resonant amplification of the stresses induced in the structure. These can be broken down into the following components:

- (a) wave induced hull pressure variations;
- (b) hull pressure variations caused by transient ship motions;
   and
- (c) inertial reactions resulting from the acceleration of the mass of the ship and its contents.
- (3) High frequency dynamic loads are time varying loads of sufficiently

high frequency that they may induce vibratory response of the ship structure. Some of the exciting loads may be quite small in magnitude but, as a result of resonant amplification, can give rise to large stresses and deflections. Examples of such dynamic loads include the following:

- (a) hydrodynamic loads induced by propulsive devices;
- (b) loads imparted to the hull by reciprocating or unbalanced machinery;
- (c) hydrostatic loads resulting from interaction of appendages
   with the flow past the ship; and
- (d) wave induced loads due primarily to short waves whose frequency of encounter overlaps the lower natural frequencies of hull vibration, called *springing*.

(4) Impact loads are loads resulting from slamming or wave impact on the bow, including the effects of green water on deck. In a naval ship, weapon effects constitute a very important category of impact loads. Impact loads may induce transient hull vibration that is called *whipping*.

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c. The most important classes of loads are the static loads resulting from the ship's weight and buoyancy, and the low frequency dynamic loads, while springing loads are important in very long flexible ships such as the Great Lakes carriers. In addition to the above four main categories, there may exist specialized operational loads, which may be the dominant loads for certain ship types. Examples of such loads, which may be either static or dynamic, are:

(1) ice loads in the case of a vessel intended for ice breaking or Arctic navigation;

(2) loads caused by impact with other vessels, as in the case of tugs and barges;

(3) impact of cargo handling equipment;

(4) structural thermal loads imposed by special cargo carried at extreme temperature and/or pressures;

(5) sloshing and impact loads on internal structures caused by movements of liquids in tanks; and

(6) aircraft or helicopter landing forces.

#### 2. Static loading.

The two main categories involved in static loading are the weight of the hull and its components and buoyancy, as shown in Figure 8-21. The individual loads may have both local and overall structural effects. A very heavy piece of machinery induces large local loads at the points of attachment to the ship; therefore its foundation must be designed to distribute these loads evenly into the hull structure. Simultaneously, the weight of this piece of machinery contributes to the distribution of shear forces and bending moments acting along the length of the hull.

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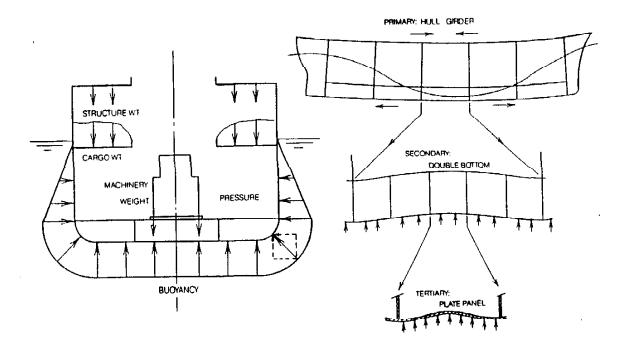


Figure 8-21. Static loads and structural response.

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The geometrical arrangement and resulting stress and deflection patterns of typical ship structures are such that the associated response a usually divided into three components, as shown in Figure 8-21. The primary response is the response of the entire hull, when bending and twisting as a beam, under the external longitudinal distribution of vertical, lateral, and torsional loads. Study of this response constitutes the longitudinal strength calculations and are usually performed in ship structural analysis and design. The secondary response comprises the stress and deflection of a single panel of stiffened plating. The loading of the panel is normal to its plane, and the boundaries of the secondary panel are usually formed by other secondary panels, such as side shell and bulkheads. The tertiary response describes the out of plane deflection and associated stress of an individual panel, and its boundaries are formed by the stiffeners of the secondary panel of which it is a part. The last two responses can be evaluated using the familiar laws of structural member response from solid mechanics.

A typical longitudinal distribution of weight and buoyancy for a ship afloat in calm water is illustrated in Figure 8-22. In the lower part of this figure is plotted a curve (1) of buoyancy force per unit length, which is equal to the weight density, pg, of the water times the sectional area. For any waterline shape, the buoyancy curve can be easily obtained from the Bonjean curves. The upper curve (2) of Figure 8-22 shows the longitudinal distribution of the weight force, which essentially consists of a book-keeping process in which every item aboard the ship is recorded and assigned to a particular location. The total load acting on the ship is

$$f(x) = b(x) - w(x)$$

where b(x) is the buoyancy per unit length, and w(x) the weight per unit length. The conditions for static equilibrium require that the integral of the total load over the ship length and the integral of the longitudinal moment of the load curve each be zero. As in

standard beam calculations, the shear force at some location  $x_1$  is equal to the integral of the load curve,

$$V(x_i) = \int_0^{x_i} f(x) dx;$$

and the bending moment is the integral of the shear force

$$M(x_1) = \int_0^{x_1} V(x) dx.$$

It can be observed that the shear force and bending moment are zero at the bow and the stern, as they ought to be since the ship is essentially a free-free beam resting on an elastic foundation. Besides the still water buoyancy curve at the design waterline, two other conditions are traditionally studied, as shown in Figure 8-22. The first is that of a wave of length equal to the length of the ship located with its crest at amidships, and this condition is called *hogging*. The second wave condition traditionally studied is that of a wave whose trough is located amidships, and this condition is called *sagging*. Although no dynamic affects are considered in the sagging and hogging conditions, they can be used to provide extreme loading conditions for comparative or design purposes when combined with the appropriate ship loading condition.

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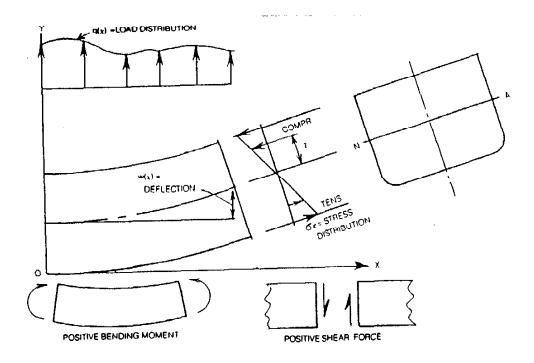


Figure 8-22. Static loads, shear, and bending moment.

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#### 3. Wave induced loading.

The principal wave induced loads are those previously referred to as low frequency dynamic loads or loads involving ship and wave motions that result in negligible dynamic stress amplification. The calculation of the bending moment, shear force, and torsional loading on a ship hull due to waves requires a knowledge of the time varying fluid pressure distribution over the wetted surface of the hull together with the distribution of the inertial reaction loads. The fluid loads depend on the wave induced motions of the water and the corresponding ship motions, which in turn depend on the fluid loads. One popular solution to this complicated problem involves the use of *strip theory*, where the ship a divided into narrow transverse strips. This allows the reduction of a three dimensional problem into a family of two dimensional problems that are easier to solve. The results then are integrated along the length of the hull.

a. One of the important assumptions of linear strip theory is that both the wave and ship motion amplitudes are, in some sense, small. As a result it is possible to consider the total instantaneous vertical force on a thin transverse strip to be composed of the sum of several terms that are computed independently of each other. Two of these forces are the still water buoyancy and weight of the element of the ship length, in other words the static loads from the previous section. The remaining forces are time varying and result from inertial reaction and from the water pressures, and can be divided into the following categories:

(1) A wave pressure force component computed as though the presence of the ship does not disturb either the incident waves or the dynamic pressure distribution in those waves. This is called the *Froude-Krylov* force.

(2) A wave pressure force component computed from the properties of the diffracted wave system. These waves result from the reflection and distortion of the incident waves as they impinge upon the ship, and is called the *diffraction* force. Together with the Froude-Krylov force, it is sometimes referred to as the *wave exciting* force.

(3) A term proportional to the instantaneous vertical displacement of the ship strip from its mean position, as if in calm water. This is called the *hydrostatic* restoring force and is equal to the change in the mean static buoyancy of the element.

(4) A term proportional to the instantaneous vertical velocity of the element, called a *damping* force.

(5) A term proportional to the instantaneous vertical acceleration of the element called an *added mass* force. The added mass and damping forces are also known as the *radiation* forces since as a result of the ship motions, a wave system that radiates away from the ship is generated.

The first two of the above forces are computed as though the ship moves steadily forward through the waves but experiences no oscillatory motion response to the wave forces. The last three forces are computed as though the ship is undergoing its oscillatory wave induced motion while moving at a steady forward speed through calm water. Within the assumptions and limitations of linearity, such a breakdown is permissible.

In addition to the sum of the above forces q(x), there must be added the inertial force  $-m(x)a_r$  per unit length, where m(x) is the mass of the strip and  $a_r$  is the vertical absolute acceleration of the ship strip. The wave induced loading per unit length is then

$$f_w(x) = q(x) - m(x)a_z,$$

and the wave induced shear force and bending moment are obtained by successive integrations of the load.

Figure 8-23 illustrates the different components of the load distribution at a fixed time for a typical Mariner class cargo ship moving through a simple sinusoidal wave

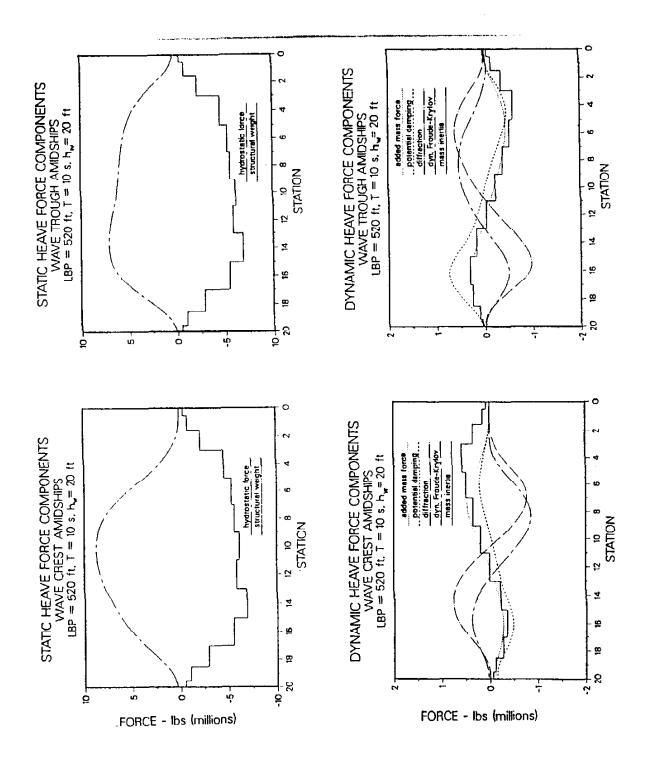


Figure 8-23. Typical wave induced ship loads.

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of unit amplitude. We can see that the total loading consists of a number of tears of similar magnitude which may differ in sign and phase. There may be cancellation or reinforcement among the different components, with the result that the total loading may be larger or smaller than any individual component. This cancellation or reinforcement varies along the ship length and also varies with the frequency of wave encounter.

Although the above discussion was made with a view towards vertical ship motions (heave and pitch), a similar concept can be applied for the horizontal motions (sway and yaw). The transverse distribution of wave loads is also necessary to compute the secondary or tertiary response of structural components such as panels of stiffened or unstiffened plating.

b. Finally, the above deterministic load can be extended through the use of statistical analysis techniques, to reflect the probabilistic nature of wave loads. The statistical quantities that are usually of concern in ship strength investigations are divided into three categories:

(1) Short-term mean and extreme values. These refer to the period of time of a few hours during which the sea remains statistically stationary under normal climatic conditions.

(2) Long term mean and extreme values. These refer to a longer time period, days or years, during which the sea state may vary widely from calm to severe storm conditions. The long term response may be thought of as an accumulation of short term responses to different sea states, each having uniform or statistically stationary characteristics.

(3) *Cumulative cyclic values*. These refers to long term cyclic loading that may cause fatigue damage to the structure, even under moderate to low level of bending moment and stress.

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# **B. LONGITUDINAL STRENGTH.**

The term longitudinal strength refers to the overall structural behavior of a ship as a thin walled hollow beam under the influence of the previously mentioned bending moment and shear forces. Longitudinal strength calculations are predominantly used for midship section synthesis and the overall ship structural integrity evaluation.

In simple beam bending theory used in basic ship structural analysis, the following assumptions are made:

1. Kinematic assumptions from elementary Euler-Bernoulli beam theory, which neglect the bending from shear effects. The kinematics describe the deformation of the beam without regard to the forces on the beam.

a. Plane sections remain plane before and after deformation, no shear or warping.

b. Plane sections normal to the line of centroids remain normal before and after deformation, no shear. These two assumptions mean that  $\gamma_{xy} = \gamma_{yx} = 0$ .

c. Strains are sufficiently small so that the cross sectional geometry does not change; no Poisson effects. This means that  $\varepsilon_y = \varepsilon_z = \gamma_{yz} = 0$ .

d. Beam slopes are small.

e. Beam cross section is prismatic. This is optional but is usually the case in ship structures.

2. Physics assumptions describe the material behavior.

a. The material obeys Hooke's law; force is linearly proportional to displacement.

b. The material is isotropic (has the same properties in every direction at one point) and homogeneous (material properties are the same at all points) in the y-z plane.

c. Stress field is one dimensional, the only significant stress is along the x-axis of the beam.

A sketch of the coordinate description and the positive bending moment convention is shown in Figure 8-24. The x-axis defines the centroid of the cross section provided the first moments of area are zero

$$\int_{A} y dy dz = \int_{A} z dy dz = 0.$$

For homogenous cross sections, the centroidal axis is the same as the *neutral* axis in bending, which is defined as the line or plane of zero strain. The differential equation for the elastic curve for a symmetrical beam is

$$EI_v w'' = M(x),$$

where w is the deflection, E the Young's modulus of elasticity of the material,  $I_y$  the second moment of area of the beam cross section around the y-axis through its centroid, and M(x) the bending moment.

In terms of the load per unit length f(x), the equation can be written as

$$EI_{y}w^{m}=f(x).$$

Solution of this equation by multiple integrations, requires four boundary conditions, and since the ship is a free-free beam, these are zero shear and moment at the two end points.

The longitudinal stress at station x is related to the bending moment by

$$\sigma_x = -\frac{M(x)}{I_r}z,$$

where z is the vertical distance from the neutral axis. From the above equation it is clear that the extreme stresses are found at the top or bottom of the beam where z takes on its numerically largest values. For a positive bending moment, the top of the beam is in compression and the bottom is in tension.

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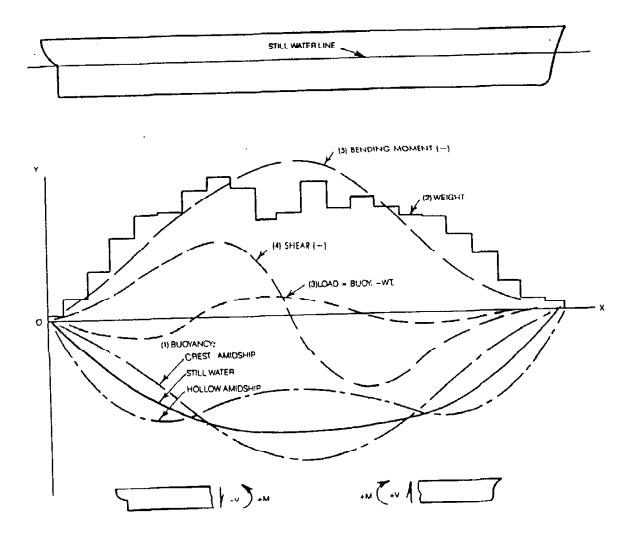


Figure 8-24. Coordinate description and sign convention.

One variation of the above beam equation is of importance in ship structures. It concerns beams composed of two or more material of different moduli of elasticity, for example, steel and aluminum, which may between the main hull and superstructure. In this case, the flexural rigidity  $EI_y$  is replaced by the integral  $\int_A E(z)z^2 dA$ , and the neutral axis is located at a height such that

$$\int_{A} E(z) z dA = 0.$$

From the previous stress equation it can be seen that there is a discontinuity in the stress distribution, whereas the strain,  $\varepsilon_x = \sigma_x / E$ , will be continuous where two different materials join.

## C. RDS 2010 ANALYSIS

A detailed structural analysis was performed on the RDS 2010, using the structural module contained in the ASSET program and is presented in the Feasibility Output Report, included as Appendix D. Detailed buoyancy, weight and load curves were produced using information from the ASSET output and are presented in Figure 8-25. The buoyancy curve was computed by converting the sectional area curve to a force per length curve by dividing the respective areas, at each station, by 35 tons/ft<sup>3</sup>. The weight distribution curve was developed by using the one digit weight groups and their respective LCG's from the ASSET output, and converting them into uniform loads centered about their LCG's. The load curve was developed by taking the difference between these two forces. As Figure 8-25 displays, there are two critical points, located at the ship's quarters, that must be analyzed more fully in the later portions of preliminary design. The sharp load changes at these points may be reduced when a more detailed weight distribution is known. Once this updated weight distribution is developed, and these points still present a

problem, the hull will have to be reinforced near the area of the critical points to compensate for the sharp changes in load.

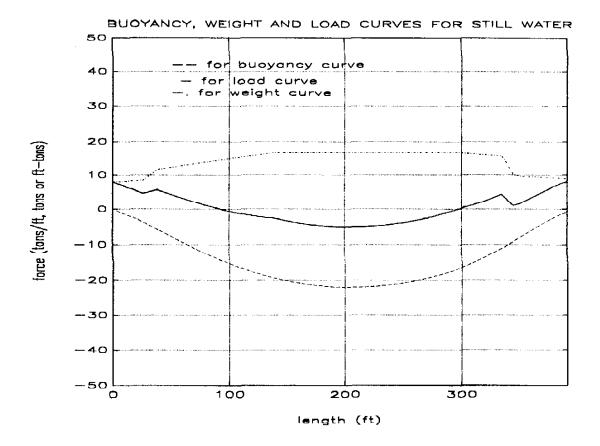


Figure 8-25. Still water force curves.

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Figures 8-26 and 8-27 display the buoyancy, weight and load curves for the hogging and sagging conditions respectively. The two buoyancy curves for the two quasi-static conditions of hogging and sagging were developed by constructing Bonjean curves for the hull form, and balancing the hull on a trichoidal wave of the correct length and height. Due to the tools available to complete this task, and the time available, the hull form was not exactly "balanced" on the wave. The difference between the areas under the buoyancy and weight curves for the two cases is on the order of five percent, at most. The difficult task was to achieve equilibrium by aligning the centroids of the areas beneath the respective curves. The inability to achieve this equilibrium caused the shear force and bending moment curves to yield erroneous results.

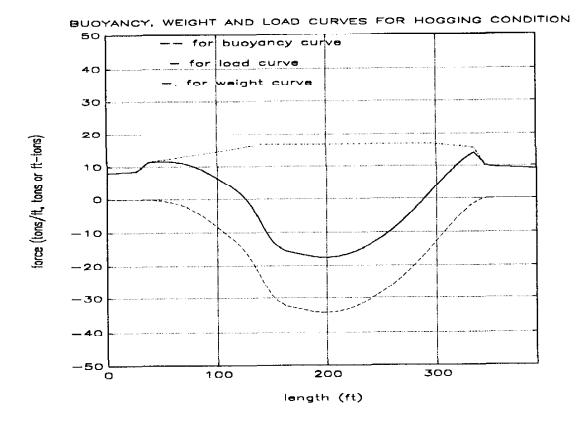
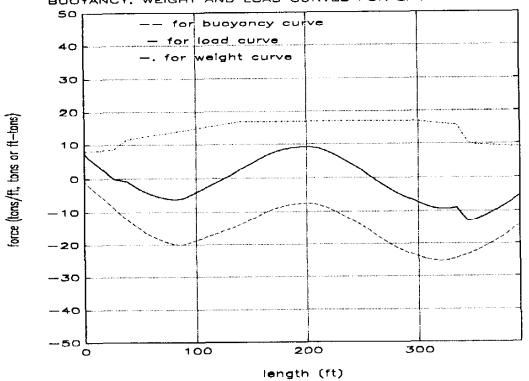


Figure 8-26. Hogging condition force curves.

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BUOYANCY. WEIGHT AND LOAD CURVES FOR SAGGING CONDITION

Figure 8-27. Sagging condition force curves.

As Figure 8-28 shows, the shear force and bending moment curves do not return to zero at the end of the ship. This error would be alleviated if the centroids of the respective areas could be aligned. Although the curves do not correctly represent the shear force and bending moment, the maximums of these are of the order needed for design purposes.

Using an early estimate for midship section design, the required design bending moment can be determined. The empirical formulas available to obtain this estimated moment are;

$$M = \frac{\Delta L}{C},$$

where C represents a constant depending on the ship type and bending condition (hogging or sagging);

$$BM_{H} = 0.000457(LBP)^{2.5}B$$

for the hogging condition;

$$BM_{\star} = 0.000381(LBP)^{2.5}B_{\star}$$

A typical value of C for a ship of this type is approximately 30, for both bending conditions.

Using these equations, the design bending moment is approximately 80,000 FT-LTON. As Figure 8-28 displays, the bending moment using the erroneous curve is approximately 200,000 FT-LTON in still water. If the same bending moment curve was plotted for the hogging and sagging conditions it would be shown that the maximum bending moment value is approximately 250,000 FT-LTON. Further refinement of the weight distribution curve would bring these results closer to the estimated bending moment.

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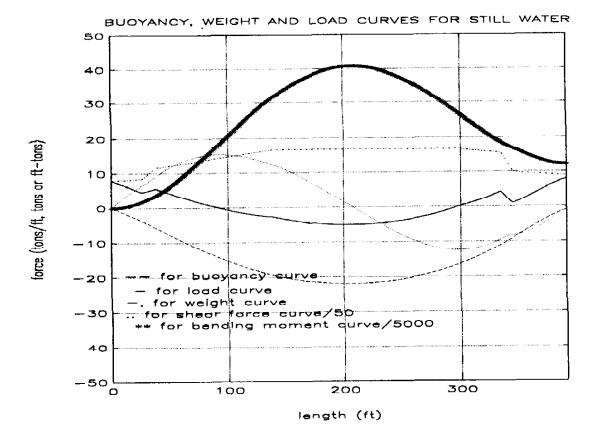


Figure 8-28. Still water force and bending moment curves.

## D. MIDSHIP SECTION DESIGN

The midship section was designed, through thousands of iterations using the ASSET Hull Structures Module, and is shown in Figure 8-29. Information concerning the size and placement of scantlings and stiffeners can be found in the ASSET Feasibility Output Report, Appendix D.

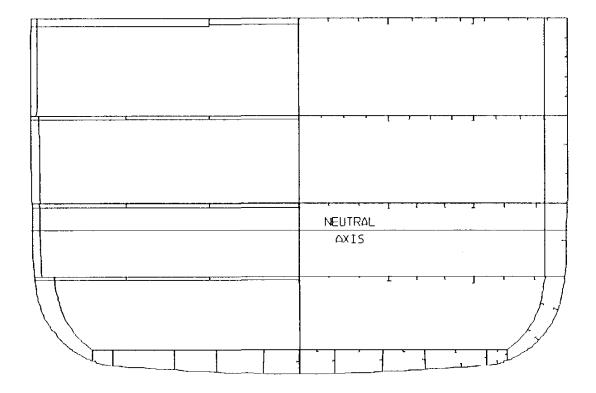


Figure 8-29. RDS 2010 Midship section design..

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#### **IX. DESIGN EVALUATION**

Once the feasibility studies and preliminary design phase have been completed, the design team must step back and perform an evaluation of design efforts to date. The design is assessed in a number of ways, based on top level design specifications and mission requirements:

- 1) The ship meets stated performance goals, including
  - (a) speed, endurance, and other performance based attributes; and
  - (b) systems installed to perform designated missions.
- 2) The ship meets given cost and 'political' goals.
- 3) The ship meets stated survivability goals.

The first two elements above are actually part of the iterative design process. Assuming that the design requirements and goals were clearly stated and then implemented, then the design process will constantly revisit whether the design matches the original set of requirements. For instance, using the ASSET program, one input is desired cruising speed. The ship design which ASSET produces is iterated until this performance goal is met. Other performance based attributes are similarly met during the ASSET iterative cycle.

During the combat system definition process, the threat scenarios were evaluated to ensure the combat system was adequate. This included not only the systems installed, but numbers of engagement elements and number of rounds required.

The cost goal was not met, but the faculty raised to cost ceiling based on our analysis and the desire not to give up critical capabilities of the ship. The "political" goals are more subjective, as equally hard to design to as they are, to evaluate the success of meeting them.

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The last item, meeting stated survivability goals still needs to be assessed in some manner, however. The total ship survivability assessment is divided into four phases:

- Cover and Deception the ability to remain undetected or prevent the enemy from obtaining a fire control solution accurate enough to launch a weapon
- Threat Destruction and Evasion the ability to intercept and destroy or divert threat weapons
- Damage Tolerant Design addresses the loss in mission capability due to weapons impact
- Damage Control and Repair addresses the ship's ability to recover mission capability lost due to the weapons hit

Note that the first two items are what is typically called the susceptibility, whereas the last two deal with the ship's vulnerability.

A low design priority was given to the cover and deception aspects for the most part. This is due to the ship's mission of operating close to shore. There was a conscious effort to reduce the ship's infrared and radar cross-sections, however. Oversized stacks were designed to reduce the gas turbine exhaust temperatures. Shaping of the ship's superstructure was done to reduce RCS. There is, however, no way for the design team to evaluate the effectiveness of these efforts.

The threat destruction and evasion capability is directly related to the types and numbers of defensive weapons placed on the ship. As shown in Chapter 4, threat scenario evaluations were completed in the AAW warfare area to ensure adequate numbers and types of AAW engagement elements. Similarly analysis still needs to be performed for the ASUW and ASW warfare areas.

The tolerance of the design to battle damage is addressed by the enclaving scheme and associated systems architectures. Similarly, the ability of the ship/crew to control and

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repair damage is directly related to the physical design attributes of the ship, including the survivability management system and automated damage control systems. Again, however, there is no firm method for the design team to assess the performance of these concepts.

The tools to evaluate the ship's systems readiness and survivability are:

- 1) readiness logic diagrams (RLDs);
- 2) system deactivation diagrams; and
- 3) physical arrangements of the ship.

The system deactivation diagrams are necessary and appropriate for detailed analysis for cause and effect of damage on specific elements and systems. However, the complexity of this approach precluded the design team from using this tool.

The design team did, however, develop a set of RLDs at the first level of detail for four mission areas (AAW, ASUW, ASW, and MOB). These were combined with the physical layout of the ship to perform a ship system survivability assessment at the enclave level of detail.

The RLDs were developed based on the required operational capabilities (ROCs) by mission/warfare category and the actual systems designed into the ship. Figures 9-1 through 9-4 show the RLDs for the AAW, ASUW, ASW, and MOB mission areas, respectively.

The "M" and "C" readiness rating levels apply to warfare and composite areas, respectively. Table 9-1 shows the relative definition of the mission readiness rating levels. The level indicates the readiness level rating due to a component or mission area

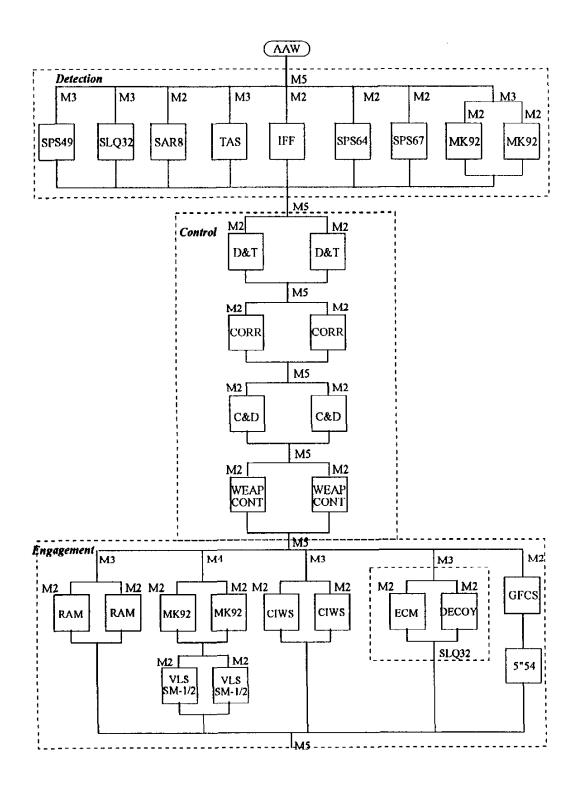


Figure 9-1. AAW Readiness Logic Diagram.

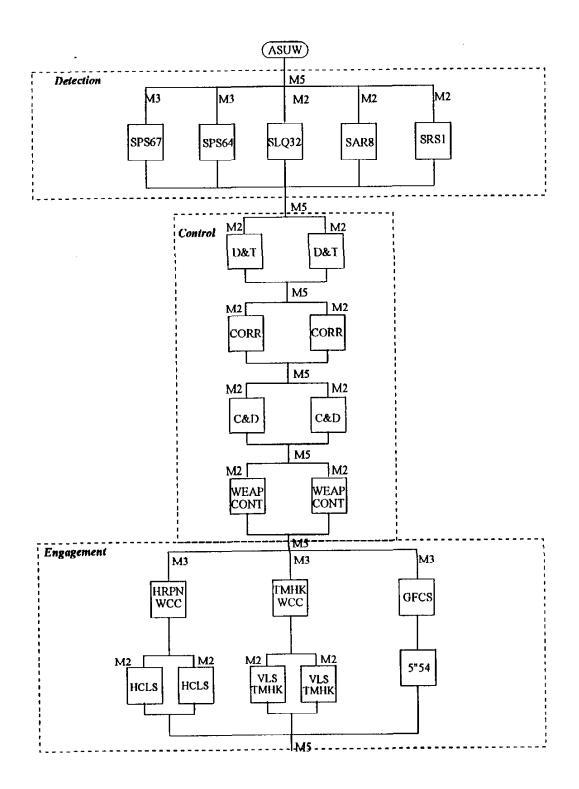


Figure 9-2. ASUW Readiness Logic Diagram.

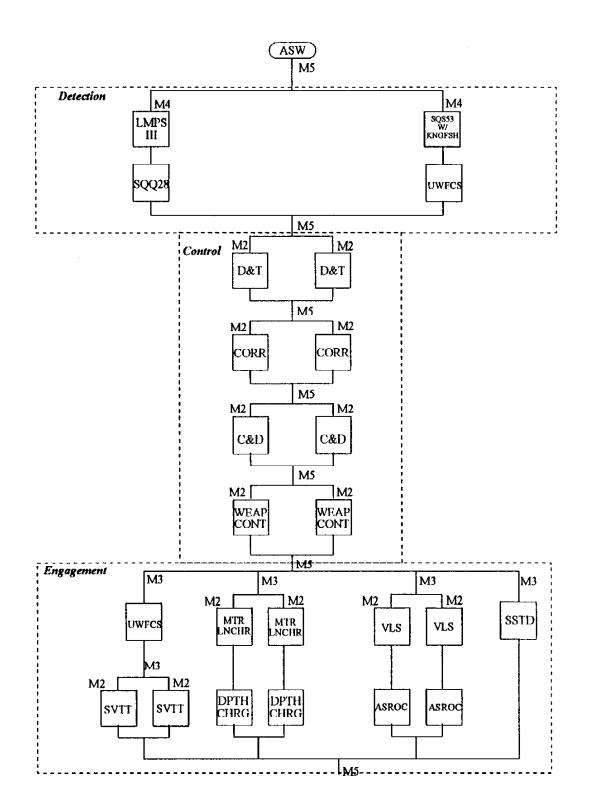
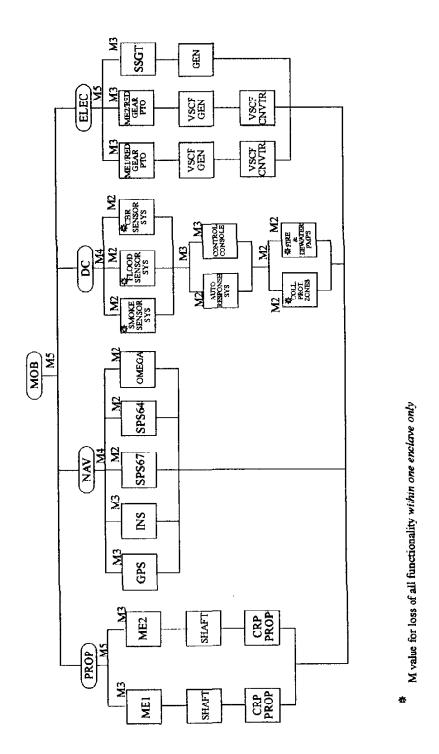


Figure 9-3. ASW Readiness Logic Diagram.

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loss. The lower level values are rolled-up to produce the higher level values, and finally the composite scores.

Rating Level	Capability
M1, C1	90-100%
M2, C2	70-89%
M3, C3	60-69%
M4, C4	1-59%
M5, C5	No Capability

**TABLE 9-1.** MISSION READINESS RATING LEVEL DEFINITIONS.

Using these RLDs in conjunction with a physical layout of the ship, an enclave level readiness assessment was completed. This assessment reveals the ship's readiness condition due to the loss of a single enclave. Loss of an enclave means the loss of all elements functionality contained with the enclave (i.e., if the No. 1 Mk-92 is within enclave 2, then loss of enclave 2 means loss of any capability associated with the No. 1 Mk-92). Loss of an enclave does not decimate all system pass through capability, however. The assumption is that due to the redundancy designed into systems such as electrical distribution, fiber optic ring bus, fire main water, high pressure air, etc., that at least partial pass through capacity remains short of catastrophic ship damage. Any damage which is so severe to destroy not only all elements within an enclave, but also destroy all systems which merely pass through the enclave would likely result in immediate ship loss.

Within each enclave, each mission area (AAW, ASUW, ASW, and MOB) was evaluated using the RLDs to see what each area's readiness assessment score ("M" rating) was upon loss of the systems within that enclave. The individual mission area ratings were

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then rolled-up into a composite score to reveal the ship's total readiness condition resulting from loss of the enclave.

Figure 9-5 illustrates these results. Note that the ship is fairly well balanced, with each enclave loss resulting with a ship's composite score of C3. The exception is loss of enclave 5. The C5 rating for enclave 5 is due to the assumption that both screws are lost if enclave 5 is lost, resulting in total loss of propulsion. Arguments may be made that from an operational sense, loss of all propulsion does not result in a zero capable ship. From a combat system vantage, loss of enclave 5 only degrades the ship to a C3 level. This argument cannot be resolved until their is reconciliation between the present method of reporting readiness and a more appropriate scoring method usable for real-time, from the scene ship's readiness assessment reporting.

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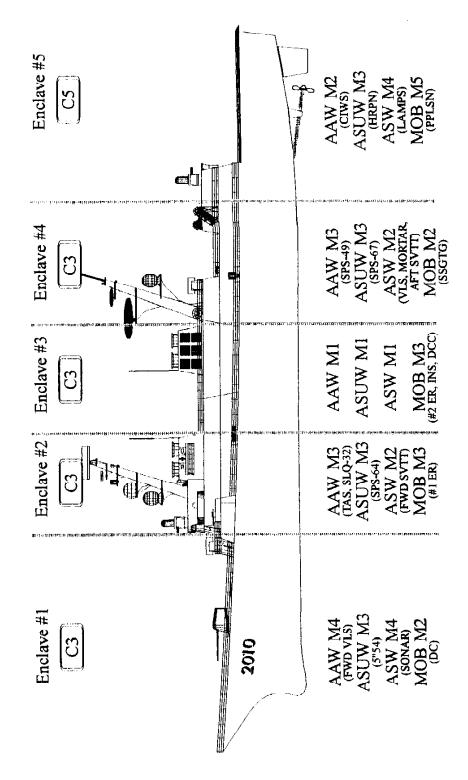


Figure 9-5. Enclave level survivability assessment.

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# Appendices

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## **DESIGN HISTORY**

- **28 SEP 92** TS4002/4003 course sequence introduction given by Professors Calvano and Francis B Fassnacht. The design team consists Charles N Alexander, LCDR Dean Cottle, LT Kent W. Kettell, of LCDR Dwight and LT Jeff Riedel. Received a CNO Tentative Requirement Statement, written in operational/political terms for a new class of surface ship, FPS 2010. As a review of requirements determination and setting, the first objective is to assist the CNO in developing a formal acquisition requirements statement with which he can task NAVSEA to design and procure the ships.
- 29 SEP 92 It was agreed upon by the design team that LT Kettell would be the design team coordinator.
- 07 OCT 92 The design team completed the "Requirements Document for Force Projection Ship (FPS) 2010". The requirements were written such that the ship would not be required to conduct ASW screening operations during Battle Group transit. Additionally, it was not considered necessary for the FPS 2010 to capable of long range AAW.
- 08 OCT 92 The Force Projection Ship 2010 is renamed Regional Deterrence Ship (RDS) 2010, and the "Requirements for Regional Deterrence Ship (RDS) 2010" is released by the CNO (faculty) with a few major changes other than the name:

1) The ship is not required to deploy promptly, fully ready for extended operations.

- 2) The time on station reduced from 60 days to 20 days.
- 3) The ship would be required to support short duration covert operations.
- 4) The combat system would incorporate an appropriate SSES.

5) The ship should support flight operations of non-assigned joint forces helicopters.

6) The ship will carry a surgeon and have operating room facilities.Additionally, it was clarified that approximately 10 of the RDS ships would be built.

Since to date there has been no clear recognition of specific threats for which the design team should be concerned when designing the combat system, it was agreed to that a list of most formidable threats would be generated prior to completing selection of the major ship elements.

- Design team completed the major threat evaluation. This was a 19 OCT 92 lengthy process in which the design team assumed the role of intelligence determined the air launched, surface launched and subexperts and surface weapons which were deemed to impose the greatest threat. The process was lengthy in spite of the fact that sufficient information does not exist in the open literature. The parameters which seemed worthy of comparison were radar cross-section, speed, range, warhead size, guidance type and the profile of the trajectory. In the air and launched surface missile categories the plan to determine the most formidable threats was as follows:
  - a) three with the smallest radar cross-section,
  - b) three with the fastest speed,
  - c) three with the longest range, and
  - d) three with the largest warhead.

In a few cases there was overlap, but generally this provided a worthy selection for later evaluation. The next step was to eliminate some of the threats based on simple comparison with others within the same category. At this point there remained only ten missiles which were significantly threatening in one way or another. This is shown in Table I. The torpedo threats were determined in a similar manner using speed and range. The mine size was determined based on the need to detect mines of this size in order to maneuver around them in sufficient

time in order to prevent either influence or contact. The mines smaller than this size were deemed to be less threatening based on the amount of explosive potential. To whittle the missile list down to a most fearsome four, the type of guidance package and the profile of the trajectory were considered. To account for advances in technology some of the characteristics of two weapons were merged to give a margin of safety. The missiles used therefore do not represent actual missiles, but ones very similar to actual ones. For security purposes the real

names are not used and the categories do not necessarily portray exact values, however they are realistic.

- 22 OCT 92 Element selection rough draft was completed. It is apparent that some elements which do not currently exist will be needed in order to build a ship which has been designed at the total ship level, looking at the entire combat system. The combat system needs to be designed at the mission level in order to achieve a completely integrated shipboard combat system. At this time many new combat system elements can not be readily integrated into the chipboard combat system, reducing the performance that was expected. It is expected that some current system elements may have to undergo major modification in order to make them compatible in a systems sense.
- 06 NOV 92 Revised element selection portion of the analysis and tradeoff study is complete to the point of having a definitive threat scenario. Optimally, threat scenarios as related to ship design could very well encompass a whole course.
- 10 NOV 92 Completed initial round of threat scenario with basic elements. With this completed, the element selection process can be finalized.
- **12 NOV 92** Decision matrices for threat evaluation finalized.
- 13 NOV 92 Specific element selection process complete, although there may be continued tradeoff analyses performed in future work in order to accommodate the price margin. Next step is to present this material in a meaningful way.
- 17 NOV 92 Rough final draft of the results of the specific element selection analysis and tradeoff study completed. Commenced the feasibility process using the ASSET program. The abbreviated documentation of this program is sketchy.....terminals not working well for present system configuration....
- 19 NOV 92 Rough draft of the threat scenarios completed.

- 20 NOV 92 Adjustments made to specific element selection in order to accommodate the four threat scenarios. No fleet guidance was available for determining the minimum required loadout of weapons. Since this deterrence ship will be operating alone, it should be capable of defending itself in the four threat scenarios discussed while either help is coming from other regions or it makes a retreat to a less threatening environment.
- 24 NOV 92 All aspects of specific element selection complete, including the paperwork.
  Received documentation for use of ASSET. Volume 1, the system manual provides good insight as to how the program should be used. Volume 2(A-E) must also be used in order to make decisions regarding how the envisioned ship will be constructed, outfitted, manned, and operated.
- **25 NOV 92** Completed revised draft of threat scenario.
- 04 DEC 92 Successfully completed an initialized feasible ship. The next step is to get the modules to converge individually so the synthesis portion of ASSET will be capable of running to convergence.
- 07 DEC 92 Convergence achieved on ASSET synthesis model. Although the ship does not have the all the same characteristics of the envisioned ship, the concept is predicable. The factors which affect a cost and stability will have to be optimized in order to determine if the ship is buildable at the requested price. In 2010 dollars, it seems that a small patrol boat may not even be economically feasible for \$350 million.
- 11 DEC 92 Final draft of threat scenario complete. Because of the details involved in the tedious calculations, this paper was made readable for those individuals not having received prior experience in threat probabilities as applied to scenarios such as these..
- 17 DEC 92 Commenced effort to reduce cost to \$350M.
- 06 JAN 93 Began drafting a detailed design philosophy which would provide a concrete basis for backing trade-off decisions

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- 07 JAN 93 Commenced work on the general combat system architecture.
- 15 JAN 93 Completed the formal design philosophy.
- 20 JAN 93 Reached point of diminishing returns on cost reductions to reach the stringent \$350M limit. Began draft of cost adjustment proposal. Stopped working with ASSET, and began working with AUTOCAD for the creation of a 3-D hull and superstructure.
- 21 JAN 93 Commenced enclaving effort in order to best locate systems and elements throughout the ship.
- 25 JAN 93 Decided to include the Integrated Readiness Assessment and Survivability Management Requirements as part of the Combat System Architecture.
- **08 FEB 93** Enclaving progressing such that topside layout must undergo several iterations before below decks enclaving can resume.
- 10 FEB 93 Commenced work on "Ship Descriptors".
- 16 FEB 93 Enclaving at the point where below decks arrangements can begin. Commenced drafting ROCs to be used in survivability assessment. In hindsight, the design team agreed that this portion should have been done much earlier had the usefulness of this type of document been understood.
- 18 FEB 93 Completed the General Combat System Architecture, including the one-line connectivity diagram, battle organization, and manning structure.
- 19 FEB 93 Commenced electrical system design.
- 01 MAR 93 ROCs finalized so that survivability assessment can proceed though RLDs.
- 04 MAR 93 Completed electrical system design.

- 05 MAR 93 Began making slides for design presentations.
- **08 MAR 93** Arrangements completed after several iterations, enclaving verified from keel to masts.
- 09 MAR 93 Completed survivability assessment. The ship is very well balanced.
- 12 MAR 93 Completed "Ship Descriptors" portion of design.
- 18 MAR 93 Formal presentation of ship design to Naval Postgraduate School.
- 23 MAR 93 Formal Washington, DC presentation of ship design to NAVSEA 05 at NC3, Crystal City.
- **'08 APR 93** Formal presentation of ship design to Monterey chapter of Surface Navy Association.
- 21 APR 93 Completed master compilation of all design project reports into one report.

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Wortler Area         680         AGT         AGT         AGT         MAD         FW         MAY         EW         MAY         MAY         LAND STRK           Strip revisions         500-00         Magnet         500-00         Magnet         500-00         May						Fayload Selection Matrix	Itrix			RDS-2010
Genue         Weapone/Cummer         Senser         Kenpone/Cummer	Warfare Area	MSM		ASUW		AAW		EW	NAV	LAND STRK
Mercanase         S05-33 (L3)         Mat-30 Torp         STS-64 (pn)         SM-1/2         LBPA         SM-1/2 (R1M-66/67)         SLA-32 (Y3)         STS-64 (pn)           LAMTS         CSATADEADC         STS-44         IN-40 Torp         STS-44 (pn)	dp Option	Sensor	Weapons/Cntrmsr	Sensor	Weapons	Sensor	Weapons/Cntrmsr			
Indicator         STS-45         WA	Options Considered	- 392.20	Mk-50 Torp	SPS-67(pri)	SM-1/2	LBPA	SM-1/2 (RIM-66/67)	SLQ-32 (V3)	SPS-64 (pri)	TOMAHAWK BIK III
LAMPS     CAMANLADC     7-54     FNS-46     FNAM<(RM-116)     Funne       UV     RBU0600Filedgenge     25mm Chain Gun     PSAM<(RM-7)		Kingfisher adjunct	GLLSS	SPS-64 (bu)	HARPOON	SPS-48	w/ SPG-XX illuminator		[LN-66 (bu)	SWG-3(V)ATWCS
UVV     RBU 6000/ridgetes     Zamm Chain Ch		LAMPS	CSANAE/ADC		5"-54	SPS-49	RAM (RIM-116)		Furno	
Animatical consistent     Phalaex       Option 1     SSS-33 (LB)     Mk-30 Tarp     Total consistent     Kik-38 Decoy Lacter     SRS-44 (pu)       Option 1     SSS-33 (LB)     Mk-30 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp       Option 1     SSS-33 (LB)     Mk-30 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp       Advise work100     SST0     SST0     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     Mk-20 Tarp     SSS-44 (bu)       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     Mk-30 Tarp     TarcAN       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     Mk-30 Tarp     TarcAN       Advise work100     SSC-31 (LB)     Mk-20 Tarp     SSS-44 (bu)     TarcAN       Advise work100     SSC-31 (LB)     Mk-30 Tarp     TarcAN       Advise work100     SSC-31 (LB)     Mk-30 Tarp     TarcAN       Advise work100     SSC-31 (LB)     Mk-30		<b>VUV</b>	RBU 6000/Hedgehog		25mm Chain Gun	IFF	NSSM (RIM-7)		TACAN	
Optimi 1     SSS-31 (LB)     Mk-30 Top     DTO 76mm Gun     Goalteerer       Nove Marcel     Nev-90 Top     Nev-90 Top     Nev-90 Top     SSS-44 (pr)       Optimi 1     with Kingfalser     SSTD     Nev-90 Top     SSS-44 (pr)       Mk-30 Top     SSS-41 (pr)     NH-12     SN-44 (pr)     SN-44 (pr)       Mit Kingfalser     SSTD     NN-20 Top     SSS-44 (pr)     NH-12       Mit Kingfalser     SSTD     NN-20 Top     SN-44 (pr)     NH-12       Mit Kingfalser     SSTD     Nev Moture System     SSS-44 (pr)     NH-12       Mit Kingfalser     SSTD     Nev Moture System     SSS-44 (pr)     NH-12       Mit Kingfalser     SSTD     Nev Moture System     SSS-44 (pr)     NH-38       Optimi 2     SOS-33 (LB)     Mk-30 Top     SSS-44 (pr)     NH-38       Optimi 2     SOS-33 (LB)     Mk-30 Top     SSS-44 (pr)     NH-38       Mit Kingfalser     SSTD     NH-38     SM-12 (HM 66677)     SLQ-32 (Y3)     SSS-44 (pr)       Mit Kingfalser     SSTD     NH-38     NH-38     SLQ-32 (Y3)     SSG-44 (pr)       Mit Kingfalser     SSTD     NH-38     NH-38     NH-38     NH-36       Mit Kingfalser     SSTD     SSG-34 (pr)     SN-12     NH-38     NH-36					7.62mm Mini Gun		Phalanx			
Option 1     SQS-33 (LB)     Mk-30 Torp     SPS-64 (bi)     Mk-38 Decoy Ledtr       Option 1     SQS-33 (LB)     Mk-40 Torp     SPS-64 (bi)     HA/ROOK       Option 1     SQS-33 (LB)     Mk-40 Torp     SPS-64 (bi)     HA/ROOK       Mk Kingfieler     SSTD     SSTD     SPS-64 (bi)     HA/ROOK       Mind Kingfieler     SSTD     SSTD     SPS-64 (bi)     HA/ROOK       Option 2     Ku Kingfieler     SSTD     SKK-32 (JB)     HA/ROOK       Mind Gun     SSTD     Mk-30 Torp     SPS-64 (bi)     HA/ROOK       Mind Kingfieler     SSTD     Mk-30 Torp     SPS-64 (bi)     HA/ROOK       Mind Kingfieler     SSTD     Mk-30 Torp     SPS-64 (bi)     HA/ROOK       Mind Kingfieler     SSTD     SPS-64 (bi)     HA/ROOK     SPS-64 (bi)       Mind Kingfieler     SSTD     SPS-64 (bi)     HA/ROOK     SPS-64 (bi					OTO 76mm Gun		Goalkeeper			
Option 1     S05-33 (LB)     Mu-90 Torp     SFS-64 (pri)     SM-1/2     LAD     ExBOC       Option 1     S05-33 (LB)     Mu-90 Torp     SFS-64 (pri)     SM-1/2     ExBOC     LAD       Option 1     S05-33 (LB)     Mu-90 Torp     SFS-64 (pri)     SM-1/2     SFS-64 (pri)     LAD       Virk Kingfrater     SSTD     SSTD     SN-1/2     SFS-64 (pri)     LAD     SLQ-23 (Y3)     SFS-64 (pri)       Virk Kingfrater     SSTD     New Mortar System     F*St     RAM     RAM     LAD     LAO       John 2     Virk Kingfrater     SSTD     New Mortar System     F*St     RAM     LAO     LAO       John 2     Set 2     Mu-30 Torp     SFS-64 (pri)     MK-38     SLQ-32 (Y3)     SFS-64 (pri)       John 2     Set 2     Mu-30 Torp     SFS-64 (pri)     MK-38     SLQ-32 (Y3)     SFS-64 (pri)       John 2     Set 2     Mu-30 Torp     SFS-64 (pri)     MK-38     SLQ-32 (Y3)     SFS-64 (pri)       Virk Kingfrater     SSTD     Mu-30 Torp     SFS-99     Mu-30 Torp     Job 200 Lorp     Job 200 Lorp       Virk Kingfrater     SSTD     SFS-90     Mu-30 Torp     SFS-90     Mu-30 Torp     Job 200 Lorp       Virk Kingfrater     SSTD     SFS-90     Mu-1/2							Mk-38 Decoy Luchr			
Option 1     Sec.33 (LB)     MeraPatakots     ELAD     ELAD       Option 1     sec.33 (LB)     MeraD Torp     SFS-67(pri)     SFS-45 (bu)     SFS-46 (pri)       MitRis wCUUY     New Module System     SFTD     SFS-46 (bu)     MK-23     SFS-46 (pri)       MitRis wCUUY     New Module System     SFS-67 (pri)     SFS-46 (bu)     MK-33     SFS-46 (pri)       MitRis wCUUY     New Module System     SFS-67 (pri)     SFS-46 (bu)     MK-33     SFS-46 (pri)       MitRis wCUUY     New Module System     T-62mm Misia Gun     MK-33     Decoy Ladia     I/V-66 (pri)       MitRis wCUUY     New Module System     T-62mm Misia Gun     MK-33     Decoy Ladia     I/V-66 (pri)       MitRis wCUU     SST3 (LB)     MK-30 Torp     SFS-67 (pri)     SM-12     SFS-66 (pri)     I/V-66 (pri)       MitRis wCUU     SST3 (LB)     MK-30 Torp     SFS-67 (pri)     SFS-67 (pri)     SFS-66 (pri)     I/V-66 (pri)       MitRis wCUU     SST3 (LB)     MK-30 Torp     SFS-67 (pri)     SFS-66 (pri)     I/V-66 (pri)       MitRis wCUU     SST3 (LB)     MK-30 Torp     SFS-67 (pri)     SFS-66 (pri)     I/V-66 (pri)       MitRis wCUU     SST3 (LB)     MK-30 Torp     SFS-66 (pri)     I/V-66 (pri)     I/V-66 (pri)       MitRis wCUU     SST3 (LB							SRBOC			
Option 1         SIGE-33 (LB)         M30 Torp         BIV-IACKOP         BIV-IACKOP         SIN-1.2         RIM-66677         SLQ-32 (V3)         SPS-64 (pri)           With Kingficher         SSTD         SSTD         SST-30 (LB)         M30 Torp         SIN-1.2 (RIM-66677)         SLQ-32 (V3)         SPS-64 (pri)           With Kingficher         SSTD         SSTD         SST-30 (LB)         MA30 Torp         MC-32 (M-3)         SPS-64 (pri)           AVITE with Ling Control         New Monter System         SY-34         WK-33 (M-30 (Pri)         MC-30 (Pri)         MC-30 (Pri)           AVITE with Ling Control         New Monter System         Track         MC-33 (Boord Lacter         MC-33 (Boord Lacter         MC-30 (Pri)           AVITE With Ling Control         MC-30 (Pri)         MC-33 (Boord Lacter         MC-33 (Pri)         MC-30 (Pri)           AVITE MALL         Struct Resolution         MC-33 (Boord Lacter         MC-33 (Pri)         MC-30 (Pri)         MC-30 (Pri)           AVITE Resolution         Struct Resolution         MC-33 (Pri)         MC-33 (Pri)         MC-30 (Pri)         MC-30 (Pri)           AVITE Resolution         Struct Resolution         MC-33 (Pri)         MC-33 (Pri)         MC-30 (Pri)         MC-30 (Pri)           AVITE Resolution         Struct Resolution				PRI=PRIMARY			LAD			
Option 1     SQS-53 (LB)     MK-50 Torp     SPS-67(rm)     SM-1/2     SPS-46 (67)     SLQ-32 (Y3)     SPS-46 (67)       with Kingfelder     SSTD     SSTD     SPS-64 (bu)     HARDOON     WK 922     W SPG-2X (11)unimator     LN-66 (bu)       with Kingfelder     SSTD     SPS-64 (bu)     HARDOON     WK 922     W SPG-2X (11)unimator     LN-66 (bu)       LANIPS w: 011     New Mortar System     SPS-64 (bu)     HARDOON     WK 922     W SPG-2X (11)unimator     LN-66 (bu)       LANIPS w: 011     New Mortar System     25mm Chair Gun     Phalaux     FAAM     TACAN       Option 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     TACAN       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     TACAN       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     TACAN       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     TACAN       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     TACAN       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     FAAM       Vision 2     S0S-33 (LB)     Mk-50 Torp     SPS-64 (bu)     FAAM     FAAM       Vision 3     SS-34				BU-BACKUP			Torch			
with Kingfisher     STD     SPS-64 (bu)     HARPOON     MK #2,2     w SPG-XX illuminator     LN-66 (bu)       JAMRS w(JU) <sup>1</sup> New Mortar System     27mm Chain Gun     FF     RAM     TACAN       JAMRS w(JU) <sup>1</sup> New Mortar System     27mm Chain Gun     Phalaux     TACAN       JAMRS w(JU) <sup>1</sup> New Mortar System     25mm Chain Gun     Mc-38 Decoy Lach     TACAN       JAMRS w(JU) <sup>1</sup> New Mortar System     265mm Min Gun     Nc-38 Decoy Lach     TACAN       Option 2     SQS-33 (LB)     Mk-39 Torp     SN-12     SN-12     SN-12       Vith Kingfisher     STT     STD     SN-12     SN-12     SN-12       Vith Kingfisher     STT     STG-31 (LB)     Mk-39 Torp     SN-12     SN-12       Vith Kingfisher     STT     StG-67 (bu)     HARPOON     StG-32 (CB)     SLQ-32 (CB)       Lakites     STT     StG-64 (bu)     HARPOON     StG-32 (CB)     SLQ-32 (CB)       Vith Kingfisher     STT     StG-64 (bu)     HARPOON     StG-32 (CB)     SLQ-32 (CB)       Lakites     STT     RS-44     W STG-32 (CB)     SLQ-32 (CB)     StG-94 (pr)       Lakites     STT     RS-44     W STG-32 (CB)     StG-32 (CB)     StG-32 (CB)       Lakites     StG-94 (bu)     HARDON	Option 1	SQS-53 (LB)	Mk-50 Torp		SM-1/2		SM-1/2 (RIM-66/67)	SLQ-32 (V3)	SPS-64 (pri)	TOMAHAWK BIK
IAMR® wCULU     New Mortar System     5*54     IFF     RAM     Tarman       23mm Chair Gun     Philanx     Philanx     Philanx     Tarva (un)       23mm Chair Gun     7.62mm Miai Gun     SRBOC     LAD     Tarva (un)       23mm Chair Gun     SRBOC     LAD     Philanx     Tarva (un)       7.62mm Miai Gun     SRBOC     LAD     Philanx     Tarva (un)       7.62mm Miai Gun     SRBOC     LAD     Philanx     Tarva (un)       7.62mm Miai Gun     SRBOC     LAD     Philanx     Tarva (un)       1     Torch     Torch     SRBOC     LAD     Tarva (un)       1     View Mortar System     SPS-64 (nu)     HARPOON     SPS-64 (nu)     Philanx       1     New Mortar System     STBOCN     SPS-64 (nu)     Philanx     TACAN       1     New Mortar System     25mm Chair Gun     Philanx     TACAN       1     New Mortar System     7.62mm Miai Gun     Mc-38 Beery Lacht     TACAN       1     SRBOC     LAD     Philanx     TACAN       1     New Mortar System     TAC     SRBOC     LAD		with Kingfisher	SSTD	SPS-64 (bu)			w/ SPG-YX illuminator		IN SCA.	POULTA COL DUID
Option 2     SCS-33 (LB)     Mc-30 Torp     SPS-67 (pri)     Mc-30 Torp     SPS-67 (pri)       Virth Kingficher     SSTD     SNL12     SPS-66 (pri)     SLQ-32 (V3)     SLQ-32 (V3)       Virth Kingficher     SSTD     SPS-67 (pri)     SM-12     SLQ-32 (V3)     SPS-66 (pri)       Virth Kingficher     SSTD     SPS-64 (pri)     Mc-30 Torp     SPS-64 (pri)     SPS-66 (pri)       Virth Kingficher     SSTD     SPS-64 (pri)     SPS-64 (pri)     SPS-66 (pri)     SPS-66 (pri)       Virth Kingficher     SSTD     SPS-64 (pri)     Mc-30 Torp     SPS-64 (pri)     SPS-66 (pri)       Virth Kingficher     SSTD     SPS-64 (pri)     SPS-66 (pri)     SPS-66 (pri)     SPS-66 (pri)       LAMTB     Now Mortur System     SPS-64 (pri)     Mc-30 Torp     SPS-66 (pri)     SPS-66 (pri)       LAMTB     Now Mortur System     SPS-64 (pri)     Mc-30 Torp     SPS-66 (pri)     SPS-66 (pri)       LAMTB     Now Mortur System     Mc-30 Torp     SPS-66 (pri)     Mc-30 Torp     SPS-66 (pri)       LAMTB     Now Mortur System     Mc-30 Torp     SPS-66 (pri)     Mc-30 Torp     SPS-66 (pri)       LAMTB     Now Mortur System     Mc-30 Torp     SPS-66 (pri)     Mc-30 Torp     Mc-30 Torp       LAMTB     Now Mortur System     Mc-30 Tor		LAMPSWORV				8	RAM		TACAN	COM IN (A) COMO
Option 2     SCS-53 (LB)     Mk-30 Torp     SFS-65 (pri)     Mk-38 Decoy Ladin     Mk-38 Decoy Ladin       Vith Kingfalder     SCS-53 (LB)     Mk-30 Torp     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)       Vith Kingfalder     SCS-53 (LB)     Mk-30 Torp     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)       Vith Kingfalder     SSTD     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)       Vith Kingfalder     SSTD     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)       Vith Kingfalder     SSTD     SFS-67 (pri)     SFS-67 (pri)     SFS-67 (pri)     SFS-64 (pri)       Vith Kingfalder     SSTD     SFS-64 (pri)     MK-12     SFS-64 (pri)     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)       New Mortar System     SFS-64 (pri)     MK-38 Decoy Lindin     SFS-64 (pri)       New Mortar System     SFS-64 (pri)							Phalanx			
Clotical     SRBOC     IAD       Contract     SS2-33 (LB)     Mk-30 Torp     SPS-67 (pri)       With Kingflaher     SSTD     SPS-49     SM-1/2 (RIM-6667)       With Kingflaher     SSTD     SPS-46 (bu)       LMFB     New Mortar System     SPS-46 (bu)       LMFB     New Mortar System     SPS-49       LMFB     New Mortar System     SPS-64 (bu)       LMFB     SSTD     SPS-64 (pu)       LMFB     SPS-64 (pu)     SPS-64 (pu)<					7.62mm Mini Gun		Mk-38 Decoy Lucht			
Option 2     SQS-53 (LB)     Mk-30 Toop     SNk-1/2     SNk-1/2 (RIM 66/67)     SNk-1/2 (RIM 66/67)       With Kingfidater     SSTD     SNk-1/2     SSR-49     SMk-1/2 (RIM 66/67)     SNk-67 (pri)       Mk-30 Toop     SNS-54 (bu)     FLARPOON     SPS-64 (pri)     SN-1/2     SPS-64 (pri)       Mith Kingfidater     SSTD     SNS-54 (bu)     FLARPOON     SPS-64 (pri)     SN-1/2 (RIM 66/67)     SLQ-32 (Y3)       New Mortar System     STD     SPS-64 (bu)     FLARPOON     SPS-64 (pri)     Mk-38 Decoy Lodin     TACAN       LAMP     New Mortar System     255mm Chain Gun     RAM     TACAN     TACAN       SRDOC     SRDOC     SRDOC     SRDOC     SRDOC     SRDOC							SRBOC			
SQS-33 (LB)     Mk-50 Torp     SPS-67(pri)     SM-1/2     SPS-64 (pri)       SQS-33 (LB)     Mk-50 Torp     SPS-67(pri)     SM-1/2     SPS-64 (pri)       With Kingfider     SSTD     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     New Mortur System     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     New Mortur System     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     New Mortur System     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     SSTD     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     SSTD     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     SSTD     SPS-64 (bu)     HARPOON     SPS-64 (pri)       LAVPS     New Mortur System     SPS-64 (pri)     SPG-64 (pri)       LAVPS     New Mortur System     SPS-64 (pri)     SPG-64 (pri)       LAVPS     New Mortur System     SPG-64 (pri)     SPG-64 (pri)       LAVPS     New Mortur System     SPG-64 (pri)     SPG-64 (pri)       LAVPS     New Mortur System     SPG-64 (pri)     TACAN       TACAN     SPG-64 (pri)     SPG-64 (pri)     TACAN       SPG-64 (pri)     SPG-64 (pri)     SPG-64 (pri)     TACAN		-					LAD			
SQS-53 (LB)     Mk-50 Torp     SPS-67(pri)     SM-1/2     SPS-66(57)     SLQ-32 (V3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-67(pri)     SM-1/2     SPS-66(57)     SLQ-32 (V3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-67(pri)     SM-1/2     SPS-67 (pri)     SPS-64 (pri)     SPS-64 (pri)       With Kingfisher     SSTD     SPS-64 (pri)     RA-800N     SPS-64 (pri)     W/SPG-XX illuminator     LN-66 (pri)       LAMPS     New Mortar System     257 mm Chain     Mri     RA-M     TACAN     TACAN       LAMPS     New Mortar System     257 mm Chain Gun     Mri-38 Decoy Lnchr     TACAN     RA-38 Decoy Lnchr       7.62mm Mini Gun     SRB0C     SRB0C     SRB0C     SRB0C     SRB0C							Torch			
SQS-53 (LB)     Mk-50 Torp     SPS-67(pri)     SM-1/2     SPS-66(7)     SLQ-32 (Y3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (bu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     SLQ-32 (Y3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (bu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     SLQ-32 (Y3)     SPS-64 (pri)       With Kingfisher     SSTD     SPS-64 (bu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     SLQ-32 (Y3)     SPS-64 (pri)       Now Mortar System     SPS-64 (bu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     SLQ-32 (Y3)     SPS-64 (pri)       LAME     SPS-64 (bu)     HARPOON     SPS-64 (bu)     W/SPG-XX illuminator     L/M-66 (Pu)     L/M-66 (Pu)       LAME     New Mortar System     27.000     SPS-64 (bu)     M/M-38 Decoy Lnchr     TACAN       7.62mm Mini Gun     SRBOC     SRBOC     SRBOC     SRBOC     SRBOC										
SQS-53 (LB)     Mk-50 Torp     SPS-67(pri)     SM-1/2     SPS-49     SM-1/2 (RIM-66/67)     S1Q-32 (V3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (pu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     S1Q-32 (V3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (pu)     HARPOON     SPS-49     SM-1/2 (RIM-66/67)     S1Q-32 (V3)     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (pu)     HARPOON     SPS-64 (pu)     HARPOON     SPS-64 (pu)       I.Meisting     SSTD     SPS-64 (pu)     HARPOON     SPS-64 (pu)     HARPOON     SPS-64 (pu)       I.Meisting     SSTD     SPS-64 (pu)     HARPOON     SPS-64 (pu)     HARPOON     SPS-64 (pu)       I.AMEI     New Mortar System     SPS-64 (pu)     HARPOON     SPS-64 (pu)     HARPOON     TACAN       I.AMEI     New Mortar System     25mm Chain Gun     HFF     RAM     HA-38 Decoy Linder     TACAN       7.62mm Mini Gun     SRBOC     SRBOC     SRBOC     SRBOC     LAD     LAD     LAD										
SQS-33 (LB)     Mk-30 Torp     SPS-67(pri)     SM-1/2     SPS-84     SM-1/2     SPS-64 (pri)       with Kingfisher     SSTD     SPS-64 (bu)     HARPOON     SPS-84     w/ SPG-XX illuminator     LN-66 (bu)       LÅMP3     New Mortar System     SPS-64 (bu)     HARPOON     SPS-84     w/ SPG-XX illuminator     LN-66 (bu)       LÅMP3     New Mortar System     2762 Timm Osim     IFF     RAM     TACAN       LÅMP3     New Mortar System     25mm Chain Gun     Phalanx     RAM     TACAN       1.62.Timm Osim     New Mortar System     25mm Mini Gun     SRBOC     LA     LA-66 (bu)										
dialect     SSTD     SPS-64 (bu)     HARPOON     SP3-48     w/ SPG-XX illuminator     LN-66 (bu)       New Mortar System     210 / hune Out     IFF     RAM     TACAN       7:62mm Mini Gun     Mk-38 Decoy Lndrt     SRBOC     SRBOC       1.4D     1.4D     LAD	Option 2	SQS-53 (LB)	Mk-50 Torp	SPS-67(pri)	Z/1-WS		SM-1/2 (RIM-66/67)	SLQ-32 (V3)	SPS-64 (pri)	TOMAHAWK BIk I
New Morter System 010 Parent Own IFF RAM 25mm Chain Gun Phalamx 7.62mm Mini Gun Mk-38 Decoy Lnchr SRBOC 1.AD		with Kingfisher	arsa	Ĵ		SP3-48	w/ SPG-XX illuminator		[ N-66 (hu)	SWG-3VV) ATWCS
25mm Chain Gun Phalanx 7.62mm Mini Gun Mk-38 Decoy Lnchr SRBOC 1.AD		LANFS	New Morter System		Que		RAM		TACAN	
							Merilan.			
							rnalanx			
StBOC					7.62mm Mini Gun		Mk-38 Decoy Luchr			
							SRBOC			
							LAD			

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RDS-2010	FCS	MK-23 (TAS)	MK-92	SPG-XX Illuminator											Self Developed	SPG-XX Illuminator									Self Developed	SPG-XX Illuminator						
-	COUNTER- MEASURES	Mk-38 Decoy MI	Lnchr Mi	SRBOC SP	LAD	Torch	SSTD	CSANAE/ADC	SLQ-32 (V3)					 1	Mk-38 Decoy Sel	Lnchr SP	SRBOC	LAD	Torch	SSTD	SLQ-32 (V3)	-			Mk-38 Decoy Sel	Lnchr SP	SRBOC	LAD	Torch	SSTD	SLQ-32 (V3)	
	DETECTION SENSORS	SAR-8	WLR-9		KAS-1 (CWDD)			NUN	LBPA	SPS-48/-49	Furmo	LN-66	Ľ	oro-04/-0 /	SAR-8	Mk 23 (TAS)	_	_			SPS-64/-67	LN&S	SPS-48Ark-92	IFF	SAR-8	Mfk 23 (TAS)		SQS-53 (LB)			Punne	SPS-KW-49
-	WEAPONS	Phalanx SAR-8	Goalkeeper WLR-9	Mk-50 Torp Mk 23 (TAS)	25mm Chain Gun KAS-1 (CWDD)	7.62mm Mini Gun SQS-53 (LB)	76 mm Oto Melara LAMPS III	RBU 6000/Hedgehog UUV	TOMAHAWK Blk III LBPA	SWG-3(V) ATWCS SPS-48/-49					Phalanx SAR-8	Mk-50 Torp Mk 23 (TAS)	25mm Chain Gun KAS-1 (CWDD)	7.62mm Mini Gun SQS-53 (LB)	New Mortar System LAMPS III		TOMAHAWK BIK III SPS-64/-67	SWG-3(V) ATWCS LN66		1	Phalanx SAR-8	Mk-50 Top Mk 23 (TAS)	25mm Chain Gun KAS-1 (CWDD)	7.62mm Mini Gun SQS-53 (LB)	76 mm Oto Méana LAMPS III	New Mortar System SPS-64-67	TOMAHAWK Blk III Runne	SWG-3(V) ATWCS SPS-48-49
Payload Selection Matrix	WE	Z/1-WS	RAM	MSSM	HARPOON	5"-54									SM-1/2	RAM	HARPOON	3"-54							2/1-WS	RAM	HARPOON					
Payload S	COMMAND & DECISION	ACDS (Self-developed)	SYS-1 (Modified)												ACDS (Self-developed)	SYS-1 (Modified)									ACDS (Self-developed)	SYS-1 (Modified)						
-	COMMUNICATIONS	SATCOM	SUITS	JOTS	COPERNICUS	LINK 11	SQTN								SATCOM	SUITS	OTS	COPERNICUS	LINK 11		SQTN				SATCOM	SOLLS	STOL	COPERNICUS	LINK 11	SQTN		
	COMM	U/W Telephone	HF	UHF	VHF	SESS	TACAN								U/W Telephone	HF	UHF	VHF	SESS		TACAN				U/W Telephone	HF	UHF	VHF	SESS	TACAN		
TS4002	Equipment Cat.	100.1	Options Considered												Option 1		B-								Option 2							

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Primary Air Search Sensor Matrix

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	LBPA	Relative	1.00	0.67	1.00	0.67	0.44	0.32	0.35	0.07	1.72
		Parameter	40	10	65	200	100,000	10,000	40,000	75	
ir Search		Relative	0.73	0.80	0.46	1.00	0.90	1.00	1.00	1.00	3.99
Primary Air Search	SPS49	Parameter	29	12	30	300	49,248	3,165	14,004	5	
	48	Relative	96.0	1.00	1.00	0.77	1.00	0.56	0.58	0.42	2.93
	SPS-48	Parameter	39	15	65	230	44,232	5,684	24,018	13	
		Weighting	0.20	0.50							:
		Category	Gain (Db)	Scan Rate (RPM)	Elevation (degrees)	Range (Nm)	Size (in^2)	Weight (abovedeck)	(belowdeck)	Cost ( \$ millions)	Summary

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Secondary Air Search Sensor Matrix

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		Relative	1.00	0.3				0.2		0.13	1.64
	Ē	Parameter	40	10	65	200	100,000	10,000	40,000	75	
Ð											
Air Sea		Relative	0.53			0.22			1.00	1.00	4.35
Secondary Air Search	1W	Parameter	21	30	75	50	29,799	1,950	10,000	10	
Š											
-	SF SdS	Relative	0.96			1.00	0.67	0.34	0.42	0.77	2.76
	SdS	Parameter	39	15	65	230	44,232	5,684	24,018	13	
		Weighting	0.20					1.00			
		Category	Gain (Db)	Scan Rate (RPM)	Elevation (degrees)	Range (Nm)	Size (in^2)	Weight (abovedeck)	(belowdeck)	Cost (\$ millions)	Summary
							(	C-2	2		

RDS-2010

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Navigation Radar Matrix

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		Relative	1.00	0.73	1.00	0.29	0.69	1.00	1.00	1.00	1.00	4.67
		Data	30.0	24.0	25.0	2.4	50.0	3.4	50.0	50.0	0.1	
Navigation Radar	99	Relative	1.00	0.67	0.88	0.35	1.00	0.43	1.00	1.00	1.00	4.49
Navigati		Data	30.0	22.0	22.0	2.0	72.0	8.0	50.0	50.0	0.1	
	77545	Relative	0.93	1.00	0.88	1.00	0.69	0.28	0.15	0.25	0.33	2.29
	36	Data	28.0	33.0	22.0	0.7	50.0	12.0	332.0	200.0	0.3	
	8888	Weighting	0.20	0.50	0.20	0.20	0.50	0.50	1.00	1.00	1.00	
		Category	Gain (dB)	Scan Rate (RPM)	Vertical BW (deg)	Horizontal BW (deg)	Range (Nm)	Antenna Width (ft)	Weight (abovedeck)	(belowdeck)	Cost ( \$ millions)	Summary
								(	C-3	5		

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**Missile Selection Matrix** 

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AAW Missil	

SM-1 (ER) RIM-66B	Parameter Relative	76 1.00	2961 0.05		0000		10 1.00	2.61
		0.18	0.06	0.29	0.00		1.00	
NSSM RUM-7	Relative	0.18	0.32	0.49	0.00		1.00	1.54
	Parameter	14	500	67	0		10	
RAM RIM-115A	Parameter Relative		162 1.00	5 0.04	1 1.00		10 1 00	1.69
	Weighting I	1	0.2	0.6	0.4		1	
	Category	Range (nm)	Weight (Ibs)	Warhead (Ibs)	Illumination Req'rd	0=yes, 1=no	<ul> <li>Logistics Support</li> </ul>	Summary 4

Value in summary column is the sum of the weighting factor x relative values

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**CIWS Selection Matrix** 

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	Goalkeeper	Parameter Relative	30 1.00	1150 1.00	360 1.00	-25 1.00	85 1.00	9.7 0.64	4200 0.93	1.61 1.00	1190 0.76	2 0.20	4.82
Short Range Engagement of Sea Skimming Missile	7	Relative	0.67	0.90	0.86	1.00	0.94	1.00	1.00	0.50	1.00	1.00	5.38
	Phalanx Mk-15	Parameter Re	20	1030	310	-25	80	6.18	4500	0.81	1562	10	
		Weighting	0.7	0.5	0.2	0.2	0.2	1	0.7	-	0.7	1	
		Category	Caliber (mm)	V muzzle (m/s)	Azimuth (deg)	Elevation (deg) (-)	( <del>+</del> )	Weight (LT)	O Fire Rate (rnd/sec)	<sup>C</sup> Range (nm)	Rounds	Logistics Commonality	Summary

Value in summary column is the sum of the weighting factor x relative values

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0.60 1.00 1.00 8. 8. 8 1.00 1.00 0.69 0.80 1.00 0.20 0.45 1.00 6.59 **Oto Melara** NK 75 76/62 Relative 925 360 -15 8 2 9 7.5 85 8.6 6.4 8 3.5 10 76 14 Parameter Qun 1.00 0.76 0.43 0.50 0.35 1.00 0.87 0.94 8.1 1.0 0.25 7.66 8 Relative 808 340 -15 21.35 12.4 20 7.7 10 65 30 20 20 80 127 ME 54 Single Sr Parameter Weighting 0.5 0.2 0.2 0.2 0.2 0.1 0.4 0.5 Azimuth (deg) Elevation (deg) (-) Rounds (+) Tmg.Rate (deg/s): Az. Elev. Caliber (mm) V muzzle (m/s) Weight (LT) Fire Rate (rnd/sec) Range (nm) ASUW Range (nm) AAW Round Weight Cost (\$M) Logistics Commonality Summary Category

**C-6** 

Value in summary column is the sum of the weighting factor x relative values

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Medium Cał Gun Selection Matrix

Medium Caliber

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TS4002

# HULL GEOM MODULE

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# PRINTED REPORT NO. 1 - HULL GEOMETRY SUMMARY

MIN BEAM, FT	40.00
MAX BEAM, FT	55.00
HULL FLARE ANGLE, DEG	7.00
FORWARD BULWARK, FT	4.00

#### HULL PRINCIPAL DIMENSIONS (ON DWL)

	==≠≈≠₩₩₽₽₽₽	======================================	
LBP, FT	390.00	PRISMATIC COEF	0.650
LOA, FT	409.31	MAX SECTION COEF	0,919
BEAM, FT	55.00	WATERPLANE COEF	0.787
BEAM @ WEATHER DECK, FT	60.27	LCB/LCP	0.515
DRAFT, FT	15.01	HALF SIDING WIDTH, FT	1.00
DEPTH STA 0, FT	45.00	DEPTH STA 3, FT	41.46
DEPTH STA 10, FT	36.50	DEPTH STA 20, FT	37.40
FREEBOARD @ STA 3, FT	30.46	BARE HULL DISPL, LTON	5493.55
STABILITY BEAM, FT	55.00	AREA BEAM, FT	54.17
BARE HULL DATA ON LI	~L	STABILITY DATA ON	LWL

x≠=====================			
LGTH ON WL, FT	389.99	KB, FT	8.19
BEAM, FT	55.00	BMT, FT	16.92
DRAFT, FT	14.99	KG, FT	19,59
FREEBOARD @ STA 3, FT	30.48	PRISMATIC COEF	0.649
MAX SECTION COEF	0.921		
WATERPLANE COEF	0,788	GMT, FT	5.51
WATERPLANE AREA, FT2	16904.38	GML, FT	763.36
WETTED SURFACE, FT2	22804.14	BARE HULL DISPL, LTON	5496.68
APPENDAGE DISPL, LTON	225.04	FULL LOAD WT, LTON	5721.71

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#### PRINTED REPORT NO. 2 - HULL OFFSETS

		•						
STATION NO	. 1. AT X = -	10 315 FT	STATION NO.	. 7, AT X =	50.453 FT	STATION NO.	12, AT $X = 14$	49.539 FT
	HALF BEAM, FT	WATERLINE, FT		HALF BEAM, FT	WATERLINE, FT		ALF BEAM, FT	WATERLINE, FT
	0.000	45.890	1	1.000	0,000	1	1.000	0.000
1 2	0.325	46,006	ź	1.942	0.042	2	15.419	0,642
ŝ	0.737	46.122	3	2.082	0.062	3	15.652	0.662
4	1.168	46.238	4	2.661	0.206	4	16,548	0.800
5	1.411	46.354	5	3,668	0.596	5	17.956	1.174
-			6	5.056	1,356	б	19.751	1,903
			7	6.659	2,608	7	21.700	3,105
			8	8.220	4.476	8	23.470	4.898
			9	9.546	7.083	9	24.783	7.400
			10	10.695	10.552	10	25.600	10.730
	2, AT X =		11	12.104	15.006	11	26.244	15,006
POINT	HALF BEAM, FT	WATERLINE, FT	12	13.741	21.729	12	26.841	20.665
1	0.000	27.882	13	14.742	28.453	13	27.028	26.324 31.982
Z	0.883	32,328	14	16,487	35.176	14 15	27.119 27.432	37.641
3	2.526	36.774	15	20.35 <del>6</del>	41.899	13	21.432	37.041
4	4.878 7.752	41.220 45.665	STATION NO	8. AT X -	70 271 ET	STATION NO	13, AT X = 1	69.356 FT
5	1.732	43.005		HALF BEAM, FT	WATERLINE, FT		ALF BEAM. FT	WATERLINE, FT
			1	1.000	0.000	1	1.000	0.000
			2	4.040	0.135	ź	17.464	0.733
			3	4.202	0.156	3	17.705	0.753
			4	4.885	0.299	4	18,608	0.890
			5	6.088	0,686	5	19.978	1,262
STATION NO	). 3, AT X =	0.000 FT	6	7.775	1.441	6	21.665	1,986
	HALF BEAM, FT	WATERLINE, FT	7	9.760	2.685	7	23.439	3.181
1	0.138	15,006	8	11.743	4.541	8	24.992	4,962
2	0.983	22.504	9	13.471	7.132	9	26.068	7,449
3	2.849	30.003	10	14.942	10.579	10	26.634	10.757
4	5.912	37,501	11	16.531	15.006	11	26.989	15,006
5	10.348	45.000	12	18.093	21.468	12	27.344	20,525
			13	18,775	27,930	13	27.467	26.043
			14	19.931	34.392	14	27.487	31,562
			15	22.916	40,854	15	27.535	37.081
CTATZON NO	<b>.</b> .	5 410 57	STATION NO	9. AT X =	90 088 FT	STATION NO	14. AT $X = 18$	9 174 FT
	), 4, AT X = HALF BEAM,FT	5.410 FT WATERLINE,FT		HALF BEAM, FT	WATERLINE, FT	POINT	HALF BEAM, FT	WATERLINE FT
1	0.000	5,395	1	1.000	0.000	1	1.000	0.000
2	0.005	5,405	2	6.745	0.255	2	18,524	0,780
3	0.072	5,472	3	6.930	0.276	3	18.804	0,797
4	0,288	5.655	4	7.696	0.418	4	19.726	0,915
ŝ	0.672	6.010	ŝ	9.031	0.802	5	20.977	1,235
Ğ	1.149	6.597	6	10.886	1,551	6	22.414	1.858
7	1.558	7,471	7	13.063	2.785	7	23.923	2,885
8	1.725	8,692	8	15.235	4.626	8	25.365	4,418
ĝ	1.583	10,316	9	17.113	7.196	9	26.539	6.556
10	1.275	12.401	10	18.655	10,615	10	27.129	9,402
11	1.226	15,006	11	20.193	15.005	11	27.367	15,006
12	2.268	22.414	12	21.566	21.231	12	27.522	20,409
13	4.099	29.822	13	22.021	27,455	13	27.565	25,812
14	7.110	37.230	14	22.719	33.680	14	27.552	31,215
15	11.688	44.637	15	24.822	39.905	15	27.535	36,618
						CTATTON NO		
	. 5, AT X -	10.819 FT		10. AT X = 1 HALF BEAM,FT			15, AT X = 20 HALF BEAM,FT	WATERLINE, FT
POINT	HALF BEAM, FT	WATERLINE,FT 0.000	POINT 1	1,000	0,000	1	1,000	0,000
1 2	0.000	0.015	2	9.751	0.390	2	18.416	0,776
ź	0.337	0.120	3	9,955	0,410	3	18.714	0.794
4	0.680	0.405	4	10.785	0.550	4	19.693	0,920
5	1.028	0.960	5	12.193	0.931	5	21.018	1,263
6	1.335	1.876	6	14.110	1.673	6	22,538	1,932
7	1,563	3.241	7	16.320	2,896	7	24.130	3.034
8	1.705	5.147	8	18.479	4.720	8	25.643	4.678
9	1,801	7.683	9	20.285	7.267	9	26.858	6.972
10	1.965	10.939	10	21.683	10.655	10	27.425	10.025
11	2.410	15.006	11	22.992	15,006	11	27.516	15,006 20,317
12	3,610	22.325	12	24.114	21.018	12	27.571	25,629
13	5.376	29.644	13	24.426 24.812	27.030 33.041	13 14	27.568 27.544	30,940
14	8.297	36.963 44.282	14 15	26.157	39.053	15	27.535	36,252
15	12.960	44.202	15	20.137	39.035	70	277333	201626
STATION NO	. 6, AT X =	30.636 FT	STATION NO	). 11, AT X =	129.722 FT	STATION NO.	16, AT X = 22	28,808 FT
POINT	HALF BEAM, FT	WATERLINE, FT	POINT	HALF BEAM, FT	WATERLINE, FT		HALF BEAM, FT	WATERLINE, FT
1	0,762	0.000	1	1.000	0.000	1	1.000	0.000
2	0.851	0.015	2	12.745	0,523	2	17.126	0.718
3	1.216	0.120	3	12.965	0.543	3	17.466	0.739
4	1.805	0.405	<u> </u>	13.839	0.682	1	18.580	0.882
5	2.574	0.960	5	15.268	1.059	5	20.090	1,272
6	3.449	1.876	6	17.155	1,795	6	21.823	2,031 3.282
7			7	19,272	3.006	7	23.640	
7	4.315	3.241			4 014	-		
8	4.315 5.063	5,147	8	21.273	4.814	8	25.369	5,149
8 9	4.315 5.063 5.670	5.147 7.683	8 9	21.273 22.860	7.337	9	25.369 26.763	5,149 7,754
8 9 10	4.315 5.063 5.670 6.270	5,147 7,683 10,939	8 9 10	21.273 22.860 23.983	7.337 10.695	9 10	25.369 26.763 27.429	5,149 7,754 11,220
8 9 10 11	4.315 5.063 5.670 6.270 7.209	5,147 7,683 10,939 15,006	8 9 10 11	21.273 22.860 23.983 24.967	7,337 10,695 15,006	9 10 11	25.369 26.763 27.429 27.525	5,149 7,754 11,220 15,006
8 9 10 11 12	4.315 5.063 5.670 6.270 7.209 8.753	5,147 7,683 10,939 15,006 22,015	8 9 10 11 12	21.273 22.860 23.983 24.967 25.823	7,337 10,695 15,006 20,829	9 10 11 12	25.369 26.763 27.429 27.525 27.595	5,149 7,754 11,220 15,006 20,250
8 9 10 11 12 13	4.315 5.063 5.670 6.270 7.209 8.753 10.148	5.147 7.683 10.939 15.006 22.015 29.024	8 9 10 11 12 13	21.273 22.860 23.983 24.967 25.823 26.056	7.337 10.695 15.006 20.829 26.652	9 10 11 12 13	25.369 26.763 27.429 27.525 27.595 27.595	5,149 7,754 11,220 15,006 20,250 25,494
8 9 10 11 12	4.315 5.063 5.670 6.270 7.209 8.753	5,147 7,683 10,939 15,006 22,015	8 9 10 11 12	21.273 22.860 23.983 24.967 25.823	7,337 10,695 15,006 20,829	9 10 11 12	25.369 26.763 27.429 27.525 27.595	5,149 7,754 11,220 15,006 20,250

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	). 17, AT X - 24			20, AT X = 31			. 23, AT X =	
POINT	HALF BEAM, FT	WATERLINE, FT	POINT	HALF BEAM, FT	WATERLINE, FT		HALF BEAM, HI	WAIERLINE, FI
1	1.000	0.000	1	1.000	2.819	1	1,000	13.698
2	14.653	0.608	2	1.151	2.831	2	1.024	13.699
3	15.061	0.633	3	1.971	2.917	3	1.237	13,708
4	16.409	0.804	4	3.777	3.148	4	1.868	13.733
5	18.239	1.269	5	6.717	3.599	5	3.082	13.781
6	20.344	2,175	6	10.597	4.342	6	4.938	13.861
7	22.557	3,668	7	14.892	5.451	7	7.363	13,980
8	24,677	5,896	8	18.880	6,999	8	10.141	14.146
ğ	26.415	9.005	9 9	21.964	9.059	9	12,918	14.367
10	27.319	13.142	10	23.934	11.703	10	15,196	14.651
11	27.422	15.006	11	25.103	15.006	11	16.287	15.006
12	27.586	20.207	12	26.067	20.251	12	18.602	20,604
			13	26.343	25.497	13	19.925	26,203
13	27.583	25.408				14	20.695	31,801
14	27.528	30.609	14	26.340	30,742			
15	27.535	35.810	15	26.463	35.988	15	21.352	37.400
CTATION N		1 107 FT	CTATION NO	31 AT V 34	1 875 FT			
	D. 18, AT X = 27			. 21, AT X = 34				
POINT	HALF BEAM, FT	WATERLINE, FT	POINT	HALF BEAM, FT	WATERLINE, FT			
1	1.000	0.263	1	1.000	5.490			
2	10.133	0.670	2	1.118	5.499			
3	10.371	0.689	3	1.768	5.566			
4	11.386	0.827	4	3.214	5.746			
5	13.205	1.201	5	5.599	6.099			
6	15,791	1,928	6	8.829	6.679			
7	18.871	3.128	7	12.536	7.545			
8	21,954	4,917	8	16.193	8.754			
9	24.514	7.415	9	19.306	10,362			
10	26.227	10.738	10	21.581	12.427			
11	27.098	15,006	11	22,998	15.006			
12	27.469	20.187	12	24,355	20.335			
13	27.538	25.369	13	24,848	25.664			
					30.992			
14	27.497	30.551	14	24.962				
15	27.535	35.732	15	25.187	36.321			
STATION	NO. 19. AT X = 2	95.750 FT	STATION N	0. 22, AT X = 3	66.438 FT			
POINT	HALF BEAM, FT	WATERLINE, FT	POINT	HALF REAM, FT	WATERI INF, FT			
1	1.000	1.145	1	1.000	9.290			
ź	1.834	1.183	ī	1.076	9.295			
3	2,069	1.202	3	1.523	9.335			
4	3,304	1.334	4	2.573	9.444			
	5,968	1.695	5	4.376	9.655			
5			5	6.917	10.004			
ē,	10.113	2.396						
7	15.157	3.553	7	9.987	10.524			
8	20.006	5.278	8	13.228	11.250			
9	23.595	7.687	9	16.232	12.216			
10	25.514	10,891	10	18.608	13.457			
11	26.399	15.006	11	19.998	15.006			
12	27.043	20.202	12	21.823	20.452			
13	27.208	25.399	13	22. <del>6</del> 80	25.899			
14	27.183	30.595	14	23.064	31.345			
15	27.259	35,791	15	23.470	36.792			
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#### PRINTED REPORT NO. 3 - HULL BOUNDARY CONDITIONS

LBP, FT	390.00	LCB/LBP	0.515
BEAM, FT	55.00	LCF/LBP	0.555
DRAFT, FT	15.01	HALF SIDING WIDTH, FT	1.00
DEPTH STA O, FT	45.00	DEPTH STA 3, FT	41.46
DEPTH STA 10, FT	36.50	DEPTH STA 20, FT	37.40
RAISED DECK HT, FT	0.00	PRISMATIC COEF	0.650
WATERPLANE COEF	0.787	MAX SECTION COEF	0.919
NO POINTS BELOW DWL	11.	FWD KEEL/BL LIMIT	0.028
NO POINTS ABOVE DWL	4.	AFT KEEL/BL LIMIT	0.637
POINT DIST FAC ABOVE DWL	3.000	BOW ANGLE, DEG	50.00
POINT DIST FAC BELOW DWL	1.000	BOW SHAPE FAC	0.000
BOW OVERHANG	0.050	STA 20 SECTION COEF	0./00
STERN OVERHANG	0.009	HULL FLARE ANGLE, DEG	7.

SECTIONAL AREA AND DWL CURVES

	AREA	DWL				
		<b>-</b>				
STA O ORDINATE	0.000	0.005				
STA 0 SLOPE	-1.189	-1.352				
STA 20 ORDINATE	0.039	0.591				
STA 20 SLOPE	1.084	1.173				
PARALLEL MID LGTH	0.000	0.000				
STA MAX ORDINATE	10.500	11.300				
STA MAX AREA SLOPE	0.000	0.000				
TENSOR NO 1	0.000	0.000				
TENSOR NO 2	0.000	0.000				
TENSOR NO 3	0.000	0.000				
TENSOR NO 4	0.000	0.000				
TENSOR/POLY SWITCH	0.000	0.000				
DECK AT EDGE CURVE		FLAT OF BOTTOM CURVE				
		<b>■≈≈≈≈≈≈≈≈</b> ≈≈≈≈≈≈≈≈≈≈≈≈≈≈≈				
STATION 0 OFFSET	0.376	STA OF TRANS START	1.500			
STA 0 SLOPE	-1.800	SLOPE-STA OF TRANS START	-0.190			
STA 10 OFFSET	1.000	STA OF START OF MID	8.688			
STA 10 SLOPE	0.000	STA OF END OF MID	13.414			
STATION 20 OFFSET	0.775	STA OF TRANS END	15.542			
STA 20 SLOPE	0.693	SLOPE-STA OF TRANS END	0.000			
PARALLEL MID LGTH	0.271	FLAT OF BOT ANGLE, DEG	2.550			
STA OF PARALLEL MID	11.242	ELLIPSE RATIO	1.000			

#### SLOPES AT SECTION CURVES

	BOT	Dwi	DAF			
STA O ORDINATE, DEG	8.000	87.000	55.364			
STA O SLOPE	17.900	113.117	76.563			
STA 10 ORDINATE, DEG	1.016	89.000	90.000			
STA 10 SLOPE	0.475	0.000	0.000			
STA 20 ORDINATE, DEG	1.000	62.158	82.404			
STA 20 SLOPE	5.000	23.238	12.842			
PARALLEL MID LGTH	0.000	0.000	0.000			
STA OF PARALLEL MID	10.500	10.918	9.455			

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# PRINTED REPORT NO. 4 - MARGIN LINE

MIN FREEBOARD MARGIN, FT 0.25

DIST FROM FP	HT ABOVE BL
FT	FT
-19.31	46.10
-9.66	45.42
0.00	44.75
5.41	44.39
10.82	44.03
30.64	42.79
50.45	41.65
70.27	40.60
90.09	39.65
109.90	38.80
129.72	38.05
149.54	37,39
169.36	36.83
189.17	36.37
208.99	36.00
228.81	35.73
248,63	35.56
272.19	35.48
295.75	35.54
319.31	35.74
342.88	36.07
366.44	36.54
390.00	37.15

## PRINTED REPORT NO. 5 - HULL SECTIONAL AREA CURVE

STATION	LOCATION.FT	AREA.FT2
1	-19.31	0.00
2	-9.66	0.00
3	0.00	0.00
4	5.41	25.69
5	10.82	52.50
6	30.64	158.70
7	50.45	271.48
8	70.27	382.65
9	90.09	485.27
10	109.90	574.11
11	129.72	646.09
12	149.54	700.07
13	169.36	736.36
14	189.17	755.95
15	208.99	759.89
16	228.81	748.75
17	248.63	722.26
18	272.19	668.83
19	295.75	585.81
20	319.31	470.15
21	342.88	324.39
22	366.44	164.23
23	390.00	30.00

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# HULL SUBDIV MODULE

### PRINTED REPORT NO. 1 - SUMMARY

SHAFT SUPPORT TYPE IND-OP	EN STRUT		
LBP. FT	390.00	HULL AVG DECK HT, FT	9.95
DEPTH STA 10, FT	36.50	NO INTERNAL DECKS	3
HULL VOLUME, FT3	598974.	NO TRANS BHDS	13
MR VOLUME, FT3	118500.	NO LONG BHDS	6
TANKAGE VOL REQ, FT3	62536.	NO MACHY RMS	3
EXCESS TANKAGE, FT3	0.	NO PROP SHAFTS	2
ARR AREA LOST TANKS, FT2	2557.1		
HILL ARR ARFA AVATI, FT2	42299.5		

### PRINTED REPORT NO. 2 - TRANSVERSE BULKHEADS

NO TRANS BHDS 13 TRANS BHD SPACING(/LBP) 0.075						
BULKHEAD NO	DISTANCE FROM FP,FT	DISTANCE FROM FP/LBP	MR FWD BHD LOC			
======= 1	19.50	0.050				
2	42.76	0.110				
3	66.02	0.169				
	89.29	0.229				
4 5	112.55	0.289	MMR			
6	148.33	0.380				
7	177.58	0.455	MMR			
8	213.15	0.547				
9	242.40	0.622	AMR			
10	282.88	0.725				
11	309.66	0.794				
12	336.44	0.863				
13	363.22	0.931				

### PRINTED REPORT NO. 3 - LONGITUDINAL BULKHEADS

NO LONG BHDS LBP, FT HALF BREADTH, FT			5 .00 .54		
	-/P,+/S	FWD	AFT	UPPER	LOWER
BULKHEAD	DIST OFF	BHD	BHD	DECK	DECK
NO	CL, FT	ID	ID	ID	ID
		===	===		
1	25.61	3	6	0	3
2	-25.61	3	6	0	3
3	25.61	6	9	0	3
4	-25.61	6	9	0	3
5	25.61	9	12	0	3
6	-25.61	9	12	0	3

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	TED REPORT				AND INNER BO	-
	STA 10 FT		02.85	CVK HT FT	THREE DOTTOR	2 50
	VC DECK HT	FT	9 95	HORZ OFFSE	T HT, FT	10.00
	DECK HT, FI	r	0.00		T, FT	2 00
	•					
TNT	DIST FROM	DECK		FLAT AFT I	0C, FT 0C, FT 0 L0C, FT 7 L0C, FT	315 73
DECK	RIAT	SHEER		OFFSET FWD		19 50
NO	S I RP FT	FRAC		OFFSET AFT	10C FT	315 73
=====		=====				313.75
2	26.50 17.50 10.00	0.0				
2	10.00	0.0				
IB	2.50	0.0				
INT	AVL ARR	AVL ARR	USABLE	VOIDS	ARR AREA	
	AREA					
	FT2					
===#	1222222	=======	22žece,	친분분들은		
1	18233.8	187964.	0.	0.	0.0	
	13384.3				0.0	
3	9086.2	74163.	2095.	2031.	0.0	
	1595.2	23545.	18793.	0.	2557.1	
HOLD				88.		
	<b>-</b>	<b>-</b>		+	<b>_--</b>	
TOTAL	42299.5	420708.	62536.	2659.	2557.1	

# PRINTED REPORT NO. 5 - LARGE OBJECT SPACES

FOREPEAK VOID VOL FOREPEAK TANKAGE, CHAIN LOCKER VOL, SEWAGE VOL REQ, F SHAFT ALLEY VOL,	FT3 FT3 T3	734. 1469. 2203. 385. 3011.				
MR AFT BHD POS. F		82.88				
INNER BOT VOL. FT		6241.				
INNER BOT VOL, IT	, <u> </u>	0241.				
FWD UPR	LGTH	LGTH	HT	нт	MR	INNER
MR BHD DEC		ROD	AVL	RQD	VOL	BOT VOL
NO TYPE ID ID	ਜ	FT	FT	FT	FT3	FT3
		******				
1 MMR 5 1	35.78	35.78	26,50	Z3.49	43855.	3674.
2 MMR 7 1.	35.57	35.57	26.50	22.83	45123.	4310.
3 AMR 9 2	40.48	40.48	17.50	17.50	29522.	3935.
			-	TOTAL	118500.	11919.

## PRINTED REPORT NO. 6 - HULL COMPARTMENT ARRANGEABLE AREA AREAS FOR EACH HULL COMPARTMENT:

DECK HT, FT ABL	26.5 346.5	17.5	10.0	2.5
COMP 2, FT2	528.3	367.5	288.7	92.4
COMP 3, FT2	750.1	636.8	528.5	239.7
COMP 4, FT2	942.1	867.0	749.7	404.1
COMP 5, FT2	1090.7	1041.5	935.4	574.9
COMP 6, FT2	1861.6	MMR	MMR	MMR
COMP 7, FT2	1599.3	1578.9	1532.5	1172.2
COMP 8, FT2	1960.8	MMR	MMR	MMR
COMP 9. FT2	1613.0	1612.5	1593.6	1207.6
COMP 10, FT2	2230.4	2218.0	AMR	AMR
COMP 11, FT2	1454.4	1431.1	1334.9	449.0
COMP 12, FT2	1398.6	1358.0	1186.8	12.4
COMP 13, FT2	1299.2	1229.2	869.9	
COMP 14, FT2	1158.9	1043.7	66,2	

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#### DECKHOUSE MODULE

#### PRINTED REPORT NO. 1 - DECKHOUSE SUMMARY

LBP, F1 BEAM, FT	390.00 55.00	DKHS LENGTH OA, FT DKHS MAX WIDTH, FT	89.49 43.04
AREA BEAM, FT	54.17	DKHS HT (W/O PLTHS), FT	55.65
	STA 4.6	OTHER ARR AREA REQ, FT2	41663.04
DKHS AFT LIMIT	STA 9.2	HULL ARR AREA AVAIL, FT2	42299.48
DKHS AVG DECK HT, FT	8.50	DKHS ARR AREA REQ, FT2	7744.25
DKHS NO LVLS	3	HANGER ARR AREA REQ, FT2	1700.00
DKHS AVG SIDE CLR, FT	6.00	PLTHS ARR AREA REQ, FT2	671.93
DKHS AVG SIDE ANG, DEG	7.00		
DKHS NO PRISMS	20	DKHS MAX ARR AREA, FT2	17095.67
DKHS ARR AREA DERIV, FT2	429.74	DKHS ARR AREA AVAIL, FT2	7828.90
DKHS MIN ALW BEAM, FT	31.25	DKHS VOLUME, FT3	67163.65
BRIDGE L-O-S OVER BOW, FT	239.08	DKHS WEIGHT, LTON	114.10
DKHS SIDE CLR OFFSET, FT		DKHS VCG, FT	47.88
DKHS SIDE ANG OFFSET, DEC			

#### PRINTED REPORT NO. 2 - SUPERSTRUCTURE DECKHOUSES

NO OF SS DECKHOUSE BLKS DKHS VOLUME, FT3 DKHS ARR AREA AVAIL, FT2	20 67164. 7828.9				
				JMBER	
	1	2	3	4 112.61	5
DIST FROM BOW, FT	89.70	97.34	104.98	112.61	120.25
LENGTH, FT	7.64	7.64	7.64	7.64	7.64
DIST FROM CL, FT					
FWD/PORT/BTM	-18,79	-19.37	-19.87	-20.30	-20.66
AFT/PORT/BTM	-19.37	-19.87	-20.30	-20.66	-20.94
FWD/STBD/BTM	18,79	19.37	19.87	20.30	20.66
AFT/STBD/BTM	19.37	19.87	20.30		20.94
FWD/PORT/TOP	-17.75				-19.62
AFT/PORT/TOP	-18.32				-19.90
FWD/STBD/TOP		18.32			19.62
AFT/STBD/TOP	18.32				
DIST ABV BASELINE FWD, FT					38.65
DIST ABV BASELINE AFT, FT	39.58				
HEIGHT, FT				8.50	
VOLUME, FT3	2458.				-
ARR AREA, FT2	283.5	291.7	298.9	304.9	309.8
				UMBER	
	6				10
DIST FROM BOW, FT	127.89		143.17	-	
LENGTH, FT	7.64		7.64		7.64
DIST FROM CL. FT	7104				
FWD/PORT/BTM	-20.94	-21.16	-21.33	-21.45	-17.75
AFT/PORT/BTM	-21.16				
FWD/STBD/8TM	20.94		21.33	21.45	17.75
AFT/STBD/BTM	21.16		21.45	21.52	18.32
FWD/PORT/TOP	-19.90			-20.40	-16.70
AFT/PORT/TOP	-20.12	-20.29	-20,40	-20.48	-17.28
FWD/STBD/TOP	19.90	20.12	20.29	20.40	16.70
	70 17				

20.12

38.36

38.10

8.50

2708.

313.6

AFT/STBD/TOP

HEIGHT, FT VOLUME, FT3

ARR AREA, FT2

DIST ABV BASELINE FWD, FT DIST ABV BASELINE AFT, FT

20.29

38.10

37.84

8.50

2731.

316.6

20.40

37.84

37.60

8.50

2748.

318.8

20.48

37.60

37.38

8.50

2758.

320.2

17.28

48.42

48.42

8.50

2274.

267.5

	ΟE	скноч	SE N	UMBER	
	11	12	13	14	15
DIST FROM BOW, FT	97.34	104.98	112.61	120.25	
LENGTH, FT	7.64	7.64	7.64	7.64	7.64
DIST FROM CL, FT					
FWD/PORT/BTM	-18.32	-18.83	-19.26	-19.62	-19.90
AFT/PORT/BTM	-18.83	-19.26	-19.62	-19.90	-20.12
FWD/STBD/BTM	18.32	18.83	19.26	19.62	19.90
AFT/STBD/BTM	18.83	19.26	19.62	19.90	20.12
FWD/PORT/TOP	-17.28		-18.21	-18.57	-18.86
AFT/PORT/TOP	-17.78		-18.57		-19.07
FWD/STBD/TOP	17.28	17.78		18.57	18.86
AFT/STBD/TOP	17.78	18.21		18.86	19.07
DIST ABV BASELINE FWD, FT	48.08	47.76		47.15	46.86
DIST ABV BASELINE AFT, FT	48.08		47.44		46.86
HEIGHT, FT	8.50	8.50	8.50	8.50	8.50
VOLUME, FT3	2344.	2405.	2456.	2498.	2530.
ARR AREA, FT2	275.8	282.9	288.9	293.8	297.7
	<b>n</b> <i>r</i>	<u> </u>	C C N		
		скнои		UMBER	20
DICT FROM DOLL FT	16	17	18	19	20
DIST FROM BOW, FT	16 135.53	17 143.17	18 150.80	19 158.44	89.70
LENGTH, FT	16	17 143.17	18 150.80	19 158.44	
LENGTH, FT DIST FROM CL, FT	16 135.53 7.64	17 143.17 7.64	18 150.80 7.64	19 158.44 20.75	89.70 30.56
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM	16 135.53 7.64 -20.12	17 143.17 7.64 -20.29	18 150.80 7.64	19 158.44 20.75 -21.52	89.70 30.56
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM	16 135.53 7.64 -20.12 -20.29	17 143.17 7.64 -20.29 -20.40	18 150.80 7.64 -20.40 -20.48	19 158.44 20.75 -21.52 -21.54	89.70 30.56 -11.75 -14.05
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM	16 135.53 7.64 -20.12 -20.29 20.12	17 143.17 7.64 -20.29 -20.40 20.29	18 150.80 7.64 -20.40 -20.48 20.40	19 158.44 20.75 -21.52 -21.54 21.52	89.70 30.56 -11.75 -14.05 11.75
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM	16 135.53 7.64 -20.12 -20.29 20.12 20.29	17 143.17 7.64 -20.29 -20.40 20.29 20.40	18 150.80 7.64 -20.40 -20.48 20.40 20.48	19 158.44 20.75 -21.52 -21.54 21.52 21.54	89.70 30.56 -11.75 -14.05 11.75 14.05
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36	19 158.44 20.75 -21.52 -21.54 21.52 21.54 -19.43	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70
LENGTH, FT DIST FROM CL, FT FWD/PORT/8TM AFT/PORT/8TM FWD/STBD/8TM AFT/STBD/8TM FWD/PORT/TOP AFT/PORT/TOP	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43	19 158.44 20.75 -21.52 -21.54 21.52 21.54 -19.43 -19.45	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP FWD/STBD/TOP	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36	19 158.44 20.75 -21.52 -21.54 21.54 -19.43 -19.45 19.43	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP FWD/STBD/TOP AFT/STBD/TOP	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07 19.24	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24 19.36	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36 19.43	19 158.44 20.75 -21.52 -21.54 21.52 21.54 -19.43 -19.45 19.43 19.45	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70 13.01
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP FWD/STBD/TOP AFT/STBD/TOP DIST ABV BASELINE FWD, FT	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07 19.24 46.60	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24 19.36 46.34	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36 19.43 46.10	19 158.44 20.75 -21.52 -21.54 -19.43 -19.43 -19.43 19.45 19.43 19.45 37.38	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70 13.01 55.65
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP AFT/STBD/TOP AFT/STBD/TOP DIST ABV BASELINE FWD, FT DIST ABV BASELINE AFT, FT	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07 19.24 46.60 46.60	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24 19.36 46.34	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36 19.43 46.10 46.10	19 158.44 20.75 -21.52 -21.54 -19.43 -19.43 19.45 19.43 19.45 37.38 36.84	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70 13.01 55.65 55.65
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP AFT/STBD/TOP AFT/STBD/TOP DIST ABV BASELINE FWD, FT DIST ABV BASELINE AFT, FT HEIGHT, FT	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07 19.24 46.60 46.60 8.50	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24 19.36 19.24 46.34 46.34 8.50	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36 19.43 46.10 8.50	19 158.44 20.75 -21.52 -21.54 21.52 21.54 -19.43 -19.43 19.45 19.43 19.45 37.38 36.84 17.00	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70 13.01 55.65 55.65 8.50
LENGTH, FT DIST FROM CL, FT FWD/PORT/BTM AFT/PORT/BTM FWD/STBD/BTM AFT/STBD/BTM FWD/PORT/TOP AFT/PORT/TOP AFT/STBD/TOP AFT/STBD/TOP DIST ABV BASELINE FWD, FT DIST ABV BASELINE AFT, FT	16 135.53 7.64 -20.12 -20.29 20.12 20.29 -19.07 -19.24 19.07 19.24 46.60 46.60	17 143.17 7.64 -20.29 -20.40 20.29 20.40 -19.24 -19.36 19.24 19.36 46.34	18 150.80 7.64 -20.40 -20.48 20.40 20.48 -19.36 -19.43 19.36 19.43 46.10 8.50	19 158.44 20.75 -21.52 -21.54 21.52 21.54 -19.43 -19.43 19.45 19.43 19.45 37.38 36.84 17.00	89.70 30.56 -11.75 -14.05 11.75 14.05 -10.70 -13.01 10.70 13.01 55.65 55.65

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# PRINTED REPORT NO. 3 - DECKHOUSE STRUCTURE WEIGHT SUMMARY

14450.

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DKHS STRUCT DENSITY, LBM/FT3 4.18 HANGER VOL, FT3	
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CALCULATED	SWBS15		LTON	VCG-FT 47.88	LCG-FT 132.61
	NO. 2 NO. 3 NO. 4 NO. 5 NO. 6	2677. 2708. 2731. 2748. 2758. 2274. 2344. 2405. 2498. 2498. 2530. 2555. 2574. 2586. 14679. 6431.	43.71 43.39 42.79 42.25 42.00 41.76 52.63 52.63 51.66 51.66 51.66 51.66 51.36 50.81 50.51 50.32 45.60		
		67164.	47.88		

D-9

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# HULL STRUCT MODULE

### PRINTED REPORT NO. 1 - SUMMARY

HOGGING 8M, FT-LTON 7 SAGGING 8M, FT-LTON 6 MIDSHIP MOI, FT2-IN2 28 DIST N.A. TO KEEL, FT DIST N.A. TO DECK, FT SEC MOD TO KEEL, FT-IN2 1	'5500. F 52944. F 51961. F	PRIM STRESS KEE PRIM STRESS KEE PRIM STRESS DEC	L-HOG, KSI L-SAG, KSI K-HOG, KSI	8.84 7.37
TYPE	NO OF SEGMENT			
WET. DECK HY 80 SIDE SHELL HY 80 BOTTOM SHELL HY 80 INNER BOTTOM HY 80 INT. DECK HY 80 STRINGER, SHEER HY 80 LONG BULKHEAD HY 80 TRANS BULKHEAD HY 80	3 4 6 3 1	1 1 1 3 1 6 13		
HULL STRUCTURE WEIGHT SWBS COMPONENT	WEIGHT,	, LTON VCG,	FT	
HULL STRUCTURE WEIGHT SWBS COMPONENT 100 HULL STRUCTURE 110 SHELL+SUPPORT 120 HULL STRUCTURAL BHD 130 HULL DECKS 140 HULL PLATFORM/FLATS	25	53.7 <u>16.</u> 53.7 <u>33.</u>	4/ 16	

#### PRINTED REPORT NO. 2 - HULL STRUCTURES WEIGHT

SWBS COMPONENT	WT-LTON	VCG-FT
	**********	*======================================
*100 HULL STRUCTURES	1245.3	19.23
* 110 SHELL + SUPPORTS	661.0	15.65
111 PLATING	330.8	19.88
113 INNER BOTTOM	135.4	3.07
115 STANCHIONS	8.1	18.25
116 LONG FRAMING	59.4	.93
117 TRANS FRAMING	102.4	18.11
120 HULL STRUCTURAL BULKHDS	209.0	16.47
121 LONG BULKHDS	80.7	10.28
122 TRANS BULKHDS	97.9	20.37
123 TRUNKS + ENCLOSURES	30.4	20.37
130 HULL DECKS	253.7	33.16
131 MAIN DECK	141.1	37.76
132 2ND DECK	112.6	27,40
133 3RD DECK		
134 4TH DECK		
135 5TH DECK+DECKS BELOW		
136 O1 HULL DECK		
140 HULL PLATFORMS/FLATS	121.6	14.39
141 1ST PLATFORM	71.9	17.46
142 2ND PLATFORM	49.7	9,95
143 3RD PLATFORM		5155
144 4TH PLATFORM		
145 STH PLAT+PLATS BELOW		

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

**D-1**0

#### PRINTED REPORT NO. 3 - WEATHER DECK

DECK MTRL TYPE-HY 80 STRINGER PLATE MTRL TYPE-HY 80

JININGEN FLATE MINE ITFE~			
		SHELL	STRINGER PLATE
MODULUS OF ELASTICITY, K	SI	29600.0	29600.0
DENSITY, LBM/FT3		489.02	489.02
YIELD STRENGTH, KSI		80.00	80,00
MAX PRIMARY STRENGTH, KS	I	23.52	23.52
ALLOWABLE WORKING STRENG	55.00	55.00	
	MAX	MIN	
STIFFENER SPACING, IN	48.00	24.00	
STRINGER PLATE WIDTH, FT	6.00		

SEGMENT GEOMETRY

	NO	DE COORD,	FT		SCND. LO	AD, FT
SEG	YIB	ZIB	YOB	ZOB	HEAD1	HEAD2
1	0.00	36,51	9.28	36.51	8.64	
2	9.28	36.51	21.54	36.51	8.63	
3	21.54	36.51	27.54	36,51	8.62	

SEGMENT SCANTLINGS

SCANTLINGS OF STIFFENED PLATES								
				CATLG	NO.OF	PLATE	SPACING	
SEGINXINXIN/IN					NO	STIFF	TK, IN	IN
1 *R	3.920X	2.000X	0.120/	0.180	2.	2	0.4375	37.12
2 *R	3.920X	2.000X	0.120/	0.180	2.	4	0.3438	29.41
3 *R	3.002X	2.000X	0.125/	0.188	1.	3	0.3438	24.00
NOTE:	*R STANDS	FOR ROLL	ED SHAPE					

SEGMENT PROPERTIES

		PF	ROPERTIES OF	STIFFENED	PLATES		
	AREA		N.A. TO	SEC N	SEC MOD		
	TOTAL	SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO
SEG	IN2	IN2	IN	IN3	IN3	LBF/FT	
1	17.12	0.54	0.38	25.95	2.37	58.14	0.05
2	10.99	0.53	0.42	22.22	2.31	37.33	0.09
3	9.00	0.44	0.38	13.35	1.60	30.57	0.09

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#### PRINTED REPORT NO. 4 - SIDE SHELL

SIDE SHELL MTRL TYPE-HY 80 SHEER STRAKE MTRL TYPE-HY 80 SHEER STRAKE SHELL MODULUS OF ELASTICITY, KSI 29600.0 29600.0 DENSITY, LBM/FT3 489.02 489.02 YIELD STRENGTH, KSI 80.00 80.00 MAX PRIMARY STRENGTH, KSI ALLOWABLE WORKING STRENGTH, KSI 23.52 55.00 23.52 55.00 MAX MIN STIFFENER SPACING, IN 48.00 24.00 SHEER STRAKE WIDTH, FT 6.00 SEGMENT GEOMETRY -----SCND. LOAD, FT-----SCND. LOAD, FT--

SEG	YUPR	ZUPR	YLWR	ZLWR	HEAD1	HEAD2		
1	27.54	36.51	27.55	30.51	7.81			
2	27.55	30.51	27.56	26.50	12.00			
3	27.56	26.50	27.48	17.50	18.51			
4	27.48	17.50	27.23	10.00	26.76			

SEGMENT SCANTLINGS

SCANTLINGS OF STIFFENED PLATES										
	S	TIFFENERS	5	CATLG	NO.OF	PLATE	SPACING			
SEG	II	INXINXIN/IN					TK, IN	IN		
1 *R	3.002X	2.000X	0.125/	0.188	1.	3	0.3438	24.00		
2 *R	3.002X	2.000X	0.125/	0.188	1.	1	0.3125	24.06		
3 *R	3.920X	2.000X	0.120/	0.180	2.	2	0.3438	36.01		
4 *R	4.9ZOX	2.000X	0.120/	0.180	4.	1	0.4375	45.02		
NOTE:	*R STANDS	FOR ROLL	ED SHAPE							

#### SEGMENT PROPERTIES

	AREA		N.A. TO	TOSEC MOD			SMEAR
	TOTAL	SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO
SEG	IN2	INZ	IN	IN3	IN3	LBF/FT	
1	9.00	0.44	0.38	13.35	1.60	30.57	0.09
2	8.27	0.44	0.38	13.05	1.58	28.08	0.10
3	13.26	0.53	0.38	25.01	2.31	45.03	0.07
4	20.70	0.66	0.39	39,33	3.01	70.29	0.05

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### PRINTED REPORT NO. 5 - BOTTOM SHELL

BOTTOM SHELL MTRL TYPE-HY MODULUS OF ELASTICITY,		29600.0	
DENSITY, LBM/FT3	101	489.02	
YIELD STRENGTH, KSI		80.00	
MAX PRIMARY STRENGTH, K	(SI	23.52	
ALLOWABLE WORKING STREM	55.00		
	MAX	MIN	
STIFFENER SPACING, IN	48.00	24.00	
SEGMENT GEOMETRY			
NODE COORD,	FT		SCND
		711-0	UEAI

COMENT	GEOMETRY					
-	NO	DE COORD,	FT		SCND. LO	AD, FT
SEG	YUPR	ZUPR	YLWR	ZLWR	HEAD1	HEAD2
1	27.23	10.00	21.38	1.45	35.56	
2	21.38	1.45	19.27	0.86	39.44	
3	19.27	0.86	12.94	0.53	39.84	
4	12.94	0.53	8.59	0.34	42.08	
5	8.59	0.34	3.72	0.12	42.93	
6	3.72	0.12	0.00	0.00	42.12	

SEGMENT SCANTLINGS

SCANTLINGS OF STIFFENED PLATES										
	STIFFENERS						PLATE	SPACING		
SEG	II	NXINXIN/1	[N		NO	STIFF	TK, IN	IN		
1 *R	4.920X	3.000X	0.120/	0.180	6.	2	0.4375	43.58		
2 *R	3.002X	2.000X	0.125/	0.188	1.	1	0.3438	13.56		
3 *R	4.920X	2.000X	0.120/	0.180	4.	1	0.5000	31.02		
4 *R	4.920X	2.000X	0.120/	0.180	4.	1	0.4375	25.18		
5 *R	4.920X	3.000X	0.120/	0.180	6.	1	0.5625	33.12		
6 *R	3.920X	2.000X	0.120/	0.180	2.	1	0.3438	20.72		
NOTE:	*R STANDS	FOR ROLL	ED SHAPE							

SEGMENT PROPERTIES

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		PF	ROPERTIES OF	STIFFENED	PLATES	<del>-</del> -	
	AREA		N.A. TO	SEC N	SEC MOD		SMEAR
	TOTAL	SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO
SEG	INZ	INZ	IN	IN3	IN3	LBF/FT	
1	20.26	0.66	0.45	45,93	4.05	68.79	0.06
2	5.41	0.44	0.51	9,32	1.59	18.38	0.16
3	16.51	0.67	0.47	33,15	3.05	56.06	0.06
4	12.02	0.66	0.52	28.90	2.99	40.80	0.09
5	19.82	0.68	0.52	41.05	4.15	67.31	0.06
6	8.00	0.53	0.51	17,73	2.30	27.18	0.12

### PRINTED REPORT NO. 6 - INNER BOTTOM

INNER BOTTOM MTRL TYPE-HY	80	
MODULUS OF ELASTICITY, K	SI	29600.0
DENSITY, LBM/FT3		489.02
YIELD STRENGTH, KSI		80.00
MAX PRIMARY STRENGTH, KS	51	23.52
ALLOWABLE WORKING STRENG	στH, KSI	55.00
	MAX	MIN
STIFFENER SPACING, IN	48.00	24.00

SEGMENT GEOMETRY

	NO	DE COORD,	FT		SCND. LO	DAD, FT
SEG	YUPR	ZUPR	YLWR	ZLWR	HEAD1	HEAD2
1	25.23	10.00	21.38	2.50	3.14	38.99
2	21.38	2.50	19.27	2.50	2.64	39.70
3	19.27	2.50	12.94	2.50	3.26	38.21
4	12.94	2.50	8.59	2.50	2.97	35.25
5	8.59	2.50	3.72	2.50	3.05	33.02
6	3.72	2.50	0.00	2.50	2.88	30.70

SEGMENT SCANTLINGS

SCANTLINGS OF STIFFENED PLATESSCANTLINGS OF STIFFENED PLATES											
	5	CATLG	NO.OF	PLATE	SPACING						
SEG	I	NXINXIN/I	N		NO	STIFF	TK, IN	IN			
1 *R	3.920X	2.000X	0.120/	0.180	2.	2	0.3750	34.92			
2 *R	3.002X	2.000X	0.125/	0.188	1.	1	0.2188	12.64			
3 *R	3.920X	2.000X	0.120/	0.180	2.	1	0.4375	38.00			
4 *R	3.002X	2.000X	0.125/	0.188	1.	1	0.4375	26.10			
5 * R	3.002X	2.000X	0.125/	0.188	1.	1	0.5000	29.24			
6 *R	3.002X	2.000X	0.125/	0.188	1.	1	0.3438	22.30			
NOTE:	*R STANDS	FOR ROLL	ED SHAPE								

SEGMENT PROPERTIES

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	PROPERTIES OF STIFFENED PLATESPROPERTIES OF STIFFENED PLATES										
	AREA		N.A. TO		SEC MOD						
	TOTAL	SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO				
SEG	IN2	IN2	IN	IN3	IN3	LBF/FT					
1	13.97	0.54	0.38	24.94	2.33	47.45	0.07				
2	3.52	0.43	0.62	6.79	1.52	11.94	0.27				
3	17.50	0.54	0.38	26.22	2.37	59.45	0.05				
4	12.17	0.45	0.37	14.40	1.65	41.33	0.07				
5	15.37	0.46	0.37	15.07	1.70	52.20	0.05				
6	8.42	0.44	0.39	12.80	1.60	28.59	0.10				

D-14

## PRINTED REPORT NO. 7 - INTERNAL DECKS

	OF INTERNA						
INTERNAL	DECK MTR	L TYPE-HY	80	29600.0			÷
MODULI	JS OF ELAS TY, LBM/FT STRENGTH,	TICITY, K	51	29600.0 489.02			
	STRENCTU	3 VCT		409.02 80.00			
MAY DI	SINCINGIN,	ENCTH KS	т	23.52			
ALLOW/	STRENGTH, RIMARY STR ABLE WORKI	NG STRENG	TH, KSI	55.00			
SECMENT	GEOMETRY						
 655	•NOD	E COORD, I	FI	700	SCND. LO HEAD1	AU, FI	
DECK NO.	1	210	TUB	200	HEADI	<b>NLAUZ</b>	
~ ~ ~							
1	0.00	26.50	9.28	26.50	2.67 2.67 2.67	25.40	
2	9.28	26.50	17.90	26.50	2.67	29.87	
3	17.90	26.50	27.56	26.50	2.67	34.36	
DECK NO.	.2						
SEG	0 00	17 50	0.28	17 50	7 67	25 40	
2	9.28	17.50	17.90	17.50	2.67	29.87	
3	17.90	17.50	27.48	17.50	2.67 2.67 2.67	34.36	
DECK NO	.3						
SEG							
1	0.00	10.00	9.28	10.00	2.67	25.40	
2	9.28	10.00	17.90	10.00	2.67	29.87	
3	17.90	10.00	27.23	10.00	2.67 2.67 2.67	34.36	
SEGMENT	SCANTLING	5					
		SC	ANTLINGS	OF STIFFE	NED PLATES-		CDACTNC
		SILFFENER	5		CATLG NO.OF NO STIFF	PLAIE TV TN	
		INAINAIN/	TN			ik, in	TIN
DECK NO	.L R 3 002X	2.000X	0 1257	0.188	1. 3	0.2500	Z7.84
2 * R	4,920X	2.000X	0.120/	0.180	4. 3	0.2500	25.86
3 *R	4.920X	2.000X	0.120/	0.180	1. 3 4. 3 4. 3	0.2813	29.00
DECK NO	2						
1 *R	3.002X	2.000X	0.125/	0.188	1. 2 2. 2 2. 2	0.2500	37.12
2 *R	3.920X	2.000X	0.120/	0.180	2. 2	0.2500	34.47
3 *R	3.920X	2.000X	0.120/	0.180	2. 2	0.2813	38.33
DECK NO	.3	2 0001	o 1357	A 199	1 7	0.000	37 13
1 *R	3.002X	2.0000	0.125/	0.188	$\frac{1}{2}$	0.2500	37.12
2 * K	3.9208	2.000	0.120/	0.180	1. 2 2. 2 2. 2	0.2300	37.31
NOTE	: *R STAND	S FOR ROL	LED SHAPE	0.100	2. 2	0.2015	57131
SEGMENT	PROPERTIE	S					
-		PROP	ERTIES OF	STIFFENE	D PLATES		
-	AREA-	N	.A. TO	SEC	MOD		SMEAR
	TOTAL	SHEAR	PLATE	PLATE	MOD FLANGE IN3	WT/FT	RATIO
		IN2	IN	INS	5 IN3	LBF/FI	
DECK NO	7.71	0.42	0.26	13.28	1.56	26.18	0.11
1 2	7.46	0.43 0.64	0.36 0.60	22.89		25.35	0.11
3	9.16	0.65	0.53	26,72		31.10	0.12
DECK NO				/-			
1	10.03	0.43	0.31	15.97	1.56	34.06	0.08
2	9.50	0.52	0.41	22.01		32.26	0.10
3	11.66	0.53	0.37	24.70	2.28	39.60	0.08
DECK NO						74 65	0
1	10.03	0.43	0.31	15.97		34.06	0.08
2	9.50	0.52	0.41	22.01		32.26 38.63	$0.10 \\ 0.08$
3	11.38	0.53	0.38	24.20	2.20	30.03	0.00

# PRINTED REPORT NO. 8 - STRENGTH AND STRESS OF STIFFENED PLATE AT DESIGN LOAD

SEG	-PRIMARY	CTRESS_		STRESS-		-STRENGTH-	
JLU	TENSION	COMP.	BEND.	SHEAR	BUCKL.	ULTIMATE	COLUMN
	KSI	KSI	KSI	KSI	KSI	KSI	KSI
WET D		NJI	KU1	NO1		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
1	13.10	10,92	11.62	4,21	14.87	35,67	32.39
2	13.10	10,92	9.44	3.40	14.62	35.41	44.06
3	13.10	10.92	11.09	3.34	21.96	42.01	31.59
SIDE							
1	12.17	10.15	10.05	3.03	21.96	42.01	31.59
2	10.61	8.85	15.64	4.71	18.05	38.73	33.71
3	8,59	7.16	24,73	8.93	9.76	29.69	39.05
4	6.71	5.91	34.32	12.96	10.10	30.15	40.63
BOT S							
1	7.54	8.27	32.78	16.66	10.79	31.03	48.94
2	7.90	9.31	28.89	8.65	63.82	64.00	45.34
3	7.94	9.42	34.79	13.14	27.81	46.20	47.08
4	8.15	10.02	30.33	11.39	32.31	48.99	53.81
5	8.23	10.25	29.36	14.95	30.86	48.13	50.33
6	8.16	10.03	32.57	11.69	29.47	47.27	51.46
INNER	BOT						
1	7.42	7.93	50.15	18.11	12.34	32.92	37.87
2	7.77	8.93	28.32	8.42	32.05	48.84	52.95
3	7.77	8.93	52.61	19.05	14.19	34.96	31.71
4	7.77	8.93	47.68	14.50	30,06	47.64	24.93
5	7.77	8.93	48.65	14.96	31.29	48.38	20.69
6	7.77	8.93	36.75	11.08	25.43	44.58	33.61
INT D	ECK						
NO. 1							
1	9.99	8.33	38.93	11.75	8.63	28.11	35.00
Ž	9,99	8.33	23.02	8.60	10.00	30.02	61.63
3	9,99	8.33	29.43	11.02	10.07	30.11	58.24
INT D	DECK						
NO. 2							
1	0.00	0.00	51.76	15.66	4.85	21.64	27.50
2	0.00	0.00	39.05	14.09	5.63	23.16	46.88
3	0.00	0.00	49.54	17.90	5.76	23.42	41.98
INT	DECK						
NO. 3							
1	0.00	0.00	51.76	15.66	4.85	21.64	27.50
Ż	0.00	0.00	39.05	14.09	5.63	23.16	46.88
3	0.00	0.00	48.23	17.42	6.08	24.00	42.64
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## PRINTED REPORT NO. 9 - FACTOR OF SAFETY OF STIFFENED PLATE AT DESIGN LOAD

SEG         BUCKLING         SHEAR         COMP+BEND         ULTIMATE         TENSION+BEND.           1         1.30         7.84         1.40         1.01         2.22           2         1.28         9.70         1.85         1.37         2.44           3         1.89         9.87         1.39         1.14         2.27           SIDE         SHELL         1         2.04         10.89         1.51         1.23         2.48           2         1.84         7.00         1.48         1.33         2.09         3           3         1.17         3.70         1.38         1.39         1.65           4         1.39         2.55         1.19         1.69         1.34           BOT SHELL         1         1.11         1.98         1.18         1.56         1.36           2         5.39         3.81         1.20         2.45         1.49         3           3         2.62         2.21         1.19         2.06         1.46           6         2.42         2.82         1.13         1.99         1.35           INNER BOT         1         1.58         3.92         1.94 <td< th=""><th></th><th>PLATE-</th><th>-STIFFENER-</th><th>ST</th><th>IFFENED PL</th><th>ATE</th></td<>		PLATE-	-STIFFENER-	ST	IFFENED PL	ATE
WET DECK 1 1.30 7.84 1.40 1.01 2.22 2 1.28 9.70 1.85 1.37 2.44 3 1.89 9.87 1.39 1.14 2.27 SIDE SHELL 1 2.04 10.89 1.51 1.23 2.48 2 1.84 7.00 1.48 1.33 2.09 3 1.17 3.70 1.38 1.39 1.65 4 1.39 2.55 1.19 1.69 1.34 BOT SHELL 1 1.11 1.98 1.18 1.56 1.36 2 5.39 3.81 1.20 2.45 1.49 3 2.51 2.51 1.07 1.97 1.29 4 2.78 2.90 1.21 2.27 1.43 5 2.62 2.21 1.19 2.06 1.46 6 2.42 2.82 1.13 1.99 1.35 INNER BOT 1 5.14 1.82 1.10 5.19 1.10 2 9.85 3.92 1.94 7.95 1.94 3 5.82 1.73 1.05 4.55 1.05 4 10.68 2.28 1.15 4.22 1.15 5 11.09 2.21 1.13 3.55 1.13 6 10.80 2.98 1.50 6.36 1.50 INT DECK NO. 1 1 3.68 2.81 1.41 4.20 1.41 2 1.02 3.84 1.70 1.89 1.67 3 1.01 2.99 1.40 1.76 1.40 INT DECK NO. 2 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	SEG	BUCKLING	SHEAR	COMP+BEND	ULTIMATE	TENSION+BEND.
2 1.28 9.70 1.85 1.37 2.44 3 1.89 9.87 1.39 1.14 2.27 SIDE SHELL 1 2.04 10.89 1.51 1.23 2.48 2 1.84 7.00 1.48 1.33 2.09 3 1.17 3.70 1.38 1.39 1.65 4 1.39 2.55 1.19 1.69 1.34 BOT SHELL 1 1.11 1.98 1.18 1.56 1.36 2 5.39 3.81 1.20 2.45 1.49 3 2.51 2.51 1.07 1.97 1.29 4 2.78 2.90 1.21 2.27 1.43 5 2.62 2.21 1.19 2.06 1.46 6 2.42 2.82 1.13 1.99 1.35 INNER BOT 1 5.14 1.82 1.10 5.19 1.10 2 9.85 3.92 1.94 7.95 1.94 3 5.82 1.73 1.05 4.55 1.05 4 10.68 2.28 1.15 4.22 1.15 5 11.09 2.21 1.13 3.55 1.13 6 10.80 2.98 1.50 6.36 1.50 INT DECK NO. 1 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	WET DEC	ΪK				
2 1.28 9.70 1.85 1.37 2.44 3 1.89 9.87 1.39 1.14 2.27 SIDE SHELL 1 2.04 10.89 1.51 1.23 2.48 2 1.84 7.00 1.48 1.33 2.09 3 1.17 3.70 1.38 1.39 1.65 4 1.39 2.55 1.19 1.69 1.34 BOT SHELL 1 1.11 1.98 1.18 1.56 1.36 2 5.39 3.81 1.20 2.45 1.49 3 2.51 2.51 1.07 1.97 1.29 4 2.78 2.90 1.21 2.27 1.43 5 2.62 2.21 1.19 2.06 1.46 6 2.42 2.82 1.13 1.99 1.35 INNER BOT 1 5.14 1.82 1.10 5.19 1.10 2 9.85 3.92 1.94 7.95 1.94 3 5.82 1.73 1.05 4.55 1.05 4 10.68 2.28 1.15 4.22 1.15 5 11.09 2.21 1.13 3.55 1.13 6 10.80 2.98 1.50 6.36 1.50 INT DECK NO. 1 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41		1.30	7.84	1.40	1.01	2.22
SIDE SHELL         1       2.04       10.89       1.51       1.23       2.48         2       1.84       7.00       1.48       1.33       2.09         3       1.17       3.70       1.48       1.33       2.09         3       1.17       3.70       1.48       1.39       1.65         4       1.39       2.55       1.19       1.69       1.34         BOT SHELL	2		9.70		1.37	2.44
1       2.04       10.89       1.51       1.23       2.48         2       1.84       7.00       1.48       1.33       2.09         3       1.17       3.70       1.38       1.39       1.65         4       1.39       2.55       1.19       1.69       1.34         BOT SHELL       1       1.11       1.98       1.18       1.56       1.36         2       5.39       3.81       1.20       2.45       1.49         3       2.51       1.07       1.97       1.29         4       2.78       2.90       1.21       2.27       1.43         5       2.62       2.21       1.19       2.06       1.46         6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1	3	1.89	9.87	1.39	1.14	2.27
2       1.84       7.00       1.48       1.33       2.09         3       1.17       3.70       1.38       1.39       1.65         4       1.39       2.55       1.19       1.69       1.34         BOT SHELL	SIDE SH	ELL				
3       1.17       3.70       1.38       1.39       1.65         4       1.39       2.55       1.19       1.69       1.34         BOT SHELL       1       1.11       1.98       1.18       1.56       1.36         2       5.39       3.81       1.20       2.45       1.49         3       2.51       1.07       1.97       1.29         4       2.78       2.90       1.21       2.27       1.43         5       2.62       2.21       1.19       2.06       1.46         6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       5.14       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       1       1.87       2.11       <	1	2.04	10.89	1.51		2.48
4       1.39       2.55       1.19       1.69       1.34         BOT SHELL       1       1.11       1.98       1.18       1.56       1.36         2       5.39       3.81       1.20       2.45       1.49         3       2.51       2.07       1.43       1.29         4       2.78       2.90       1.21       2.27       1.43         5       2.62       2.21       1.19       2.06       1.46         6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       5       1.42       1.10       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       NO. 1       1       1.67       1.40       1.41         1       3.68       2.81       1.41       4.20 <td< td=""><td></td><td>1.84</td><td>7,00</td><td>1.48</td><td>1.33</td><td>2.09</td></td<>		1.84	7,00	1.48	1.33	2.09
BOT SHELL       1       1.11       1.98       1.18       1.56       1.36         1       1.11       1.98       1.18       1.56       1.36         2       5.39       3.81       1.20       2.45       1.49         3       2.51       2.51       1.07       1.97       1.29         4       2.78       2.90       1.21       2.27       1.43         5       2.62       2.21       1.19       2.06       1.46         6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       5.14       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.30         6       10.80       2.98       1.50       6.36       1.50         INT DECK       NO. 1       1       1.41       4.20       1.41         NO. 2       1       1.87		1.17	3.70	1.38		1,65
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	4	1.39	2.55	1.19	1.69	1,34
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	BOT SHE	LL				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$			1.98	1.18	1.56	1.36
$\begin{array}{cccccccccccccccccccccccccccccccccccc$				1.20		1.49
5       2.62       2.21       1.19       2.06       1.46         6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       5.14       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       NO. 1       1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK       NO. 2       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41         INT DECK       NO. 3       1       1.87       2.11       1.06       2.29 <td></td> <td></td> <td></td> <td></td> <td></td> <td>1.29</td>						1.29
6       2.42       2.82       1.13       1.99       1.35         INNER BOT       1       5.14       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41         3       2.46       1.84       1.11       4.19       1.11         INT DECK       1       1.87       2.11       1.06       2.29       1.06         2					2.27	1.43
INNER BOT       1       5.14       1.82       1.10       5.19       1.10         2       9.85       3.92       1.94       7.95       1.94         3       5.82       1.73       1.05       4.55       1.05         4       10.68       2.28       1.15       4.22       1.15         5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       NO. 1       1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK       NO. 2       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41       1.11         INT DECK       NO. 3       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41		2.62	2.21		2.06	1,46
$\begin{array}{cccccccccccccccccccccccccccccccccccc$			2.82	1.13	1.99	1,35
$\begin{array}{cccccccccccccccccccccccccccccccccccc$						
$\begin{array}{cccccccccccccccccccccccccccccccccccc$				1.10	5.19	1.10
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	2	9.85	3.92	1.94	7.95	1,94
5       11.09       2.21       1.13       3.55       1.13         6       10.80       2.98       1.50       6.36       1.50         INT DECK       1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41         3       2.46       1.84       1.11       4.19       1.11         INT DECK       1       1.87       2.11       1.06       2.29       1.06         NO. 3       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41	3	5.82	1.73	1.05	4.55	1.05
6       10.80       2.98       1.50       6.36       1.50         INT DECK       1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41         3       2.46       1.84       1.11       4.19       1.11         INT DECK       1       1.87       2.11       1.06       2.29       1.06         NO. 3       1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41		10.68			4.22	1,15
INT DECK NO. 1 1 3.68 2.81 1.41 4.20 1.41 2 1.02 3.84 1.70 1.89 1.67 3 1.01 2.99 1.40 1.76 1.40 INT DECK NO. 2 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41 3 2.46 1.84 1.11 4.19 1.11 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	5	11.09	2.21	1.13	3.55	1.13
NO. 1 1 3.68 2.81 1.41 4.20 1.41 2 1.02 3.84 1.70 1.89 1.67 3 1.01 2.99 1.40 1.76 1.40 INT DECK NO. 2 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 4.19 1.11 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	6	10.80	2.98	1.50	6.36	1.50
1       3.68       2.81       1.41       4.20       1.41         2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK	INT DEC	.K				
2       1.02       3.84       1.70       1.89       1.67         3       1.01       2.99       1.40       1.76       1.40         INT DECK	NO. 1					
3       1.01       2.99       1.40       1.76       1.40         INT DECK			2.81	1.41	4.20	1,41
3       1.01       2.99       1.40       1.76       1.40         INT DECK	2	1.02	3.84	1.70	1.89	1.67
INT DECK NO. 2 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41 3 2.46 1.84 1.11 4.19 1.11 INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	3	1.01	2,99	1.40	1.76	1.40
1       1.87       2.11       1.06       2.29       1.06         2       2.73       2.34       1.41       5.27       1.41         3       2.46       1.84       1.11       4.19       1.11         INT DECK	INT DEC					
2       2.73       2.34       1.41       5.27       1.41         3       2.46       1.84       1.11       4.19       1.11         INT DECK	NO. 2					
3       2.46       1.84       1.11       4.19       1.11         INT DECK	1	1.87	2.11	1.06	2.29	1.06
INT DECK NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	2	2.73	2.34	1.41	5.27	1.41
NO. 3 1 1.87 2.11 1.06 2.29 1.06 2 2.73 2.34 1.41 5.27 1.41	3	2.46	1.84	1.11	4.19	1.11
1         1.87         2.11         1.06         2.29         1.06           2         2.73         2.34         1.41         5.27         1.41	INT DEC					
2 2.73 2.34 1.41 5.27 1.41	NO. 3					
2 2.73 2.34 1.41 5.27 1.41	1	1.87	2.11	1.06	2.29	1,06
		2.62	1.89	1.14	4.40	1.14

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# PRINTED REPORT NO. 10 - GIRDER PROPERTIES, STRENGTH , STRESSES AND FACTOR OF SAFETY BOT MTRL TYPE-HY 80

DECK MTRL TYPE-HY 80

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	STIFF., POS								INT DECK GIRDER	<b>4</b> .						
WET DECK	CO	VLOC	FT ZLOC		LOAD, F HEAD				2	30.53 29.73 30.11	1.18 1.36 2.39	0.56 0.66 0.75		83 13	.59 103. .69 100. .74 102.	95 0.11
1 2 3 INT DECK		9.28	36.51 26.51 36.51	8.56 8.40 8.40					GIRDER 1 2	19.53 19.03	10.55	15.34 14.62	177.	21 177	.21 64.	64 0.00
GIRDER 1 2		0.00	26.50 26.50	2.76	8.87 13.51				4 5 6	26.28 25.26 9.10 7.56	11.73 10.71 4.42 2.88	13.41 12.24 8.98 5.71	67.	.56 215 .07 53		79 0.00 89 0.00
INT DECK GIRDER 1	2.		26.50	2.76	17.82				BOTTOM STIFF. 1 2	5.91 5.91	0.44 0.44	0.49 0.49	9.	.98 1	.59 20. .59 20.	06 0.15
2 3 INT DECK GIRDER	( 3.	9.28 17.90	17.50 17.50	2.76	21.31 25.62				3 4 5 6	7.31 7.31 4.03 4.03	0.45 0.45 0.43 0.43	0.48 0.48 0.56 0.56	10. 7.	.85 1 .80 1	.64 24. .64 24. .53 13. .53 13.	83 0.11 69 0.23
1 2		0.00 9.28 17.90	10.00 10.00 10.00	2.76 2.76 2.76	23.16						STI	RENGTH A			. ST F	
BOTTOM		17.90	10.00	2.70	52.1	•				RIMARY S		+LOCAI BEND,	AT DESIN		-STRENGTH-	COLUMN
1 2		0.00 3.72	0.00	0.29	40.51 40.39	;			WET DECI	KSI	KSI	KSI	KSI	KSI	KSI	KSI
3		8.59 12.94	0.34	0.37 0.37	40.17				GIRDER	13.10	10.92	22.02	7.94	64.60	64.62	29,90
S 6 BOTTOM STIFF.		19.27 21.38	0.86 1.45	0.29 0.29	40.58 41.13					13.10 13.10 ( 1.	10.92 10.92	21.08 21,50	7.51 7.75	64.60 64.60	64.62 64.62	37.42 36.87
1 2 3		0.00 3.72 8.59	1.25 1.31 1.42	0.29 0.29 0.37	39.20 39.20 39.09	1			1 2	9,99 9,99 9,99	8.33 8.33 8.39	48.71 49.81 54.10	11.48 12.56 19.55	75.34 64,89 71.10	76.75 64.85 70.88	17.44 34.54 35.36
4 5 6		12.94 19.27 21.38	1.52 1.68 1.98	0.37 0.19 0.19	38.99 39.70 40.50	i			3 INT DECI GIRDER 1	(2. 0.00	0.00	51.35	18.56	71.10	70.88	34,95
-			NTLINGS OF					-	2 3 INT DECI	0.00	0.00	54.15 54.67	19,55	64.60 70.89	64.62 70.63	45.02
SUPPORT		IRDER/ST			CATLO			•	GIRDER	0.00	0.00	50.40	25.40	70.89	70.63	44,58
WET DECK GIRDER		-++1NX1N	KIN/IN		NÜ	ικ, <u>τ</u> κ	IN IN		2 3 BOTTOM	0.00	0.00	49.38 53.12	25.51 16.81	64,60 68.07	64.62 67,67	52.90 59.40
1 *R 2 *R	6.990X	3.000X			17,	0.3438		99	GTRNER 1	8.00	9.60	2.01	1.85	56.22	59.92	80.00
3 * R INT DECK GIRDER		3.000X	0.180/	Q.310	17.	0.3438	109.9	4	2 3 4	7.99	9.57	2.78	2.51	61.01 74.01	61.93 74.69	80.00 80.00
1 *R	4.990X 6.950X	2.000X		0.310 0.250	9. 11.	0.2500			5 6	7.95 7.92 7.87	9.46 9.37 9.21	2.36 7.63 8.20	2.43 4.75 4.50	75.79 53.15 74.63	77.49 58.78 75.64	80.00 80.00 80.00
J R INT DECK GIRDER	5.950X	4.000X	0.100/	0.250	15.	0.2500		'1	STIFF.	7.89	9.27	31.76	9.53	77.31		43.26
1 *R	5.950X 6.990X	4.000X 3.000X	0.180/ 0.180/	0.250 0.310		0.2500			2 3	7.88	9.25	31.71 30,61	9.51 9.24	77.31 77.31	80.00	43.26 39.00
INT DECK	5.990X (3.	5.000X	0.180/	0.310		0.2500		21	4 5	7.86 7.85	9.19 9.15	30.53 33.51	9.22 10.00	77.31 77.31	80.00 80.00	39.00 50.37
GIRDER 1 * R 2 * R	5.990X 6.990X	5.000X	0.180/ 0.180/	0.310		0.2500			6	/.8Z	9.07	34.18	10,20 D OF SAFE	77.31	80.00	50.37
3 *R BOTTOM		3.000X		0.310		0.2500							AT DESIG	IN LOAD	ATE	
GIRDER 1	30.000X	13.408X	0.344/	0.344		0.3438	: 41.4	13		BUCKLIN					TENSION+	
2	28.547X 25.940X	13.408X 17.063X	0.344/ 0.438/	0.344 0.438		0.3438	53.1 58.3	14 10	GIRDER 1 2	5.56			1.06	1.66	1.57	,
4 5 6 BOTTOM	23.614X 19.636X 12.594X	17.063X 8.533X 8.533X	0.219/	0.438 0.219 0.219		0.4375 0.3438 0.3438			Z 3 INT DECI GIRDER	5.55 5.55 (1.			1.22 1.20	2.08	1.61	
STIFF. 1 *R		2.000X		0.188		0.3438		00	1 2	49.66 42.78	2.	87 63	1.13 1.10	8.87 14.77	$1.1^{\circ}$ 1.10	
2 4 R 3 4 R 4 4 R		2.000X 2.000X		0.188	1	0.4375	5 15.0	00	3 INT DECI	34.04 (2.	1.	69	1.02	12.00	1.02	2
5 * R 6 * R	3.002X	2.000X 2.000X 2.000X 2.000X 5 FOR ROI	0.125/ 0.125/ 0.125/ LLED SHAPE	0.198 0.188 0.188	1. 1. 1.	0.2188	15.0		GIRDER 1 2 3 INT DECI	36.25 31.33 26.65	1.	69	1.07 1.02 1.01	12.63 14.11 11.96	1.07	2
			PERTIES OF					SMEAR	GIRDER	29.36	1.	20	1.09	13.04	1.09	,
WET DECK	TOTAL IN2		PLATE	PLATE	. FLAP	IGE V	/T/FT .BF/FT	RATIO	2 3 BOTTOM	25.59 25.59 29.16	1.	29	1.11 1.04	14.07	1.11	L
		1.39 1.38	0.45 0.47	158.96 148.13			73.08	0.05	GIRDER 1 2	54.37 42.76			27.32 19.80	46.36 34.73	27.31 19.80	
3 INT DECK	39.91 ( 1.	1.38	0.46	150.03			35.53	0.06	3	65.55	14.	24	25.02 23.31	52.93 51.16	25.02	2
GIRDER 1	29.40	1.00	0.32	75.70			99.84	0.06	5	16.95 23.11	6.	94	7.21 6.71	15.00	7.21	L
3	28.00	1.34 1.16	0.42 0.45	111.20 108.81			97.52 00.37	0.07 0.08	STIFF.	29.75	7	46	1 73	12 27		
INT DECK GIRDER 1	29.97	1.16	0.45	110.00		18 1	01.77	0.08	1 2 3	29.75 29.79 32.48	э.	47	1.73 1.73 1.80	13.32 13.34 13.11	1.71	1
2	29.97 29.10 29.99	1.36	0.52 0.57	128.98	9.	57	98.81 01.85	0.08	4	32.56 22.98	э.	58 30	1.80 1.64	13.14 11.98	1.80 1.80 1.64	) 1
-									6	22.52	3.		1.61	11.74	1.6	

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#### PRINTED REPORT NO. 11 - LONGITUDINAL BULKHEADS

YIE MAX	G BHD ULUS C ISITY, LD STR PRIMA OWABLE	DF ELAS LBM/FT ENGTH, RY STF	TICIT 3 KSI RENGTH	Y, KST	KSI	29600. 489.0 80.0 23.5 55.0	2 10 2							
TFF	ENER S	PACIN	, IN		MAX 18.00	MIN 24.0								
	GEOMETRY	E COORD,	FT		SCND. L	OAD, FT		BHD NO.S	,					
EG NØ.1 EG	YUPR	ZUPR	YLWR	ZLWR	HEAD1	HEAD2		1 2 3	6.76 9.19 8.38	0.43 0.44 0.52	0.39 0.36 0.44	12.01 13.98 19.92	1.55 1.59 2.26	31.21
1	25.61 25.61	36.51 26.50	25.61 25.61	26.50 17.50	21.42 29.21			BHD NO.4 SEG		0.32	0.44	13.32	2.20	20,10
NO.2	25.61	17.50	25.61	10.00	35.71			1 2	6.76 9.19	0.43	0.39 0.36	12.01 13.98	1.59	31,21
G	25.61	36.51	25.61	26.50	21.42			3 BHD NO.5	8.38	0.52	0.44	19.92	2.26	28,46
10.3	25.61 25.61	26.50 17.50	25.61 25.61	17.50 10.00	29.21 35.71			5EG	6.76 9.19	0.43	0.39 0.36	12.01 13.98		
0.2	25.61	36.51	25.61	26.50	21.42			3 ≸HD NO.0	8.38	0.52	0.44	19.92		
	25.61 25.61	26.50 17.50	25.61 25.61	17.50 10.00	29.21 35.71			SEG	6.76	0.43	0.39	12.01	1.55	
10.4	25.61	36.51	25.61	26.50	21.42			2 3	9.19 8.38	0.44 0.52	0.44	13.98 19.92	2.26	
_	25.61 25.61	26.50 17.50	25.61 25.61	17.50 10.00	29.21 35.71					AT D	ESIGN LOAD	)		
ND.5 G	25.61	36.51	25.61	26.50	21.42				LOCAL BEND. KSI	STRESS SHEAR KSI	BUCKL. KSI	ULTIMATE KSI	E COLUMN KSI	
	25.61	26.50	25.61	17.50	29.21			BHD NO.		K31	K31	K31	KJI	
0.6	l.							1 2	28.39 42.67	8.55 12.87	11.59 14.33	32.02 35.11	38.70 30.58	
	25.61 25.61	36.51 26.50	25.61	26.50	21.42			BHD NO.	40.69 2	14.66	7.43	26.29	49.76	
	25.61	17.50	25.61	10.00	95.71			SEG 1 2	28.39 42.67	8.55 12.87	11.59 14.33	32.02 35.11	38.70 30.58	
	SCANTLING		ANTLINGS	OF STIFFE	ED PLATES			BHD NO.	40.69 3	14.66	7.43	26.29	49.76	
VER:		INXINXIN/	TN	OF PLATE	NO STIF	FTK, IN		SEG 1 2	28.39 42.67	8.55 12.87	11.59 14.33	32.02 35.11	38.70 30.58	
к		2.0003	0.125/	0.185	1 4	0.2500	24.02	3 BHD NO.	40.69	14.66	7.43	26.29	49.76	
R R	3.002X 3.920X		0.125/ 0.120/	0.188 0.180	1 3 2 2	0.3125	27.00 30.00	SEG 1 2	28.39	8.55	11.59	32.02	38.70	
2.2								3	42.67	12.87 14.66	14.33 7.43	35.11 26.29	30.58 49,76	
R	3.002X 3.002X 3.920X	2.000X 2.000X 2.000X	0.125/ 0.125/ 0.120/	0.188 0.188 0.180	1 4 1 3 2 2	0.2500 0.3125 0.2500	24.02 27.00 30.00	BHD NO. SEG 1	5 28.39	8.55	11.59	3Z.02	38.70	
5.9		2,0001	0.120/	0.100		0.12.000	30.00	2	42.67 40.69	12.87	14.33 7.43	35.11 26.29	30,58 49,76	
* R	3.002X 3.002X	2.000X 2.000X	0.125/ 0.125/	0.188 0.188	1 4 1 3	0.2500 0.9125	24.02 27.00	BHD NO. SEG	6					
4 R -	3.920X	2.000X	0.120/	0.180	2 2	0.2500	30.00	1 2	28.39 42.67	12.87	11.59 14.33	32.02 35.11	38.70 30.58	
'R 0.4								3	40.69	14.66	7.43	26.29	49.76	
*R 0.4 *R	3.002X		0.125/	0.188	1 4	0.2500	24.02							
*R 10.4 ; *R *R *R	3.002X 3.920X	2.000X	0.125/ 0.125/ 0.120/	0.188 0.188 0.180	1 4 1 3 2 2	0.2500 0.3125 0.2500	24.02 27.00 30.00							
*R 10.4 *R *R *R 10.5	3.002X 3.920X	2.000X 2.000X	0.125/ 0.120/	0.188 0.180 0.188	1 3 2 2 1 4	0.3125 0.2500	27.00 30.00 24.02		PLATE- BUCKLING	-STIFFENE	AT DES	SIGN LOAD	D NED PLATE	
*R 0.4 *R *R *R 0.5	3.002X 3.920X 3.002X 3.002X 3.920X	2.000X 2.000X	0.125/ 0.120/	0.188 0.180 0.188 0.188	1 3 2 2	0.3125 0.2500	27.00 30.00	6HD NO. 1	PLATE- BUCKLING 1 SEG 6.14	-STIFFENE SHEAR 3.86	AT DES R COMP+BE	SION LOAD STIFFEN END ULT:	D NED PLATE IMATE TEM 6.57	NSION+BEND 1.94
*R 4 G *R *R *R *R G *R *R G *R *R *R *R 6 *R *R 6 0 0 0	3.002X 3.920X 9.002X 3.002X 3.920X	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/	0,188 0,180 0,188 0,188 0,188	1 3 2 2 1 4 1 3 2 2	0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00	6HD NO. 1 2 3	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14	-STIFFENE SHEAR	AT DES R COMP+BE	SION LOAD STIFFEN END ULT 4 ( 9 2	D NED PLATE IMATE TE	NSION+BEND
*R 4 G *R *R *R *R G *R *R G *R *R *R *R 6 *R *R 6 0 0 0	3.002X 3.920X 9.002X 3.002X 3.920X	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/	0,188 0,180 0,188 0,188 0,188	1 3 2 2 1 4 1 3 2 2	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125	27.00 30.00 24.02 27.00	6HD NO. 1 2 3	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG	-STIFFENE SHEAR 3.86 2.56 2.25 3.86	AT DES R COMP+BE 1.94 1.29 1.31 1.94	SIGN LOAD STIFFEN END ULT 4 6 2 2 5 9 4 0	D NED PLATE IMATE TE 6.57 4.32 5.53 6.57	NSION+BEND 1.94 1.29
*R.4 NO. * * * NO. * * NO. * * * NO. * R R S. & R R S. & R R R S. & R R R S. & R R R S. & * * * NO. * * * * NO. * *	3.002X 3.920X 9.002X 3.002X 3.920X	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.125/	0.138 0.180 0.188 0.183 0.183 0.180 0.188 0.188	1 3 2 2 1 4 1 3 2 2	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00	8HD NO, 1 2 3 8HD NO. 1 2 3	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG 6.14	-STIFFENE SHEAR 3.86 2.56 2.25	AT DES R- COMP+BE 1.94 1.29 1.31 1.94 1.29 1.32	SICN LOAD Stiffen End Ulti 4 ( 9 2 5 ! 4 ( 9 2	D NED PLATE IMATE TE 6.57 4.32 5.53	NSION+BEND 1,94 1,29 1,35 1,94 1,29 1,35
*R G *R *R *R G *R *R G *R *R G *R *R OTE: ENT	3.002X 3.920X 3.002X 3.002X 3.920X 3.920X 3.002X 3.002X 3.920X 3.920X 3.920X 3.920X 3.920X 3.920X	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.125/ 0.125/ 0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.125/ 0.125/	0.188 0.180 0.183 0.185 0.185 0.188 0.188 0.188 0.188	1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00	8HD NO. 1 3 8HD NO. 1 2 3 8HD NO. 1 2	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG 6.14 5.77 3.14 3 SEG 6.14 5.77	-STIFFENE SHEAR 3.86 2.56 2.25 3.86 2.25 3.86 2.25 3.86 2.56	AT DES R- COMP+BE 1.24 1.32 1.32 1.94 1.27 1.32 1.94 1.29 1.29 1.29	SIGN LOAD STIFFEN END ULT 4 6 9 2 5 9 4 0 5 9 5 9 4 0 9 4	D NED PLATE: IMATE TEP 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32	NSION+BEND 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.29
*R NO.4 G *R *R *R NO.5 G *R *R NO.6 *R *R NO.6 *R *R NO.5 *R *R *R NO.5 *R *R *R *R *R *R *R *R *R *R	3.002X 3.920X 3.002X 3.002X 3.920X 3.002X 3.002X 3.002X 3.920X *R STANE PROPERTIE	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/ 0.125/ 0.125/ 0.120/ LED SHAPE	0.188 0.180 0.183 0.183 0.188 0.188 0.188 0.188 0.180 E F STIFFENE	1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 0 PLATES	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00	6HD N0, 2 3 8HO NO. 1 2 9 8HD NO. 1 2 3 8HD NO.	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG 6.14 5.77 3.14 3 SEG 6.14 5.77 3.14 4 SEG	-STIFFENE SHEAR 3.86 2.56 2.25 3.86 2.25 3.86 2.25 3.86 2.25	AT DES R- COMP+BE 1.94 1.25 1.94 1.35 1.94 1.25 1.2	SICN LOAU STIFFEN END ULT3 4 6 9 2 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1	D NED PLATE IMATE TE/ 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53	NSION+BEND 1.94 1.29 1.35 1.94 1.99 1.35 1.94 1.29 1.35 1.94 1.29 1.35
*R NO.4 S *R *R NO.5 *R *R *R *R *R *R *R *R * * * * * * * * * * * * *	3.002X 3.920X 3.002X 3.002X 3.002X 3.920X 5 3.002X 3.920X 5 5 7.002X 3.920X 5 7.002X 3.920X 5 7.002X 3.920X 7.002X 3.920X	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/ LED SHAPE	0.188 0.180 0.183 0.183 0.188 0.188 0.188 0.188 0.180 E F STIFFENE	1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 D PLATES	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00	8HD N0, 1 2 3 8HD N0, 1 2 3 8HD N0, 1 2 3 8HD N0, 1 2	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG 6.14 5.77 3.14 3 SEG 6.14 5.77 3.14 4 SEG 6.14 5.77	-STIFFENI SHEAR 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25	AT DES R- COMP+BE 1.94 1.22 1.32 1.94 1.94 1.22 1.3	SICN LOAC STIFFEN END ULT 4 6 9 2 5 1 4 1 9 4 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1 5 1	D NED PLATE: IMATE TER 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32	1,29 1,35 1,94 1,29 1,35 1,94 1,29 1,35 1,94 1,29
NO.6 EG 1 *R 2 *R 9 *R NOTE: MENT	3.002X 3.920X 3.920X 3.002X 3.002X 3.920X 3.920X 3.920X 3.920X 3.920X 4.875AND PROPERTIN TOTAL IN2	2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X 2.000X	0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/ 0.125/ 0.120/ LED SHAPI LED SHAPI LED SHAPI I.A. TO PLATE IN	0.188 0.180 0.180 0.188 0.188 0.180 0.180 0.180 0.180 F STIFFENE F STIFFENE F STIFFENE F STIFFENE TN3	1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 D PLATES FLANGE IN3	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00	6HD NO. 1 2 3 8HD NO. 1 2 3 8HD NO. 1 2 3 8HD NO. 1 2 3 8HD NO. 1 2 3 8HD NO. 1 2 3 8HD NO. 1 2 3 8 8 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 1 2 3 8 8 1 8 1 1 2 3 8 8 1 8 1 8 1 2 3 8 8 1 8 1 8 1 8 8 8 1 8 1 8 8 8 8 8 8 8 8 8 8 8 8 8	PLATE- BUCKLING 1 SEG 6.14 5.77 3.14 2 SEG 6.14 5.77 3.14 3 SEG 6.14 5.77 3.14 4 SEG 6.14 5.77 3.14	-STIFFEN SHEAR 3.86 2.56 2.25 3.86 2.25 3.86 2.56 2.55 2.25	AT DES R- COMP+BE 1.94 1.25 1.31 1.94 1.27 1.31 1.94 1.21 1.31 1.94 1.22 1.33 1.94 1.23 1.35 1.3	SICN LOAK STIFFER END ULT 4 6 9 4 5 9 4 1 9 4 5 9 4 1 9 4 5 9 4 1 9 4 5 9 5 9 5 9 5 9 5 9 5 9 5 9 5 9 5 9 5 9	D NED PLATE: IMATE TEP 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53	NSION+BEND 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35
* R           NO.4           C           L * R           3 * R           NO.5           C           L * R           3 * R           NO.5           C           L * R           NO.5           C           L * R           NO.6           C           L * R           NO.6           C           NO.6           C           NO.1           EG           L * R           NO.6           C           NO.6           C           NO.1           EG           L * R           S * R           NO.1           EG           L * R           S * R      NO.1	3.002X 3.920X 3.920X 3.002X 3.920X 3.920X 3.920X 3.920X 3.920X 3.920X 4.920X 3.920X 4.	2.000X 2.	0.125/ 0.120/ 0.125/ 0.125/ 0.125/ 0.120/ 0.125/ 0.120/ 0.125/ 0.120/ PERTIES 01 1.A. TO PLATE IN 0.39 0.36	0.188 0.180 0.180 0.188 0.180 0.188 0.180 0.188 0.180 E F STIFFENE 	1 3 2 2 1 4 1 3 2 2 1 4 1 5 2 2 1 4 1 5 2 2 D PLATES FLANGE TN3 1.55 1.59	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.3125 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00	8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2	PLATE- BUCKLING 6.14 2.5EG 6.14 2.5EG 6.14 3.5EG 6.14 5.77 3.14 4.5.77 3.14 5.56 6.14 5.77 5.14 5.577	-STIFFENI SHEAR 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25	AT DES R- COMP+BI 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.35 1.94 1.25 1.35 1.94 1.25 1.35 1.94 1.25 1.35 1.94 1.25 1.35 1.94 1.25 1.35 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.35 1.94 1.25 1.35 1.35 1.25 1.35 1.35 1.25 1.35 1.35 1.35 1.25 1.35 1.35 1.25 1.3	STON LOAG STIFFEN ND ULT 4 6 9 2 5 9 4 1 9 2 5 9 4 1 9 4 5 9 4 1 9 4 5 9 4 1 9 4 4 1 9 4 4 1 9 4 4 1 9 4 9 4 9 4 9 4 9 4 9 4 9 4 9 4 9 4 9 4	D NED PLATE: IMATE TER 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32	NSION+BEND 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29
*R 4 NO.4 *R 5 *R 5 *R 5 *R 5 *R 5 *R 5 *R 5 *R 5	3.002X 3.920X 3.	2.000X 2.00X 2.0	0.125/ 0.120/ 0.125/ 0.	0.188 0.180 0.180 0.183 0.180 0.180 0.188 0.180 0.188 0.180 E F STIFFEME F STIFFEME F STIFFEME F STIFFEME 12.01 13.98	1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 1 4 1 3 2 2 0 PLATES	0.3125 0.2500 0.3125 0.2500 0.3125 0.2500 0.3125 0.3125 0.3125 0.2500	27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00 24.02 27.00 30.00 30.00	8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2 3 8HD N0. 1 2	PLATE- BUCKLING 6.14 5.77 3.14 2 SEG 6.14 5.77 3.14 4 SEC 6.14 5.77 3.14 4 SEC 6.14 5.77 3.14 5 SEG 6.14 5.77 3.14 5 SEG 6.14 5.77 5.77 5.77 5.77 5.77 5.77 5.77 5.7	-STIFFENI SHEAR 3.86 2.56 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.25 3.86 2.56	AT DES R- COMP+BI 1.94 1.25 1.31 1.94 1.94 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.25 1.94 1.9	Ston         Load           -Stiffer         -Stiffer           -Stiffer         -Stiffer           4         6           2         -           4         1           2         -           4         1           2         -           4         1           2         -           4         1           2         -           4         1           2         -           4         1           2         -           4         1           3         -           4         1           3         -           4         1           9         -           4         1           9         -           4         1           9         -           4         1           9         -           4         1	D NED PLATE: TEI 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32 5.53 6.57 4.32	NSION+BEND 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35 1.94 1.29 1.35

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#### PRINTED REPORT NO. 12 - TRANSVERSE BULKHEADS

TRANS BHD MTRL TYP	PE-HY 80				
MODULUS OF ELAS	FICITY, I	KSI	29600.0		
DENSITY, LBM/FT	3		489.02		
YIELD STRENGTH,	KSI		80.00		
MAX PRIMARY STR	ENGTH, K	SI	23.52		
ALLOWABLE WORKI	NG STREN	GTH, KSI	55.00		
		MAX	MIN		
STIFFENER SPACING	, IN	48.00	24.00		
SEGMENT GEOMETRY	COORD			6 CN 10	40 FT
NODI					
	ZUPR			HEAD1	HEAD2
1 0.00	36.51	0.00	26.50	22.40	

36.51 26.50 17.50 26.50 17.50 10.00 2.50 0.00 0.00 0.00 23 0.00 30.15 36.52 4 0.00 10.00 41.09

SEGMENT SCANTLINGS

		<b>s</b> C/	NTLINGS 0	F STIFF	ENED P	LATES-		
	\$7	TIFFENERS	CATLG	NO.OF	PLATE	SPACING		
SEG	II	NXINXIN/I	[N		NO	STIFF	TK, IN	IN
1 *R	6.950X	3.000X	0.180/	0.250	14	12	0.1875	30.03
2 *R	6.990X	3.000X	0.180/	0.310	17	12	0.1875	27.00
3 * R	6.950X	3.000X	0.180/	0.250	14	9	0.2188	30.00
4 *R	6.990X	3.000X	0.180/	0.310	17	9	0.2188	30.00
NOTE:	*R STANDS	FOR ROLL	ED SHAPE					

SEGMENT PROPERTIES

3.14

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		PF	OPERTIES OF	STIFFENED	PLATES	<b>-</b>	
	ARE	A	N.A. TO	SEC #	10D		SMEAR
	TOTAL	SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO
SEG	INZ	IN2	IN	IN3	IN3	LBF/FT	
1	7.69	1.33	1.40	33.98	7.98	26.12	0.37
2	7.31	1.35	1.66	31.98	9.12	24.84	0.44
3	8.62	1.34	1.28	38.53	8.05	29.28	0.31
4	8.81	1.35	1.41	39.93	9.25	29.93	0.34

		STRENGTH AT DE	AND STR	-		÷
	LOCAL	STRESS		STRENGTH-		_
		SHEAR				
		KSI				
SEG		N0-	NO1		110	-
1	52.61	11.49	7 43	26 29	49 7	6
ź		13.06				
3		15.28				
4		20.11		26.29		
-	51.07	20.11	7.43	20.25		0
				R OF SAFE	TY	
				DESIGN LO		
		-STIFFENER				TE
			-			TENSION+BEND.
SEG	BOCKLING	JICAN				
1	3.14	2.87	1 (	5 5	53	1 35
2		2.53				
3	3.14	2.16		0 5		1.35
	2.14	2.10	1.0	,		1.33

1.00

1.64

5.53

1.35

# PRINTED REPORT NO. 13 - SIDE AND BOTTOM FRAMES

FRAME	SPACING,	, FT		6.00			
SEGMENT	GEOMETRY		FT		COND		
SEG SIDE FR SEG	YUPR	ZUPR	YLWR	ZLWR	HEAD1		
1	27.54	36.51	27.56	26.50	14.01		
2 3	27.56 27.48	26.50 17.50	27.48 27.23	17.50 10.00	23.01		
BOT FRA SEG	Me				30.51		
1	27.23	10.00	21.38	1.45	39.06		
2 3	21.38 19.27	1.45 0.86	19.27 12.94	0,86 0,53	39.65		
4	12.94	0.53	8.59	0.34	39.98 40.17		
Ś	8.59	0.34	3.72	0.12	40.39		
6	3.72	0.12	0.00	0.00	40.51		
SEGMENT	SCANTLIN		CANTLINGS	OF STIFFE	NED PLATE:	S	
		STIFFENE			CATLG	PLATE	SPAN
SIDE FR SEG		-INXINXIN	/IN		NO -	TK, IN	FT
1 *R		5.000X	0.180/			0.3438	10.01
2 *R					31.	0.3125	9.00
3 *R BOT FRA SEG	ME		0.250/	0.370	30.	0.3438	7.50
1	24.000X					0.4375	13.07
2	16.115X		··,			0.3438	2.20
3 4	21.625X 24.777X					0.5000	6.34
5	27.244X					0.4375 0.5625	4.36 4.88
6	29.273X		0.344/			0.3438	3.72
NOTE	: *R STAN	ds for roi					5.72
-			PERTIES O	F STIFFENE	D PLATES-		
-			N.A. TO		MOD		SMEAR
	TOTAL		PLATE	PLATE		WT/FT	RATIO
SEG SIDE FR SEG	IN2 AME	IN2	IN	IN3	IN3	LBF/FT	
1	27.63	1.38	0.75	126.28			0.12
2	25.94	2.65	1.03	163.10			0.15
3 BOT FRA SEG	28.13 ME	2.41	0.91	158.78	16.61	95.54	0.14
1	20.88	9.30	11.89	184.62			0.14
2	8.33	3.65	7.33	\$3.19			0.14
3	25.46 25.77	9.87 11.22	10.84 12.83	213.63 228.27			0.14 0.14
5	34,34	14.15	13.68	353.07			0.14
6	19.28	10.30	14.98	182.94		65.49	0.14
	STRESS A	ND FACTOR	OF SAFET				
	BENDING			SHEAR			
SIDE FR		48. 68					
1	52.33 54.82	19.68 15.08	1.05 1.00	1.68 2.19			
3	52.88	18.33	1.00	1.80			
BOT FRA Seg	ME						
1	34.95	10.60	1.57	3.11			
2 3	3.80 7.26	4.61	14.47	7.15			
4	3.10	4.96 3.01	7.57	6.65 10.95			
3	2.61	2.69		10.95			
6	2.84	2.83		11.68			

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# PRINTED REPORT NO. 14 - DECK BEAMS

FRAME SPACING, FT 6.00

FRAME	SPACIN	KG, FT		6.00	I
SEGMENT					-
	~NC	DE COORD,			SCND. LOAD, FT
SEG	YIB	ZIB	YOB	ZOB	HEADI HEAD2
WET DECK	SE	G			
1	0.00	36.51	9.28	36,51	8.56
2	9.28	36.51	27.54	36.51	8.40
DECK NO.	1 58	c			
1	0.00	26.50	9.28	26,50	2.76
2	9.28	26,50	17.90	26.50	2.76
3	17.90	26.50	27.56	26.50	2.81
DECK NO.	Z 56	<u>с</u>			
1	0.00	17.50	9.28	17.50	2.75
2	9.28	17.50	17.90	17.50	2.76
3	17.90	17,50	27.48	17.50	2.81
DECK NO.	3 SE	6			
1	0.00	10.00	9.28	10.00	2.76
2	9.28	10.00	17.90	10.00	2.76
3	17.90	10.00	27.23	10.00	2.81

SEGMENT S	CANTLINGS						
-		SCA	NTLINGS C	F STIFF	ENED PLA	TES	
	ST	TIFFENERS			CATLG	PL ATF	SPAN
-	I	XINXIN/I	N		NO	TK. IN	FT
WET DECK	SEG						
1 *R	6.950X	2.000X	0.180/	0.250	11.	0.4375	9.28
2 *R	9.930X	5.000X	0.250/	0.370	43.	0.3438	18.26
DECK NO.	1 SEG						
1 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	9.28
2 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	8.62
3 *R	4.920X	2.000X	0.120/	0,180	4.	0.2813	9.67
DECK NO.	2 SEG		,				
1 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	9.28
2 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	8.62
3 *R	4.920X	2.000X	0.120/	0.180	4.	0.2813	9.58
DECK NO.	3 SEG						
1 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	9.28
2 *R	3.920X	2.000X	0.120/	0.180	2.	0.2500	8.62
3 *R	3.920X	2.000X	0.120/	0.180	2.	0.2813	9.33
NOTE:	*R STANDS	FOR ROLL	ED SHAPE				

SEGMEN	T PROPERT						
				OF STIFFENED			
	TOTAL	A	N.A. TU	SEC I	FLANCE	V.F. / F.T.	DATTO
	TOTAL	SHEAK	PLATE	PLATE	FLANGE	WI/FI	RATIO
SEG	IN2	1N2	LN	IN3	183	L84/41	
WET DE	CK S	EG					
1	33.31	1.37	0.48	101.72	6.75	113.12	0,06
2	29,13	2.66	1.28	196.84	26,91	98.94	0.18
DECK N	0. i ş	EU 0 73	A 37	34,93	2 77	64 13	0.05
Ţ	18.88	0.52	0.27	34,93	2.27	04.12	0.05
2	18.88	0.52	0.27	34.93	2.27	64.12	0.05
3	21.25	0.65	0.31	48.39	2.93	72.18	0.05
DECK N	0.25	EG			_		
1	18.88	0.52	0.27	34.03 34.93	2.27	64.12	0.05
2	18.88	0.52	0.27	34.93	2.2/	64.12	0.05
3	21.25	0.65	0.31	48.39	2.93	72.18	0.05
DECK N	0.3 S	EG					
1	18.88	0.52	0.27	34.93	2.27	64.12	0.05
2	18,88	0.52	0.27	34.93	2.27	64.12	0.05
3	21.13	0.53	0.27	34.93 35.24	2.29	71.77	0,04
	STRESS	AND FACTO	DR OF SAFE	TY			
	-STRESS	. KSI-	~F0	S			
	BENDINC	SHEAR	BENDING	SHEAR			
WET DE	CK S	FG					
1	53.95	11.15	1.02	2.96			
			1.00				
DECK N	1 1 SE	с.					
1	51.53	9.47	1,07	3.49			
2	44,45	8.79	1.24	3.75			
3	44.05	8.13	1,25	4.06			
DECK N	0 2 9	FC					
1	51.53	9.47	1.07 1.24	3.49			
2	44.45	8.79	1.24	3.75			
3	43.30	8.05	1.27	4.10			
	10. 3						
SEC							
1	51.53	9.47	1.07	3.49			
5	44.45	8.79	1.24	3.75			
			1.04				

#### PRINTED REPORT NO. 15 - LONGITUDINAL BULKHEAD VERTICAL STIFFENERS

NUMBER OF LONG BHD 6

NUMBER OF LO		0							
FRAME SPACING,	FT		6.00						
SEGMENT CEOMETRY						2 54.27 3 52.41	19.20	1.01	1.72
SEG YUPR ZUPR	D, FT Vive	71 WR	SCND. L	.OAD, FT		3 52.41 LBHD NO.4 SEG	19.63	1.05	1.68
JENDING 1 SEG				INCHUZ		1 20.04	15.73	1.09	2.10
1 25.61 36.51 2 25.61 26.50 3 25.61 17.50	25.61	26.50	21.46 29.31 35,75			2 54.27	19.20	1.09 1.01 1.05	1.72
3 25,61 17,50	25.61	10.00	35,75			LBHD NO.5 SEG			1.00
			31.46			1 50.64 2 54.27	15.73	1.09	2.10
1 25.61 36.51 2 25.61 26.50 3 25.61 17.50	25.61	17.50	29.31				19.20	1.09 1.01 1.05	1.72
9 25.61 17.50	25.61	10.00	35.75			FRUD NO 6 SEC			
						1 50.64 2 54.27 3 52.41	15.73	1.00	2.10
2 25.61 26.50	25.61	17.50	29.31			3 52.41	19.63	1.05	1.68
IRHUNOLA SEC									
1 25.61 35.51 2 25.61 26.50 3 25.61 17.50	25.61	26,50	21.45						
2 25.61 26.50	25.61	17.50	29.31						
LIGHD NO.5 SEG									
1 25.61 36.51 2 25.61 26.50 3 25.61 17.50	25.61	26,50	21.46						
3 25.61 17.50	25.61	10.00	35.75						
LIBHEIND.6 SEG									
1 25.61 36.51 2 25.61 26.50 3 25.61 17.50	25.61	26.50	21,46						
3 25.61 17.50	25.61	10.00	35.75						
SEGMENT SCANTLINGS									
	-SCANTLINGS	OF STIFFE	NED PLATE	s					
STIFFE SEGTNXIN	NERS		CATLG .	PLATE	SPAN				
IRHD NO.1 SEC									
1 * R 9.930X 4.00 2 * R 9.930X 4.00 3 * R 9.990X 4.00 LBHD NO.2 SEG	OX 0.250/	0.370	38.	0.2500	10.01				
3 *R 9,990X 4,00	OX 0.250/	0.310	35.	0.3125	7.50				
LBHD NO.2 SEG									
1 *R 9.930X 4.00 2 *R 9.930X 4.00 3 *R 9.930X 4.00 3 *R 9.990X 4.00	10X 0.250/ 10X 0.250/	0,370	38. 38.	0.2500	10.01				
3 R 9.990X 4.00	OX 0.250/	0,310	35.	0.2500	7.50				
LBHD NO.3 SEG	0,250/	0.370	38.	0.2500	10.01				
1 *R 9.930X 4.00 2 *R 9.930X 4.00 3 *R 9.990X 4.00	OX 0.250/	0.370	38.	0.3125	9.00				
1 *R 9.930X 4.00 2 *R 9.930X 4.00 3 *R 9.930X 4.00 3 *R 9.990X 4.00	0X 0.250/	0.370	38.	0.2500	10.01				
2 * R 9.930X 4.00	OX 0.250/	0.370	38.	0.3125	9,00				
1 *R 9.930X 4.00 2 *R 9.930X 4.00 3 *R 9.990X 4.00	OX 0.250/	0,370	38.	0.2500	10.01				
2 'R 9.930X 4.00 3 'R 9.990X 4.00	10X 0.250/ 10X 0.250/	0,370	38.	0.3125	9.00				
1 R 9.930X 4.00 2 R 9.930X 4.00 3 R 9.990X 4.00	10X 0.250/ 10X 0.250/	0,370	38.	0.2500	10.01				
3 *R 9.990X 4.00	0X 0.250/	0.310	35.	0.2500	7.50				
NOTE: "R STANDS FOR	ROLLED SHAP	E							
SEGMENT PROPERTIES									
TOTAL SHEAR SEG IN2 IN2	N A. TO	F STIFFENEL	D PLATES		SMEAR				
TOTAL SHEAR	PLATE	PLATE	FLANGE	WT/FT	RATIO				
SEG IN2 IN2 LBHD NO.1 SEG	IN	INB	IN3	LBF/FT					
1 22.00 2.64 2 26.50 2.65 3 21.75 2.64	1.40	148.05	22.70	74.71	0.22				
2 26.50 2.65	1.22	176.22	22.92	89.99	0.18				
LBHD NO.2 SEG	1.30	744.10	10.10	, , , , , , , , , , , , , , , , , , , ,	0.21				
LBHD NO.2 SEG 1 22.00 2.64 2 26.50 2.65 3 21.75 2.64	1,40	148.06	22.70	74.71	0.22				
3 21.75 2.64	1.30	144.10	20.28	73.86	D.21				
LIND NO. 3 SEG									
1 22.00 2.54 2 25.50 2.55 3 21.75 2.64	1.40	148.05	22.92	74.71 89.99	0,18				
3 21.75 2.64 LBHD NO.4 SEG	1.30	144.10	20.28	73.86	0.21				
1 22.00 2.64	1.40			74.71	0.22				
2 26.50 2.65 3 21.75 2.64	1.22	176.22	22.92		0.18				
3 21.75 2.64 LBHD NO.5	1,30	144.10	20.28	73.86	0.21				
SEG	• ••								
1 22.00 2.64 2 26.50 2.65	1.40	148.06		74.71 89.99	0.22				
3 21.75 2.64	1,30	144.10		73.86	0.21				
LBHD NO.6 SEC 1 22.00 2.64	1 40	148.00							
7 26.50 2.65	1.40	148.06 176.22	22 97	74.71	0.22				
3 21.75 2.64	1.30	144.10	20.28	73.86	0,21				
STRESS AND FACT	OR OF SAFET	Y							
-STRESS, KSI-	FOS								
BENDING SHEAR LBHD NO.1 SEG	BENDING	SHEAR							
1 50.64 15.72	1.00	2.10							
2 54.27 19.20 3 52.41 19.63	1.01 1.05	1.72 1.68							
LBHD NO.2 SEG									
1 50.64 15.73 Z 54.27 19.20	1.09 1.01	2.10							
3 52.41 19.63	1.01	1.72							
LBHD ND.3 SEG 1 50.64 15.73	1.09	2.10							
2 30.04 13.13	1.03								

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#### PRINTED REPORT NO. 1 - SUMMARY

AVG RUDDER CHORD, FT SKEG THK, FT RUDDER THK, FT SKEG PROJECTED AREA, FT2 RUDDER SPAN, FT RUDDER PROJECTED AREA, FT2 RUDDER DISP, LTON	225.0 24.5 SPADE 1.5 2 0.8078 9.83 1.00 1.10 50.8 11.95 117.4 4.9 8.9 135.14
BILGE KEEL DISP, LTON	8.9
SHAFT SUPPORT DISP, LTON SHAFT DISP, LTON	133.14 13.6 4.7
PROP TYPE IND PROP BLADE DISP, LTON NO PROP SHAFTS	CP 1.9
PROP DIA, FT SONAR DISP, LTON	15.50 165.0

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# PRINTED REPORT NO. 2 - APPENDAGE BUOYANCY AND WEIGHT

		~CENT	ER OF BUOY	ANCY	
APPENDAGE	DISP, LTON	X, FT	Y, FT	Z, FT	
	\$=========				
SHELL	24.5	200.85	0.00	8.58	
SKEG	1.5	299.09	0.00	0.72	
BILGE KEELS*	8.9	195.00	26.78	7.38	
OPEN STRUTS*	13.6	363.91	11.63	-0.54	
PROPULSION SHAFTS*	4.7	335.70	11.63	0.74	
PROP BLADES*	1.9	370.42	11.63	-1.59	
SONAR DOME	165.0	14.00	0.00	-3.20	
RUDDERS*	4.9	383.09	11.63	5.43	
	,================				
TOTAL, LTON	225.0				
* TRANSVERSE C.B. PER SIDE IS SHOWN					
SWBS114, SHLL APNDG	, LTON 13.	18 SW	BS565, ROLL	_ FINS, LTON	0.00

D-24

# **RESISTANCE MODULE**

#### PRINTED REPORT NO. 1 - SUMMARY

RESID RESIST IND	TAYLOR	BILGE KEEL IND	
FRICTION LINE IND	1110	SHAFT SUPPORT TYPE IND	
ËNDUR DISP IND	AVG DISP	PRPLN SYS RESIST IND	
ENDUR CONFIG IND	NO TS	PROP TYPE IND	CP
SONAR DRAG IND	HULL	SONAR DOME IND	PRESENT
SONAR DRAG IND SKEG IND	PRESENT	RUDDER TYPE IND CORR ALW	SPADE
FULL LOAD WT, LTON	5721.7	CORR ALW	0.00050
AVG ENDUR DISP, LTON	5459.4		0.110
USABLE FUEL WT, LTON	996.2	TRAILSHAFT PWR FAC	1.15
NO FIN PAIRS	0.	PRPLN SYS RESIST FRAC	
PROP TIP CLEAR RATIO	0.25	MAX SPEED SUSTN SPEED	0.128
NO PROP SHAFTS	2.	SUSTN SPEED	0.141
PROP DIA, FT	15.50	ENDUR SPEED	0.190
CONDITION SPEED	EFFECTIV	'E HORSEPOWER, HP	DRAG
KT FRI	IC RESID A	PPDG WIND MARGIN TOTA	L LBF
MAX 26,49 772	2. 15441.*	4293. 276. 3051. 3078	3. 378714.
SUSTN 25,26 677	6. 11663.	3691. 239. 2455. 2477	3. 319605.
ENDUR 16.00 174	19. Z384.*	1054. 62. 577. 582	7. 118673.
* DENOTES EXTRAPOLAT	TED VALUE.		

#### PRINTED REPORT NO. 2 - SPEED-POWER MATRIX

SPEED	AND	POWER	FOR	FULL	LOAD	DISP
<b>Z D D D D D D D D D D</b>	-===					

	*=====:						
FULL LOA	D WT, LTON	5	721.7				
SPEED		EFFECTI	VE HORS	EPOWER	, HP		DRAG
KT	FRIC	RESID	APPDC	WIND	MARGIN	TOTAL	LBF
2.00	4.	6.	4.	0.	2.	16.	2627.
4.00	32.	45.	28.	1.	12.	117.	9539.
6.00	104.	152.	80.	3.	37.	376.	20424.
8.00	239.	360.	172.	8.	86.	863.	35153.
10.00	456.	702.	310.	15.	163.	1646.	53653.
12.00	774.	1228.	504.	26.	279.	2811.	76328.
14.00	1210.	2186.	774.	41.	463.	4674.	108801.
16.00	1784.	2555.	1066.	61.	601.	6067.	123559.
18.00	2512.	3536.	1453.	86.	835.	8422.	152467.
20.00	3412.	4994.	1933.	119.	1150.	11607.	189119.
22.00	4501.	6706,	2497.	158.	1525.	15386.	227901.
24.00	5797.	8895.	3161.	205.	1986.	20044.	272155.
26.00	7317.	13797.*	4043.	261.	2796.	28214.	353610.
28.00	9077.	21196.*	5132.	325.	3930.	39661.	461572.

#### SPEED AND POWER FOR AVE ENDUR DISP

AVE ENDU	R DISP, LTO	N 5459	.4				
SPEED		EFFECTI	VE HORS	EPOWER	, HP		DRAG
КT	FRIC	RESID	APPDG	WIND	MARGIN	TOTAL	LBF
2.00	4.	6.*	4.	0.	2.	16.	2602.
4.00	31.	45.*	27.	1.	11.	116.	9444.
6.00	102,	150.*	80.	3.	37.	372.	20217.
8.00	234.	357.*	171.	8.	85.	854.	34793.
10.00	447.	696.*	309.	15.	161.	1629.	53093.
12.00	759.	1211.*	503.	26.	275.	2773.	75307.
14.00	1187.	2105.*	768.	41.	451.	4553.	105966.
16.00	1749.	2384.*	1054.	62.	577.	5827.	118673.
18.00	2463.	3285.*	1437.	88.	800.	8073.	146158.
20.00	3346.	4574.*	1907.	120.	1094.	11041.	179891.
22.00	4414.	6150.*	2463.	160.	1451.	14637.	216811.
24.00	5685.	8234.*	3121.	208.	1897.	19145.	259951.
26.00	7175,	12824.*	3987.	Z64.	2667.	26918.	337367.
28.00	8901.	19881.*	5057.	330.	3759.	37928.	441409.
		ATCO MALL					

\* DENOTES EXTRAPOLATED VALUE.

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#### PRINTED REPORT NO. 3 - SHIP GEOMETRIC DATA FOR RESISTANCE COMPUTATIONS

BARE HULL DISP, LTON APPENDAGE DISP, LTON TOTAL DISP, LTON LBP. FT WL LENGTH, FT BEAM AT MAX AREA STA, FT DRAFT AT MAX AREA STA, FT	FULL LOAD	AVE ENDUR DISP
BARE HULL DISP. LTON	5661.7	5399.4
APPENDAGE DISP. LTON	60.0	60.0
TOTAL DISP. LTON	5721.7	5459.4
LBP. FT	390.00	390.00
WL LENGTH, FT	389.99	389.74
BEAM AT MAX AREA STA, FT	55.00	55.09
DRAFT AT MAX AREA STA, FT	14.99	14.44
MELLED SOKE FOR KESTD VESTSI		
TAYLOR WITH SUNAR DOME DISP, FT2	22803.2	22323.3
WETTED SURF FOR FRIC RESIST		
BARE HULL+S.D. WETTED SURF, FT2	24204.1	23734.1
SONAR DOME WETTED SURF, FT2	1400.0	1400.0
SKEG WETTED SURF AREA, FT2	101.7	101.7
BARE HULL+S.D. WETTED SURF, FT2 SONAR DOME WETTED SURF, FT2 SKEG WETTED SURF AREA, FT2 WIND FRONT AREA, FT2	2037.9	2067.8
FROUDE WETTED SURF COEF LENGTH-BEAM RATIO BEAM-DRAFT RATIO PRISMATIC COEF MAX SECTION COEF DISP-LENGTH RATIO LCB-LENGTH RATIO HALF ANG ENTRANCE, DEG HALF ANG RUN, DEG TRANSOM BUTTOCK ANG, DEG BOW SECT AREA COEF TRANSOM SECT AREA COEF TRANSOM BREADTH COEF TRANSOM DEPTH COEF	6 8458	6 9268
IENCTH DEAM DATTO	7 0902	7 0751
	3 6701	3,8141
PRISMATTC COFF	0.6492	0.6436
MAX SECTION COFF	0.9211	0.9168
DISP-LENGTH RATIO	95.4517	91,2076
ICB-IENGTH RATIO	0.4947	0.4918
HALF ANG ENTRANCE. DEG	11.39	11.70
HALE ANG RUN. DEG	8.96	14.40
TRANSOM BUTTOCK ANG. DEG	11.19	11.19
BOW SECT AREA COEF	0.0000	0.0000
TRANSOM SECT AREA COEF	0,0387	0.0174
TRANSOM BREADTH COEF	0.5919	0.4954
TRANSOM DEPTH COEF	0.0860	0.0516

#### PRINTED REPORT NO. 4 - APPENDAGE DATA

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SKEG IND SKEG AREA, FT2 SHAFT SUPPORT TYPE IND NO STRUTS PER SHAFT STRUT DIMENSIONS	OPEN STRUT	MAIN	INTMD
STRUT CHORD, FT STRUT THICKNESS, FT BARREL LENGTH, FT BARREL DIA, FT		2.92 0.58 12.40 4.72	
NO PROP SHAFTS	2.		
WET SHAFT LGTH (PORT),			
WET SHAFT LGTH (STBD),	FT 58.91		
WET SHAFT LGTH (STBD), INTRMDT SHAFT DIA, FT	1.37		
PROP TYPE IND	СР		
PROP TYPE IND PROP DIA, FT	15.50		
SONAR DOME IND	PRESENT		
SONAR DRAG IND	HULL		
SONAR SECT AREA, FT2	215.0		
SONAR WETTED SURF, FT2			
SONAR DISP, LTON	165.0		
SONAR CB AFT FP, ,A2	*******		
ABV BL, ,AZ	14.00		
SONAR WETTED SURF, FT	-3.2		
SONAR DISP,			
RUDDER AREA, FT2	117.4		
ROLL FIN AREA, FT2			

#### PRINTED REPORT NO. 1 - SUMMARY

PROP TYPE IND	СР	PROP SERIES IND	TROOST
MAX SPEED, KT	26.49	ENDUR SPEED, KT	16.00
MAX EHP (/SHAFT), HP	15391.	ENDUR EHP (/SHAFT), HP	2913.
MAX SHP (/SHAFT), HP	23516.	ENDUR SHP (/SHAFT), HP	4381.
MAX PROP RPM	176.6	ENDUR PROP RPM	103.2
MAX PROP EFF	0.689	ENDUR PROP EFF	0.700
SUSTN SPEED, KT	25.26	PROP DIA, FT	15.50
SUSTN EHP (/SHAFT). HP	12387.	NO BLADES	5.
SUSTN SHP (/SHAFT), HP	18770.	PITCH RATIO	1.27
SUSTN PROP RPM	165.7	EXPAND AREA RATIO	0.790
SUSTN PROP EFF	0.695	CAVITATION NO	1.66
NO PROP SHAFTS	2.0		
TOTAL PROPELLER WT, LTON	41.43		

#### PRINTED REPORT NO. 2 - PROPELLER CHARACTERISTICS

NO PROP SHAFTS	2.
PROP DIA, FT	15.50
NO BLADES	5.
PITCH RATIO	1.27
EXPAND AREA RATIO	0,790
THRUST DED COFF	0.055
TAYLOR WAKE FRAC	0.020
HULL EFFICIENCY	0.964
REL ROTATE EFF	0.985

CHARACTERISTICS	MAXIMUM	CONDITIONS SUSTAINED	ENDURANCE
SPEED, KT	26.49	25.26	16.00
RPM	176.6	165.7	103.2
THRUST/SHAFT, LBF	200380.	169105.	62791.
EHP/SHAFT, HP	15391.	12387.	2913.
TOROUE/SHAFT, FT-LBF	689169.	586322.	219597.
SHP/SHAFT, HP	23516.	18770.	4381.
ADVANCE COEF (J)	0.961	0.976	0.992
THRUST COEF (KT)	0.201	0.193	0.185
TORQUE COEF (10KQ)	0.447	0.432	0.417
OPEN WATER EFFY	0.689	0.695	0.700
PC	0.655	0.660	0.665

### PRINTED REPORT NO. 3 - CAVITATION CHARACTERISTICS

MAX SPEED OF ADV, KT	25.96
MAX THRUST, LBF	200380.
MAX PROP RPM	176.6
PROP DIA, FT	15.50
HUB DEPTH, FT	16.58
STD CAV NO	1.66
LOCAL CAV NO (.7R)	0.27
MEAN THRUST LOADING COEF	0.12
EXPAND AREA RATIO	0.790
MIN EAR REQUIRED	0.948
BACK CAV ALLOWED, PERCENT	5.0

#### PRINTED REPORT NO. 4 - PROPELLER ARRANGEMENT

PROP DIA, FT FULL LOAD DRAFT, FT	15.50 14.99
HUB DEPTH FROM DWL, FT	16.58
LONG LOC FROM AP, FT	19.58
HUB POS FROM CL, FT	11.63
TIP CLR FROM BL, FT	-9.34
TIP CLR FROM MAX HB, FT	8.22
TIP CLR FROM HULL BOT, FT	3.88
TOTAL PROPELLER WT, LTON	41.43

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#### PRINTED REPORT NO. 1 - SUMMARY

TRANS TYPE IND SHAFT SUPPORT TYPE I NO PROP SHAFTS MAX MARG ELECT LOAD AVG 24 HR ELECT LOAI SWBS 200 GROUP WT, I SWBS 300 GROUP WT, I	2. , KW 3361. ), KW 1509. _TON 521.4	ENDUR SPEED ENDURANCE, USABLE FUEL	, KT NM WT, LTON	16.00 4950. 996.2
ARRANGEMENT OR SS G	EN TYPE	NO INSTALLED	NO ONLINE MAX+SUSTN	NO ONLINE ENDURANCE
MECH PORT ARR IND MECH STBD ARR IND SEP SS GEN VSCF SS CYCLO	M2~1 108			
	MAIN ENG	SEC ENG		SS ENG
ENG SELECT IND ENG MODEL IND ENG SIZE IND NO INSTALLED ENG PWR AVAIL, HP ENG RPM ENG SFC, LBM/HP-HR ENG LOAD FRAC	G1 GIVEN 4 13240. 4800.0		0	CALC GE-LM500 GT GIVEN 1 4500. 7000.0 .481 .784

# PRINTED REPORT NO. 2 - MACHINERY EQUIPMENT LIST

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NO EACH	ITEM	WEIGHT LTON	LENGTH FT	WIDTH FT	HEIGHT FT
	PROPULSION PLANT				
4	MAIN ENGINE (BARE)	2.5	12.24	4.80	4.80
4	MAIN ENGINE ENCLOSURE MODULE	6.7	22.32	8.30	7.60
2	LTDR GEAR (01)	42.1	9.16	14.99	12.37
2	VSCF COMB/STEP-UP GEAR (04)	.2	. 38	6.81	5.37
2	THRUST BEARING	5.7	3.02	4.22	4.22
2	PROPELLER SHAFT				
	ELECTRIC PLANT				
1	SS ENGINE (BARE)	.6	7.20	2.80	2.80
1	SS ENGINE ENCLOSURE MODULE	2.9	16.39	5.60	6.63
1	SS REDUCTION GEAR (17)	1.2	4.85	2.45	4.03
1	SEPARATE SS GENERATOR	9.1	8.59	3.60	5.10
4	VSCF SS GENERATOR	2.4	4.87	2.00	2.00
2	VSCF SS CYCLOCONVERTER	7.1			

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# PRINTED REPORT NO. 3 - ENGINES

	MAIN ENG	SEC ENG	SS ENG
ENG SELECT IND ENG TYPE IND ENG MODEL IND ENG SIZE IND NO INSTALLED ENG BARE WT, LTON ENG LENGTH, FT ENG WIDTH, FT ENG HEIGHT, FT ENG PWR AVAIL, HP ENG RPM ENG MASS FL, LDM/SEC ENG EXH TEMP, DEGF ENG SFC EQN IND ENG SFC, LBM/HP-HR	GIVEN GT RR/DDA-SPEY GIVEN 4 2.5 12.24 4.80 4.80 13240.	0	CALC GT GE-LM500 GIVEN
MAX SPEED CONDITION NO OPERATING ENG PWR. HP ENG RPM ENG MASS FL, LBM/SEC ENG EXH TEMP, DEGF ENG SFC, LBM/HP-HR	4 13153. 4800.0 106.1 828.5 .425	0	0 .0 7000.0 .0
SUSTN SPEED CONDITIO NO OPERATING ENG PWR, HP ENG RPM ENG MASS FL, LBM/SEC ENG EXH TEMP, DEGF ENG SFC, LBM/HP-HR	- 10736. 4503.4 98.2 787.7	0	0 .0 7000.0 .0
ENDUR SPEED CONDITIO NO OPERATING ENG PWR, HP ENG RPM ENG MASS FL, LBM/SEC ENG EXH TEMP, DEGF ENG SFC, LBM/HP-HR		0	0 .0 7000.0 .0

NOTE - ENGINE OPERATING DATA ARE BASED ON USE OF DFM FUEL.

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D-29

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#### PRINTED REPORT NO. 4 - GEARS

NO EACH ITEM		LENGTH FT	WIDTH FT	HEIGHT FT
2-STAGE REDUCTION GEARS 2 LTDR GEAR (01) 2 VSCF COMB/SIEP-UP GEAR (04) 1 SS REDUCTION GEAR (17)	.2 1.2	4.85		5.3/
REDUCTION GEAR DESIGN FACTORS AND DIMENSIONS	1ST STAGE		55	
REDUCTION RATIO K FACTOR FACE WIDTH RATIO CASING WT FACTOR GEAR FACE WIDTH, FT PINION GEAR DIA, FT REDUCTION GEAR DIA, FT	100.0 1.000 .750 1.16	8.40 120.0 2.000 .750 2.43 1.22 10.22	175.0 2.300 3.000 1.12 .49	

# PRINTED REPORT NO. 5 - ELECTRIC PROPULSION AND VSCF EQUIPMENT

		MOTORS AND GENERATORS		
	PRPLN GENERATOR	PRPLN	VSCF GENERATOR	
INSTALLED NUMBER TYPE FREQUENCY CONTROL	0	0	4 AC	
DRIVE ROTOR COOLING			GEARED LIQUID	
ROTOR TIP SPEED, FT/MIN STATOR COOLING ARM ELECT LOAD, AMP/IN			24500. LIQUID 2000.	
POWER RATING, MW ROTATIONAL SPEED, RPM			2.00 7650. 12.	
NUMBER OF POLES LENGTH, FT WIDTH, FT			4.9 2.0	
HEIGHT, FT WEIGHT, LTON			2.0 2.4	
OTHER ELECTRI	C PROPULSIO	N AND VSCF	EQUIPMENT	

WEIGHT

	WEIGHT
	LTON
	LION
VSCF CYCLOCONVERTERS	14.2

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D-30

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# PRINTED REPORT NO. 6 ~ SHIP SERVICE GENERATORS

FIFCT LOAD DES MARGIN FAC	0.100
ELECT LOAD SL MARGIN FAC	0.200
ELECT LOAD IMBAL FAC	0.900
MAX MARG ELECT LOAD, KW	3360.8
MAX STANDBY LOAD, KW	1993.7
24 HR AVG ELECT LOAD, KW	1509.1

#### VSCF SS CYCLOCONVERTERS

NO NO REQ AVAIL LOADING CONDITION INSTALL ONLINE KW/CYCLO KW/CYCLO FRAC								
WINTER BATTLE	2	2	1479.	2000.	0.740			
WINTER CRUISE	2	2	1680.	2000.	0.840			
SUMMER CRUISE	2	2	1272.	2000.	0,636			
ENDURANCE (24 HR AVG)	2	2	755.	2000.	0.377			

#### SEPARATE SS GENERATORS

	<b>####################################</b>						
	NO	NO	REQ	AVAIL	LOADING		
CONDITION	INSTALL	ONLINE	KW/GEN	KW/GEN	FRAC		
		··					
		-		35.00			
WINTER BATTLE	1	0	•	2500.	0.000		
WINTER CRUISE	1 1	0		2500.	0.000		
SUMMER CRUISE	1	0		2500.	0.000		
ENDURANCE (24 HR AVG)	1	0		2500.	0.000		
		TOTALS					
			REQ	AVATL	LOADING		
CONDITION			KW	KW	FRAC		
				*			
WINTER BATTLE			2958.	4000.	0.740		
WINTER CRUISE			3361.	4000.	0.840		
SUMMER CRUISE			2545.	4000.	0.636		
ENDURANCE (24 HR AVG)			1509.	4000.	0.377		

#### PRINTED REPORT NO. 7 - INTAKE DUCTS

INLET TYPE IND-PLENUM DUCT SILENCING IND-BOTH GT ENG ENCL IND-90 DBA

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	MAIN ENG	SEC ENG	SS ENG
ENG TYPE INLET DUCT XSECT AREA, FT INLET DUCT XSECT LTH, FT		.0 .0	GT 20.9 6.5
INLET DUCT XSECT WID, FT	8.30	.0	3.2

# MMR1

INLET INLET DUCTING INLET SILENCER GT COOLING SUPPLY	WT,LTON 0.7 1.4 2.0 1.4	VCG, FT 51.65 39.05 43.01 32.09	SEC ENG WT,LTON VCG,FT
GT BLEED AIR SUPPLY	MMR2 ====	ENG	SEC ENG WT,LTON VCG,FT
INLET INLET DUCTING INLET SILENCER GT COOLING SUPPLY GT BLEED AIR SUPPLY	0.7 0.7 2.0 0.7	32.39 27.52 40.09 23.12 20.80	

NOTE - NUMERIC DATA PRESENTED ABOVE ARE ON A PER ENGINE BASIS.

# TRUNK AREA AND VOLUME REQUIREMENTS -----AREA, FT2--- ENGINE CATEGORY HULL DKHS MAIN ENGINES 383.6 SECONDARY ENGINES 0.0 SECONDARY ENGINES 60.2 TOTALS 443.8 383.6 4386.

D-32

#### PRINTED REPORT NO. 8 - EXHAUST DUCTS

EXHAUST IR SUPPRESS IND-PRESENT DUCT SILENCING IND-BOTH GT ENG ENCL IND-90 DBA

EXHAUST	STACK TEMP,	DEGF	350.0
EDUCTOR	DESIGN FAC		1.000

	MAIN ENG	SEC ENG	SS ENG
	<b></b> -		
ENG TYPE	GT		GT
ENG EXH TEMP, DEG	829.		959.
ENG MASS FL, LBM/SEC	106.1		28.5
EXH DUCT GAS TEMP, DEG	743.		857.
EXH DUCT GAS DEN, LBM/FT	3 0.0325		.0297
EXH DUCT MASS FL, LBM/SE	C 121.3		32.5
EXH DUCT AREA, FT2	34.7		10.2

MMR1 \_\_\_\_

	MAIN	ENG	SEC ENG
	WT.LTON	VCG, FT	WT, LTON VCG, FT
EXH DUCT (TO BOILER/REG)			
EXH BOILER (RACER)			
EXH REGENERATOR			
EXH DUCT (TO STACK)	5.6	38,56	
EXH SILENCER	6.3	48.19	
EXH STACK	1.9	61.95	
EXH SPRAY RING	.9	43,31	
EXH EDUCTOR	5.4	62.83	
	MMR2	2	
		=	
		_	
	MAIN	ENG	SEC ENG
	MAIN	ENG	SEC ENG WT,LTON VCG,FT
	MAIN	ENG	
FXH DUCT (TO BOILER/REG)	MAIN	ENG	
EXH BOILER (RACER)	MAIN	ENG	
EXH BOILER (RACER) EXH REGENERATOR	MAIN WT,LTON	ÉNG VCG, FT	
EXH BOILER (RACER) EXH REGENERATOR EXH DUCT (TO STACK)	MAIN WT,LTON 	ENG VCG, FT 	
EXH BOILER (RACER) EXH REGENERATOR EXH DUCT (TO STACK) EXH SILENCER	MAIN WT,LTON  2.7 6.3	ENG VCG, FT  28.09 45.27	
EXH BOILER (RACER) EXH REGENERATOR EXH DUCT (TO STACK) EXH SILENCER EXH STACK	MAIN WT,LTON  2.7 6.3 1.9	ENG VCG, FT  28.09 45.27 42.69	
EXH BOILER (RACER) EXH REGENERATOR EXH DUCT (TO STACK) EXH SILENCER	MAIN WT,LTON  2.7 6.3 1.9 .9	ENG VCG, FT  28.09 45.27	

NOIE - NUMERIC DATA PRESENTED ABOVE ARE UN A PER ENGINE BASIS.

#### TRUNK AREA AND VOLUME REQUIREMENTS

sstate and state the second and the state of the second se				
	AREA	,FT2	VOLUME	,FT3
ENGINE CATEGORY	HULL	DKHS	HULL	DKHS
MAIN ENGINES	492.4	492.4	4924.	4226.
SECONDARY ENGINES	0,0	0.0	0.	0.
SHIP-SERVICE ENGINES	116.0	0.0	1061.	0.
707410				4226
TOTALS	608.5	492.4	5985.	4226.

# PRINTED REPORT NO. 9 - PROPELLERS AND SHAFTS

PROP TYPE IND-CP	
PROP DIA, FT	15.50
HUB DIA, FT	4.72
PROP BLADE WT, LTON	7.6
PROP HUB WT, LTON	13.2
BEND STRESS CON FAC	1.700
OVRHG PROP MOM ARM RATIO	0.340
EQUIV FP PROP WT, LTON	16.5
ALLOW BEND STRESS, LBF/IN2	6000.
FATIGUE LIMIT, LBF/IN2	47500.
YIELD POINT, LBF/IN2	75000.
TORQUE MARGIN FAC	1.200
OFF-CENTER THRUST FAC	2.000
NO STRUTS PER SHAFT	1

	PO	RT SHAFT	
	32	*******	
	PROP	INTERMED	LINE
	SECTION	SECTION	SECTION
ANGLE, DEG	3.58	3.58	3.58
LENGIĤ, FI	13.18	82.01	127.21
DIAMETER, FT	2.41	1.37	1.18
BORE RATIO	.550	.667	.667
WEIGHT, LTON	12.3	19.8	19.2
LCG, IT	361.07	313.57	209.16
TCG, FT	-11.63	-11.63	-11.63
VCG, FT	-1.00	1.97	8.51
FACTOR OF SAFETY		2.00	1.75
	ST	BD SHAFT	

	SIDU SHAFT		
	<b>AA======</b>		
	PROP	INTERMED	LINE
	SECTION	SECTION	SECTION
ANGLE, DEG	4.21	4.21	4.21
LENGTH, FT	13.18	99.26	67.15
DIAMETER, FT	2.41	1.37	1.18
BORE RATIO	. 550	.667	.66/
WEIGHT, LTON	12.3	24.0	10.1
LCG, FT	361.07	305.01	222.02
TCG, FT	11.63	11.63	11.63
VCG, FT	90	3.23	9.33
FACTOR OF SAFETY		2.00	1.75

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# PRINTED REPORT NO. 10 - STRUTS, PODS, AND RUDDERS

PROP DIA, FT NO STRUTS PER SHAFT NO SHAFTS OVRHG PROP MOM ARM RATIO	15.50 1 2 0.340		
	STRU	тs	
		INTERMED STRUT	
WALL THICKNESS, FT	.22		
CHORD, FT	2.92		
THICKNESS, FT	. 58		
BARREL LTH, FT BARREL DIA, FT	12.40 4.72		
	4172		
	RUDDE	RS	
RUDDER TYPE IND-SPADE			
RUDDER SIZE IND-GIVEN			
RUDDER WT (PER), LTON	17.0		
RUDDER DISP (PER), LTON	2.3		
	CHORD, FT	THICK, FT	SPAN, FT
SPADE RUDDER	9,83	1.10	11.95
1	5.05	1110	221.55

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# PRINTED REPORT NO. 11 - ELECTRIC LOADS

PAYLOAD LOADS	WINTER CRUISE KW	WINTER BATTLE KW	SUMMER CRUISE KW
COMMAND AND SURVEILLANCE (60 HZ) COMMAND AND SURVEILLANCE (400 HZ) ARMAMENT (60 HZ) ARMAMENT (400 HZ) OTHER PAYLOAD (60 HZ) OTHER PAYLOAD (400 HZ)	401.3 0.0	523.9 0.0	401.3 0.0
ARMAMENT (60 HZ)	73.5	148.4	73.5
ARMAMENT (60 HZ) ARMAMENT (400 HZ) OTHER PAYLOAD (60 HZ) OTHER PAYLOAD (400 HZ)	0.0	0.0	0.0
OTHER PAYLOAD (60 HZ)	0.0	0.0	0.0
OTHER PAYLOAD (400 HZ)	0.0	0.0	0.0
SUB-TOTAL	474.8	672.3	474.8
NON-PAYLOAD LOADS (* INDICATES US	ER ADJUSTE	ED VALUE)	
PROPULSION AND STEERING	258.9	300.3	168.3
PROPULSION AND STEERING LIGHTING	136.8	134.0	136.8
MISCELLANEOUS ELECTRIC	46.1	40.1	46.1
HEATING		366.1	
VENTILATION	292.8	225.4	292.8
AIR CONDITIONING		266.2	
AUXILIARY BOILER AND FRESH WATER			
FIREMAIN	66.6	93.9	66.6
UNREP AND HANDLING	12.0	2.9	12.0
FIREMAIN UNREP AND HANDLING MISC AUXILIARY MACHINERY SERVICES AND WORK SPACES	52.5*	34.0*	52.5*
SERVICES AND WORK SPACES	67.2	22.2	67.2
SUBTOTAL	2114.4	1618.7	1481.2
TOTAL	2589.2	2291.0	1956.0
TOTAL (INCLUDING MARGINS)	3360.8	2958.0	2544.9
MAX MARG ELECT LOAD 24 HR AVG ELECT LOAD CONNECTED ELECT LOAD ANCHOR ELECT LOAD VITAL ELECT LOAD	3360.8		
24 HR AVG ELECT LOAD	1509.1		
CONNECTED ELECT LOAD	6861.5		
ANCHOR ELECT LOAD	1993.7		
EMERGENCY ELECT LOAD	959.8		
MAX STBY ELECT LOAD	1993.7		

# PRINTED REPORT NO. 12 - POWERING

100 PCT POWER TRANS EFF	0.9781*
25 PCT POWER TRANS EFF	0.9643*
* VALUES DO NOT INCLUDE	CP PROP TRANSMISSION EFFICIENCY MULTIPLIER

	MAX	SUSTN	ENDUR
	SPEED	SPEED	SPEED
SHIP SPEED, KT	26.49	25.26	16.00
PROP RPM	176.6	165.7	103.2
NO OP PROP SHAFTS	2	2	2
EHP (/SHAFT), HP	15391.	1238/.	2913.
PROPULSIVE COEF	0.655	0.660	0.665
ENDUR PWR ALW	1.0	1.0	1.1
SHP (/SHAFT), HP	23516.	18769.	4819.
TRANS EFFY	0.978	0.976	0.964
CP PROP TRANS EFFY MULT	0.997	0.997	0.997
PROPUL PWR (/SHAFT), HP	24114.	19292.	5013.
PD GEN PWR (/SHAFT), HP	2192.	2181.	1088.
BHP (/SHAFT), HP	26306.	21472.	6101.

# PRINTED REPORT NO. 13 - HULL STRUCTURE AND MISCELLANEOUS WEIGHT

SWBS	COMPONENT	WT, LTON LCG, FT VCG, FT
		aratic States for there
	PECIAL STRUCTURES CASTINGS, FORGINGS, AND WELDMENTS	55.7 279.73 7.28
	STACKS AND MASTS	7.6 163.10 52.32
	OUNDATIONS	7.0 103.10 JZ.JZ
	PROPULSION PLANT FOUNDATIONS	91.2 169.67 9.16
183	ELECTRIC PLANT FOUNDATIONS	32.6 198.72 20.34

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 14 - PROPULSION PLANT WEIGHT

SWBS COMP	PONENT	WT,LTON	LCG, FT	VCG, FT
779 <b>2</b> - 229	======	Zeżeżeg	F=3736	lezzar
200 PROPULSION PLA	ANT	521.4	214.40	15.43
	RATING SYSTEM (NUCLEAR)		0.00	0.00
	RATING SYSTEM (NON-NUCLEAR)	0.0	0.00	0.00
230 PROPULSION (	UNITS	68.6	162.83	16.79
233 PROPULSIO	N INTERNAL COMBUSTION ENGINES	0.0	0.00	0.00
234 PROPULSIO		68.6	162.83	16.79
235 ELECTRIC			0.00	0.00
	N AND PROPULSOR SYSTEMS	264.3	255.39	6.38
241 PROPULSIO	N REDUCTION GEARS	84.5	162.60	13,30
242 PROPULSIO	N CLUTCHES AND COUPLINGS	0.0	0.00	0.00
243 PROPULSIO		97.6	293.46	3.59
	N SHAFT BEARINGS	29.8	256.47	6.09
245 PROPULSOR	S	52.4	333.58	0.58
250 PRPLN SUPPOR	RT SYS (EXCEPT FUEL+LUBE OIL)	116.8	164.75	37.87
251 COMBUSTION	N AIR SYSTEM	31.2	159.41	32.26
	N CONTROL SYSTEM		162.83	
	NG AND COOLING SEA WATER SYST	EM 5.8	245.70	13.14
259 UPTAKES (	INNER CASING)	66.8	160.59	45.37
260 PRPLN SUPPOR	RT SYS (FUEL+LUBE OIL)	36.1	156.91	12.53
261 FUEL SERVI		9.4	143.33	10.79
262 MAIN PROP	ULSION LUBE OIL SYSTEM	19.0	162.83	12.00
264 LUBE OIL I	FILL, TRANSFER, AND PURIF	7.6	158.83	16.00
290 SPECIAL PUR	POSE SYSTEMS	35.7	230.55	9.35
298 OPERATING	FLUIDS	30.4	234.00	8.00
299 REPAIR PA	RTS AND SPECIAL TOOLS	5.3	210.60	17.16

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 15 - ELECTRIC PLANT WEIGHT

SWBS COMPONENT	WI, LTON LCG, FT VCG, FT
	sester signe etter
300 ELECTRIC PLANT	182.4 208.17 24.73
310 ELECTRIC POWER GENERATION	59.8 199.43 18.08
311 SHIP SERVICE POWER GENERATION	59.8 199.43 18.08
313 BATTERIES AND SERVICE FACILITIES	0.0 0.00 0.00
314 POWER CONVERSION EQUIPMENT	0.0 0.00 0.00
320 POWER DISTRIBUTION SYSTEMS	89.7 208.91 27.58
321 SHIP SERVICE POWER CABLE	64.3 206.70 27.00
324 SWITCHGEAR AND PANELS	25.4 214.50 29.03
330 LIGHTING SYSTEM	22.4 205.08 33.15
331 LIGHTING DISTRIBUTION	13.1 206.70 32.85
332 LIGHTING FIXTURES	9.3 202.80 33.58
340 POWER GENERATION SUPPORT SYSTEMS	6.3 245.86 20.53
342 DIESEL SUPPORT SYSTEMS	0.0 0.00 0.00
343 TURBINE SUPPORT SYSTEMS	6.3 245.86 20.53
390 SPECIAL PURPOSE SYSTEMS	4.2 277.05 20.17
398 OPERATING FLUIDS	1.2 199.43 18.08
399 REPAIR PARTS AND SPECIAL TOOLS	3.0 308.10 21.00

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 16 - MACHINERY ROOMS

NO MAIN MACHINERY ROOMS	
NO AUX MACHINERY ROOMS	
NO OTHER MACHINERY ROOMS	

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BULKHEAD LOCATIONS

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MR	MR	FWD 8HD			AFT BHD			
NO	ID	BHD NO	X, FT	X/LBP	BHD NO	X, FT	X/LBP	
1	MMR1	5.	112.55	0.289	6.	148.33	0.380	
2	MMR2	7.	177.58	0.455	8.	213.15	0.547	
3	AMR1	9.	242.40	0.622	10.	282.88	0.725	
	DIMENSIONS							

	DIMENSIONS								
M	r mf	۱L	ENGTH, FT	·WI	DTH, FT	HEIGHT,	FT		
N	D 10	) AV	AIL REC	) AVAI	L REQ	AVAIL	REQ		
_	1 MMF	1 3	5.78 35.	78 52.	20 43.10	28.95	23.49		
:	2 MMF	RZ 3	5.57 35.	57 55.	15 43.10	26.88	22.83		
	3 AMF	R1 4	0.48 40.	48 54.	88 6.3	5 17.50	17.50		

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#### PRINTED REPORT NO. 17 - MACHINERY ARRANGEMENTS

# CLEARANCES (MACHINERY TO MACHINERY) 2.50 1.00 ENG TO ENG CLR, FT ENG TO GEAR CLR, FT OR ENG TO GEN CLR OR GEAR TO GEN CLR MTR TO GEAR CLR, FT 2.50 PRPLN ARR TO SS ARR CLR, FT 6.00 AISLE WIDTH CLR, FT 2.50 PORT/CL TB TO GEAR CLR, FT -3.02 STBD TB TO GEAR CLR, FT -3.02 SEPARATIONS (BETWEEN HULL AND MACHINERY) \_\_\_\_\_ LONG (TO BHD), FT 0.75 TRANS (TO SIDE SHELL), FT0.75VERT (TO HULL BOT), FT0.75RADIAL (TO POD), FT0.75 ARRANGEMENTS \_\_\_\_\_ NO NO ONLINE NO ONLINE ARRANGEMENT TYPE INSTALLED MAX+SUSTN ENDURANCE MECH PORT ARR INDM2-LTDR111MECH STBD ARR INDM2-LTDR/F111SHIP SERVICE ARRGT100 MACHINERY COMPONENT LOCATIONS -------COMPONENT MR ID X Y Z

25
5
3
3
50

SHAFTING

END POINT LOC. FT							
SHAFT TYPE	х	Y	Z	SHAFT ANGLE, DEG			
PORT SHAFT STBD SHAFT	145.68 188.54	-11.63 11.63	12.49 11.80	3.58 4.21			

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### PRINTED REPORT NO. 18 - MACHINERY SPACE REQUIREMENTS

MACHINERY ROOM VOLUME REQUIREMENTS	
VOLUME CATEGORY	VOLUME, FT3
SWBS GROUP 200	110148.
PROPULSION POWER GENERATION	41391.
PROPULSION ENGINES	30487.
PROPULSION REDUCTION GEARS AND GENERATORS	10905.
DRIVELINE MACHINERY	0.
REDUCTION AND BEVEL GEARS WITH Z-DRIVE	0.
ELECTRIC PROPULSION MOTORS AND GEARS	0.
REMOTELY-LOCATED THRUST BEARINGS	0.
PROPELLER SHAFT	9985.
ELECTRIC PROPULSION MISCELLANEOUS EQUIPMENT	0.
CONTROLS	0.
BRAKING RESISTORS	0.
MOTOR AND GENERATOR EXCITERS	0. 0.
POWER CONVERTERS	0.
DEIONIZED COOLING WATER SYSTEMS	0.
RECTIFIERS	0.
HEI TUM REERTGERATTON SYSTEMS	0.
PROPULSION AUXILIARIES	58771.
PROPULSION LOCAL CONTROL CONSOLES	3387.
CP PROP HYDRAULIC OIL POWER MODULES	2967.
FUEL OIL PUMPS	31237.
LUBE OIL PUMPS	3500.
LUBE OIL PURIFIERS	14363.
ENGINE LUBE OIL CONDITIONERS	1127.
SEAWATER COOLING PUMPS	2190.
SWBS GROUP 300	24878.
ELECTRIC PLANT POWER GENERATION	5037.
ELECTRIC PLANT ENGINES	3342.
ELECTRIC PLANT GENERATORS AND GEARS	1695.
SHIP SERVICE SWITCHBOARDS	18649.
CYCLOCONVERTERS	1191.
SWBS GROUP 500	34871.
AUXILIARY MACHINERY	34871.
AIR CONDITIONING PLANTS	7316.
AUXILIARY BOILERS	5066.
FIRE PUMPS	3822.
DISTILLING PLANTS	11984.
AIR COMPRESSORS	4959.
ROLL FIN PAIRS	0.
SEWAGE PLANTS	1724.

# ARRANGEABLE AREA REQUIREMENTS

		FT2	
SSCS	GROUP NAME	HULL/DKHS	DKHS ONLY
3.4X	AUXILIARY MACHINERY DELTA	5167.6	0.0
3.511	SHIP SERVICE POWER GENERATION	0.0	0.0
4.132	INTERNAL COMB ENG COMB AIR	0.0	0.0
4.133	INTERNAL COMB ENG EXHAUST	0.0	0.0
4.142	GAS TURBINE ENG COMB AIR	443.8	383.6
4.143	GAS TURBINE ENG EXHAUST	608.5	492.4

NOTE: \* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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DESIGN MODE IND-ENDURANCE ENDUR DISP IND-AVG DISP ENDUR DEF IND-USN SHIP FUEL TYPE IND-JP-5 SHIP FUEL LHV, BTU/LBM 18300. DFM FUEL LHV, BTU/LBM 18360.	
<ol> <li>(1) ENDURANCE REQUIRED, NM</li> <li>(2) ENDURANCE SPEED, KT</li> <li>(3) FULL LOAD DISPLACEMENT, LTON</li> <li>(3A) AVERAGE ENDURANCE DISPLACEMENT, LTON</li> <li>(4) RATED FULL POWER SHP, HP</li> <li>(5) DESIGN ENDURANCE POWER SHP Ø (2)&amp;(3A), HP</li> <li>(6) AVERAGE ENDURANCE POWER (SHP), HP</li> </ol>	6000
(2) ENDURANCE SPEED, KT	16.00
(3) FULL LOAD DISPLACEMENT, LITON	5721.7
(3A) AVERAGE ENDURANCE DISPLACEMENT. LTON	5459.4
(4) RATED FULL POWER SHP. HP	47032
(5) DESTGN ENDURANCE POWER SHP @ (2)&(3A) HP	8763
(6) AVERAGE ENDURANCE POWER (SHP), HP	9639.
(F) V 1 10	
<ul> <li>(3) X 1.10</li> <li>(7) RATIO, AVG END SHP/RATED F.P. SHP</li> <li>(6)/(4)</li> <li>(8) AVERAGE ENDURANCE BHP, HP</li> <li>(8) AVERAGE (PR)</li> </ul>	0.20494
(6)/(4)	
(8) AVERAGE ENDURANCE BHP, HP	12202.
(OA)+(OD)	
(8A) AVERAGE PRPLN ENDURANCE BHP, HP	10026.
(6)/TRANSMISSION EFFICIENCY	
(8B) SHIP SERV PWR SUPPLIED BY PRPLN ENG, HP (9) 24 HOUR AVERAGE ELECTRIC LOAD, KW	2176.
(9) 24 HOUR AVERAGE ELECTRIC LOAD, KW	1509.
(9A) 24 HOUR AVERAGE ELECTRIC LOAD PORTION	
SUPPLIED BY SS ENG, KW	0.
(10) CALCULATED PROPULSION FUEL RATE @(8), LBM/HP-HR	0.540
(11) CALC PRPLN FUEL CONSUMPTION, LBM/HR	6583.6
(10)X(8)	
(12) CALC SS GEN FUEL RATE @ (9A), LBM/KW-HR	0.000
(13) CALC SS GEN FUEL CONSUMPTION, LBM/HR	0.0
(12)X(9A)	
(14) CALC FUEL CONSUMPTION FOR OTHER SERVICES, LBM/HR	0.0
(15) TOTAL CALC ALL-PURPOSE FUEL CONSUMPTION, LBM/HR	6583.6
(11)+(13)+14)	
(16) CALC ALL-PURPOSE FUEL RATE, LBM/HP-HR	0.683
(15)/(6)	
(17) FUEL RATE CORRECTION FACTOR BASED ON (7) (18) SPECIFIED FUEL RATE, LBM/HP-HR	1.0400
(18) SPECIFIED FUEL RATE, LBM/HP-HR	0.710
(16)X(17)	
(19) AVG ENDURANCE FUEL RATE, LBM/HP-HR	0.746
(18)X1.05	
(20) ENDURANCE FUEL (BURNABLE), LTON	996.2 *
(1)X(6)X(19)/(2)X2240	
(21) TAILPIPE ALLOWANCE FACTOR	0.95
(22) ENDURANCE FUEL LOAD, LTON	1048.6
(20)/(21)	
-	

#### PRINTED REPORT NO. 20 - MACHINERY MARGINS

PROPULSION PLANT	
MATN ENG MAX LOAD FRAC TORQUE MARGIN FAC	0.993 1.200
ELECTRIC PLANT	
SS ENG MAX LOAD FRAC	0.784
ELECT LOAD DES MARGIN FAC	0.100
ELECT LOAD SL MARGIN FAC	0.200
ELECT LOAD IMBAL FAC	0.900
MACHINERY MODULE	15,700 CPU SECONDS.

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# WEIGHT MODULE

# PRINTED REPORT NO. 1 - SUMMARY

		WEI	GHT	LCG	VCG	RESULTA	LCA TV
SWBS	GROUP	LTON F	PER CENT	FT	FT	WT-LTON	VCG-FT
				======			
100	HULL STRUCTURE	1809.4	31.6	168.02	19.46	54.2	.39
200	PROP PLANT	521.4	9.1	214.40	15.43		
300	ELECT PLANT	182.4	3.2	208.17	24.73		
400	COMM + SURVEIL	354.8	6.2	148.20	24.01	145.6	1.13
500	AUX SYSTEMS	520.6	9.1	214.50	23.50	19.0	.10
600	OUTFIT + FURN	299.4	5.2	195.00	24.01		
700	ARMAMENT	105.6	1.8	175.50	34.65	103.7	.63
M11	D+B WT MARGIN	474.2	8.3	183.19	20.92		
	D+B KG MARGIN			+	2.61		
				********			
L	IGHTSHIP	4267.8	74.6	183.19	23.53	322.4	2.25
====							
F00	FULL LOADS	1453.9	25.4	252.69	8.03	127.3	.61
F10	CREW + EFFECTS	22.4		183.30	27.86		
F20	MISS REL EXPEN	100.3		171.60	32.32		
F30	SHIPS STORES	27.4		210.60	20.90		
F40	FUELS + LUBRIC	1275.4		262.81	5.56		
FS0	FRESH WATER	28.5			5.25		
F60	CARGO						
M24	FUTURE GROWTH						
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FU	LL LOAD WT	5721.8	100.0	200.85	19.59	449.7	2.87
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D-42

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# PRINTED REPORT NO. 2 - HULL STRUCTURES WEIGHT

SWBS	COMPONENT L STRUCTURES HELL + SUPPORTS	WT-LTON	VCG-FT
		WT-LTON 1809.4 674.2 330.8 135.4 13.2 8.1 59.4 102.4 209.0 80.7 97.9 20.4	
	L STRUCTURES	1809.4	19.46
	HELL + SUPPORTS	674.2	15.47
111	PLATING	330.8	19.88
113	INNER BOTTOM	135.4	3.07
114	SHELL APPENDAGES	13.2	6.50
115	INNER BOTTOM SHELL APPENDAGES STANCHIONS LONGIT FRAMING TRANSY FRAMING ULL STRUCTURAL BULKHDS LONGIT STRUCTURAL BULKHDS TRANSY STRUCTURAL BULKHDS	8.1	18.25
116	LONGIT FRAMING	59.4	. 93
117	TRANSV FRAMING	102.4	18.11
120 H	ULL STRUCTURAL BULKHDS	209.0	16.47
121	LONGIT STRUCTURAL BULKHDS	80.7	10.28
122	TRANSV STRUCTURAL BULKHDS	97.9 30.4	20.37
123	TRUNKS + ENCLUSURES	30.4	20.37
	BULKHEADS, TORPEDO PROTECT SYS		
	ULL DECKS	253.7	33.16
131	MAIN DECK	141.1	37.76
	2ND DECK	112.6	27.40
133	3RD DECK		
134	4TH DECK		
135	5TH DECK+DECKS BELOW		
	01 HULL DECK		
	02 HULL DECK		
138			
139			
140 H	04 HULL DECK ULL PLATFORMS/FLATS 1ST PLATFORM 2ND PLATFORM	121 6	14 39
141	1ST PLATEORM	71.9	17 46
142		49.7	9 95
143	3RD PLATFORM	43.7	5.55
	4TH PLATFORM		
	STH PLAT+PLATS BELOW		
1.40	EL 170		
150 0	FLAIS ECK HOUSE STRUCTURE PECIAL STRUCTURES CASTINGS+FORGINGS+EQUIV WELDMT	114 1	47 99
150 0	DECTAL STRUCTURES	212 6	47.00
100 3		213.3	11.85 7.28
161	STACKS AND MACKS	55.7	52.32
	SEA CHESTS	7.6 4.5	3.70
+ 164		29.2	3.70
	BALLISTIC PLATING	29.2	31.90
1.00	SONAR DOMES		~1.50
166	SPONSONS HULL STRUCTURAL CLOSURES	24.2	30.05
167	HULL STRUCTURAL CLOSURES	24.2	26.65
168	DKHS STRUCTURAL CLOSURES	1.0	39.85
169	SPECIAL PURPOSE CLOSURES+STRUC	5.5	40.08
170 M	DKHS STRUCTURAL CLOSURES SPECIAL PURPOSE CLOSURES+STRUCT ASTS+KINCPOSTS+SERV PLATFORM	-9.9	43.73
1/1	MASIS, LOWERS, LETRAPODS	-9.9	43,73
	KINGPOSTS AND SUPPORT FRAMES		
179	SERVICE PLATFORMS		
180 F	OUNDATIONS	215.4	16.42
181			
182	PROPULSION PLANT FOUNDATIONS	91.2	9.16
183		32.6	20.34
184		22.0	30.70
185	AUXILIARY SYSTEMS FOUNDATIONS	52.1	17.54
186		9.5	23.71
187		7.9	28.11
	PECIAL PURPOSE SYSTEMS	17.9	4,00
191	BALLAST+BOUYANCY UNITS		
197			
198		17.9	4.00
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	* DENOTES INCLUSION OF PAYLOAD (	OR ADJUSTMENTS	

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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# PRINTED REPORT NO. 3 - PROPULSION PLANT WEIGHT

SWBS	COMPONENT	WT-LTON	VCG-FT
	PULSION PLANT	521.4	
	ENERGY GEN SYS (NUCLEAR)		
	NERGY GENERATING SYSTEM (NONNUC)		
	PROPULSION BOILERS		
	GAS GENERATORS		
	MAIN PROPULSION BATTERIES		
	MAIN PROPULSION FUEL CELLS		
	PROPULSION UNITS	68.6	16.79
	STEAM TURBINES		
	STEAM ENGINES		
	DIESEL ENGINES		
	GAS TURBINES	68.6	16.79
	ELECTRIC PROPULSION		
	SELF-CONTAINED PROPULSION SYS AUXILIARY PROPULSION DEVICES		
	FRANSMISSION+PROPULSOR SYSTEMS	764 2	6.38
	REDUCTION GEARS	204,3 84.5	
	CLUTCHES + COUPLINGS	64.5	13.30
	SHAFTING	97.6	3.59
	SHAFT BEARINGS	29.8	
	PROPULSORS	52.4	
	PROPULSOR SHROUDS AND DUCTS		
247	WATER JET PROPULSORS		
250 5	SUPPORT SYSTEMS	116.8	37.87
	COMBUSTION AIR SYSTEM	31.2	32.26
252	PROPULSION CONTROL SYSTEM	12.9	23.73
	MAIN STEAM PIPING SYSTEM		
	CONDENSERS AND AIR EJECTORS		
	FEED AND CONDENSATE SYSTEM		
	CIRC + COOL SEA WATER SYSTEM	5.8	13.14
	H.P. STEAM DRAIN SYSTEM		
259	UPTAKES (INNER CASING)	66.8	
	PROPUL SUP SYS- FUEL, LUBE OIL		12.53
	FUEL SERVICE SYSTEM	9.4	10.79
	MAIN PROPULSION LUBE OIL SYSTEM		12.00
	LUBE OIL HANDLING	7.6	16.00
	SPECIAL PURPOSE SYSTEMS	35.7	9.35
	OPERATING FLUIDS REPAIR PARTS + TOOLS	30.4 5.3	8.00 17.16
299	REFAIR PARIS + IUUES	3.3	1/.16

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

## PRINTED REPORT NO. 4 - ELECTRIC PLANT WEIGHT

SWBS COMPONENT		VCG-FT
300 ELECTRIC PLANT, GENERAL	182.4	24.73
310 ELECTRIC POWER GENERATION	59.8	18.08
311 SHIP SERVICE POWER GENERA	TION 59.8	18.08
320 POWER DISTRIBUTION SYS	89.7	27.58
321 SHIP SERVICE POWER CABLE	64.3	27.00
324 SWITCHGEAR+PANELS	25.4	29.03
330 LIGHTING SYSTEM	22.4	33.15
331 LIGHTING DISTRIBUTION	13.1	32.85
332 LIGHTING FIXTURES	9.3	33.58
340 POWER GENERATION SUPPORT SY	'S 6.3	20.53
343 TURBINE SUPPORT SYS	6.3	20.53
390 SPECIAL PURPOSE SYS	4.2	20.17
398 ELECTRIC PLANT OP FLUIDS	1.2	18.08
399 REPAIR PARTS+SPECIAL TOOL	.5 3.0	21.00

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

#### PRINTED REPORT NO. 5 - COMMAND+SURVEILLANCE WEIGHT

۶I	√BS	COMPONENT	WT-LTON	VCG-FT
		= # # 물호교 방학 #		
		MAND+SURVEILLANCE	354.8	24.01
*		OMMAND+CONTROL SYS		28.41
	-	20 NAVIGATION SYS	14.8	43.95
		NTERIOR COMMUNICATIONS	23.7	25.62
*		XTERIOR COMMUNICATIONS	26.4	38,40
		URF SURV SYS (RADAR)	21.2	56,40
*		SURFACE SEARCH RADAR	1.9	65.82
*		AIR SEARCH RADAR	17.4	
#	455	IDENTIFICATION SYSTEMS (IFF)	1.9	56.75
*		NDERWATER SURVEILLANCE SYSTEMS		11.28
		OUNTERMEASURES	44.9	33.48
*		ACTIVE + ACTIVE/PASSIVE ECM	6.0	
*		TORPEDO DECOYS	10.6	
*		DECOYS (OTHER)	1.6	58.50
		DEGAUSSING	26.6	25.62
		MINE COUNTERMEASURES		
		IRE CONTROL SYS	42.1	47.06
*	481	GUN FIRE CONTROL SYSTEMS	14.5	69.16
*		MISSILE FIRE CONTROL SYSTEMS	20.0	35,90
*		UNDERWATER FIRE CONTROL SYSTEMS	3.8	
*	484	INTEGRATED FIRE CONTROL SYSTEMS	3,9	27.50
	489	WEAPON SYSTEM SWITCHBOARDS		
	490 S	PECIAL PURPOSE SYS	106.4	4.55
*	491		4.6	39.00
	492	FLIGHT CNTRL+INSTR LANDING SYS		
	493	NON-COMBAT DATA PROCESSING SYS		
	494	METEOROLOGICAL SYSTEMS		
*	495	SPEC PURPOSE INTELLIGENCE SYS	8.3	
	498	C+S OPERATING FLUIDS	86.5	-3.90
	499	REPAIR PARTS+SPECIAL TOOLS	7.0	25.62

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 6 - AUXILIARY SYSTEMS WEIGHT

SWBS	COMPONENT KILIARY SYSTEMS, GENERAL CLIMATE CONTROL COMPARTMENT HEATING SYSTEM VENTILATION SYSTEM MACHINERY SPACE VENT SYSTEM AIR CONDITIONING SYSTEM REFRIGERATION SYSTEM AUX BOILERS+OTHER HEAT SOURCES	WT-LTON	VCG-FT
500 AU	KTI TARY SYSTEMS GENERAL	520 6	23 50
510	CLIMATE CONTROL	131.0	24.97
511	COMPARTMENT HEATING SYSTEM	6.8	24.76
512	VENTILATION SYSTEM	47.2	32.39
513	MACHINERY SPACE VENT SYSTEM	8.4	33.23
514	AIR CONDITIONING SYSTEM	8,4 60.6 2.3 5.7 94.8 53.3 3.5	18.78 13.97
516	REFRIGERATION SYSTEM AUX BOILERS+OTHER HEAT SOURCES SFA WATFR SYSTEMS FIREMAIN+SEA WATER FLUSHING SYS	2.3	13.97
51/	AUX BOILERS+OTHER HEAT SOURCES	5./	21.90
521	SEA WATER SYSTEMS ETREMATH, SEA WATER ELLISHTNC SYS	94.8	21.38
521	SPRINKLING SYSTEM	3.5	25.28
	WASHDOWN SYSTEM	1.8	40.22
	AUXILIARY SEAWATER SYSTEM	110	10.122
	SCUPPERS+DECK DRAINS	1.3	38.07
527	FIREMAIN ACTUATED SERV, OTHER		
578	PLUMRING DRAINAGE	122	25.38
* 529	DRAINAGE-BALLASTING SYSTEM FRESH WATER SYSTEMS DISTILLING PLANT	21.6	25.38 12.96 24.72
530	FRESH WATER SYSTEMS	35.9	24.72
531	DISTILLING PLANT	5.0	20.94 32.21 21.74
* 532	COULING WATER	14./	32.21
533	POTABLE WATER	7.5	21.74
534	POTABLE WATER AUX STEAM + DRAINS IN MACH BOX	8.7	16.75
222	AUX STEAM + DRAINS OUT MACH BOX AUXILIARY FRESH WATER COOLING		
530	AUXILIARY FRESH WATER COULING	46 B	17 35
540	FUELS/LUBRICANTS, HANDLING+STORAGE SHIP FUEL+COMPENSATING SYSTEM	40.0	15.23
* 542	AVIATION+GENERAL PURPOSE FUELS	42.9	40.78
	AVIATION+GENERAL PURPOSE LUBO	3.3	40.70
	LIQUID CARGO		
	TANK HEATING		
	SPEC FUEL+LUBRICANTS HANDL+STOW		
	AIR, GAS+MISC FLUID SYSTEM	34.5	24.93
	COMPRESSED AIR SYSTEMS	16.3	22.38
	COMPRESSED GASES		
553	OZ N2 SYSTEM		
554	LP BLOW		
\$\$\$	LP BLOW FIRE EXTINGUISHING SYSTEMS HYDRAULIC FLUID SYSTEM	18.3	27.19
	LIQUID GASES, CARGO		
558	SPECIAL PIPING SYSTEMS		10 17
560	STEERING-DIVING CNTL SYS RUDDER	30.2	10.47
201	STEEKING+DIVING CNTE STS	16.3 33.9	20.94 5.43
562	TRIM+HEEL SYSTEMS	33.9	3.43
	MANEUVERING SYSTEMS		
570	UNDERWAY REPLENISHMENT SYSTEMS	17 9	34.94
571	UNDERWAY REPLENISHMENT SYSTEMS REPLENISHMENT-AT-SEA SYSTEMS SHIP STORES+EQUIP HANDLING SYS	10.8	37.78
572	SHIP STORES+EQUIP HANDLING SYS	10.8	30.63
573	CARGO HANDLING SYSTEMS		
574	VERTICAL REPLENISHMENT SYSTEMS		
580	MECHANICAL HANDLING SYSTEMS	66.2	36.73
581	ANCHOR HANDLING+STOWAGE SYSTEMS	66.2 29.6	29.50
582	MOORING+TOWING SYSTEMS	7.7	36.10
	BOATS, HANDLING+STOWAGE SYSTEMS	18.2	51.39
	MECH OPER DOOR, GATE, RAMP, TTBL SYS		
	ELEVATING + RETRACTING GEAR		
586			
587 * 588		E 10.7	33.10
100	, , ,	E 10.7	32.18
589	MISC MECH HANDLING SYSTEMS SPECIAL PURPOSE SYSTEMS	43.2	18.33
590 591		73.2	10.00
59Z			
593		5.2	7.81
594		3.2	/.01
595			
596	HANDLING SYS FOR DIVER+SUBMR VEH		
597			
598	AUX SYSTEMS OPERATING FLUIDS	35.4	19.76
599	AUX SYSTEMS REPAIR PARTS+TOOLS	2.7	19.79

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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D-46

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# PRINTED REPORT NO. 7 - OUTFIT+FURNISHINGS WEIGHT

SWBS	COMPONENT	WT-LTON	VCG~FT
600 OU	TFIT+FURNISHING.GENERAL	299.4	24.01
610	SHIP FITTINGS	15.0	42.76 34.96
	HULL FITTINGS	6 1	34.96
	RAILS, STANCHIONS+LIFELINES	7.1	45.68
613	RIGGING+CANVAS	1.8	34.96 45.68 57.86
670	HULL COMPARTMENTATION	77.9 25.2	21 26
620	HULL COMPARTMENTATION NON-STRUCTURAL BULKHEADS	,,,,,	27.67
622	FLOOR PLATES+GRATING	40.2	15.23
	LADDERS	40.2	24.78
		4.9	24.78
	NON-STRUCTURAL CLOSURES		
	AIRPORTS, FIXED PORTLIGHTS, WINDOWS		
	PRESERVATIVES+COVERINGS	107.8	
	PAINTING	33.3	19.02
	ZINC COATING		
	CATHODIC PROTECTION	1.1	6.00
634		26.3 32.8	25.15
635		32.8	29.37
636	HULL DAMPING	6.7	-2.50
637	SHEATHING	3.0	30.80
638	REFRIGERATION SPACES	4.6	18.08
	RADIATION SHIELDING		
640	LIVING SPACES	26.7	25.49
641	OFFICER BERTHING+MESSING	7.8	
	NON-COMM OFFICER B+M	5.1	
	ENLISTED PERSONNEL B+M	10.3	
	SANITARY SPACES+FIXTURES	2.8	
	LEISURE+COMMUNITY SPACES	2.0	28.98
+	SERVICE SPACES	.8 15.1	26.12
	COMMISSARY SPACES	6.6	
652		1.5	
		1.0	23./4
	DENTAL SPACES	<i>c</i>	20.00
	UTILITY SPACES	.6	28.98
	LAUNDRY SPACES	3.4	
	TRASH DISPOSAL SPACES	3.0	
• • •	WORKING SPACES	28.2	27.43
661	OFFICES	5.4	
	MACH CNTL CENTER FURNISHING	1.3	
663	ELECT CNTL CENTER FURNISHING	6.9	
664	DAMAGE CNTL STATIONS	3.7	31.43
665	WORKSHOPS, LABS, TEST AREAS	10.8	21.96
	STOWAGE SPACES	26.5	21.48
	LOCKERS+SPECIAL STOWAGE	8.1	
	STOREROOMS+ISSUE ROOMS	18.4	18.74
-	CARGO STOWAGE	2014	20074
	SPECIAL PURPOSE SYSTEMS	2.2	23 53
	OPERATING FLUIDS	.2	23.35
699		2.0	
099	REFAIR FARISTSFELIAL IVULS	2.0	23.17

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

D-47

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### PRINTED REPORT NO. 8 - ARMAMENT WEIGHT

	/BS	COMPONENT	WT-LTON	
	O ARM		105.6	
			53.5	34.05
		GUNS	JJ.J	54.74
		AMMUNITION HANDLING		
	713	AMMUNTTION STOWAGE		
*	720 M	ISSLES+ROCKETS	35.3	34.23
*	721	ISSLES+ROCKETS LAUNCHING DEVICES MISSILE,ROCKET,GUID CAP HANDL SYS	20.7	26.61
*	722	MISSILE, ROCKET, GUID CAP HANDL SYS	1.0	31.78
	723	MISSILE+ROCKET STOWAGE		
	724	MISSILE HYDRAULICS		
		MISSILE GAS		
		MISSILE COMPENSATING		
		MISSILE LAUNCHER CONTROL		
		MISSILE HEAT, COOL, TEMP CNTRL		
		MISSILE MONITOR, TEST, ALINEMENT		
	730 M			
		MINE LAUNCHING DEVICES		
		MINE HANDLING		
÷		MINE STOWAGE	5.0	10.40
-		EPTH CHARGES DEPTH CHARGE LAUNCHING DEVICES	5.0	39.40
		DEPTH CHARGE HANDLING		
		DEPTH CHARGE STOWAGE		
*		ORPEDOES	2.7	38.78
		TORPEDO TUBES	4. • 7	30.70
		TORPEDO HANDLING		
		TORPEDO STOWAGE		
*		MALL ARMS+PYROTECHNICS	7.7	30,94
		SMALL ARMS PYRO LAUNCHING DEV	1.0	
	762	SMALL ARMS+PYRO HANDLING		
	763	SMALL ARMS+PYRO STOWAGE	. 9	33.22
	770 C	ARGO MUNITIONS		
		CARGO MUNITIONS HANDLING		
		CARGO MUNITIONS STOWAGE		
#		IRCRAFT RELATED WEAPONS	1.4	37.78
		AIRCRAFT RELATED WEAPONS HANDL		
		AIRCRAFT RELATED WEAPONS STOW		
		PECIAL PURPOSE SYSTEMS		
		SPECIAL WEAPONS HANDLING		
		SPECIAL WEAPONS STOWAGE		
		MISC ORDINANCE SPACES		
		ARMAMENT OPERATING FLUIDS		
	799	ARMAMENT REPAIR PART+TOOLS		

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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# PRINTED REPORT NO. 9 - LOADS WEIGHT (FULL LOAD CONDITION)

SWBS	COMPONENT	WT-LTON	VCG-FT
F00 L0		1453.9	8.03 27.86 27.86 27.86 27.86 27.86
	SHIPS FORCE	270,0 27 A	77 86
	OFFICERS	22.4	27.86
F12	NON-COMMISSIONED OFFICERS	3.5	27.85
	ENLISTED MEN	15.1	27.86 27.86 27.86
	MARINES		
	TROOPS		
F16	AIR WING PERSONNEL		
F19	OTHER PERSONNEL		
F20	MISSION RELATED EXPENDABLES+SYS	100.3 93.9	32.32
* F21	SHIP AMMUNITION	93.9	31.78
	ORD DEL SYS AMMO		
* F23	ORD DEL SYS (AIRCRAFT)	6.4	40.28
F24	ORD REPAIR PARTS (SHIP)		
	ORD REPAIR PARTS (ORD)		
	ORD DEL SYS SUPPORT EQUIP		
	SPECIAL MISSION RELATED SYS		
	STORES	27.4	20.90 20.40 23.11
	PROVISIONS+PERSONNEL STORES	22.4	20.40
F32	GENERAL STORES	5.0	23.11
	MARINES STORES (SHIPS COMPLEM)		
	SPECIAL STORES		
	LIQUIDS, PETROLEUM BASED	1275.4	5.56
	DIESEL FUEL MARINE	1048.6	5.01 10.00
142	JP-5 GASOLINE	27.0	10.00
	DISTILLATE FUEL		
	NAVY STANDARD FUEL OIL (NSFO)		
	LUBRICATING OIL	199.7	7.81
	SPECIAL FUELS AND LUBRICANTS	133.7	7.01
	LIQUIDS, NON-PETRO BASED	28.5	5.25
	SEA WATER	20.5	1.27
	FRESH WATER	28.5	5.25
	RESERVE FEED WATER	10.5	
	HYDRAULIC FLUID		
	SANITARY TANK LIQUID		
	GAS (NON FUEL TYPE)		
	MISC LIQUIDS, NON-PETROLEUM		
F60	CARGO		
F61	CARGO, ORDINANCE + DELIVERY SYS		
	CARGO, STORES		
F63	CARGO, FUELS + LUBRICANIS		
F64	CARGO, LIQUIDS, NON-PETROLEUM		
	CARGO, CRYOGENIC+LIQUEFIED GAS		
	CARGO, AMPHIBIOUS ASSAULT SYS		
F67			
	CARGO, MISCELLANEOUS		
M24	FUTURE GROWTH MARGIN		
	* DENOTES INCLUSION OF PAYLOAD	OR ADJUSTMENTS	

D-49

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#### PRINTED REPORT NO. 1 - SUMMARY

COLL PROTECT SYS-PARTIAL	SONAR DOME	E-PRESENT	UNIT COMMAN	DER-NONE
FULL LOAD WT, LTON TOTAL CREW ACC HULL AVG DECK HT, FT MR VOLUME, FT3	192. 9.95 118500. PAYLOAD REQUIRED	PASSWA AC MAR SPACE AREA FT2 TOTAL REQUIRED	Y MARGIN FAC GIN FAC	0.000 0.000 0.000 VOL FT3 TOTAI ACTUAL
DKHS ONLY HULL OR DKHS	3858.0 7081.3	7744.3 41663.0	7828.9 42299.5	67164. 598974.
TOTAL	10939.3	49407.3	50128.4	666138.
SSCS GROUP	AREA FI	FZ AREA H	PERCENT	
1. MISSION SUPPORT 2. HUMAN SUPPORT 3. SHIP SUPPORT 4. SHIP MOBILITY SYSTEM 5. UNASSIGNED	12296 10978	.5 4542	.6 24.9	
TOTAL	49407	.3 7744	.3 100.0	

# PRINTED REPORT NO. 2 - MISSION SUPPORT AREA

SSCS	GROUP	TOTAL AREA FT2	DKHS AREA FT2
	MISSION SUPPORT	12296.5	AE 47 C
			4542.6
$1.1 \\ 1.11$	COMMAND, COMMUNICATION+SURV EXTERIOR COMMUNICATIONS	6888.7 150.0	1131.9
*1.111	RADIO	150.0	
1.112	UNDERWATER SYSTEMS	130.0	
	SURVEILLANCE SYS	3611 0	202.0
1.12		2611.0	291.0
*1.121 1.122	SURFACE SURV (RADAR) UNDERWATER SURV (SONAR)	669.0 1942.0	291.0
1.122	COMMAND+CONTROL		671 0
		2501.9	671.9
*1.131 1.132	COMBAT INFO CENTER CONNING STATIONS	1830.0 671.9	671.9
1.132		591.9	591.9
1.1321		80.0	80.0
1.1322	COUNTERMEASURES	1134.0	169.0
*1.14	ELECTRONIC	570.0	169.0
*1.141	TORPEDO	564.0	109.0
1.142	MISSILE	304.0	
1.145	INTERIOR COMMUNICATIONS	459.6	
1.15	ENVIRONMENTAL COTL SUP SYS	32.2	
1.16	WEAPONS	3145.3	1698.0
*1.21	GUNS	2152.0	1162.0
*1.22	MISSILES	993.3	536.0
1.23	ROCKETS	333.3	330.0
1.23	TORPEDOS		
1.24	DEPTH CHARGES		
1.25	MINES		
1.27	SPECIAL WEAPONS		
1.2/	AVIATION	1866.0	1700.0
*1.31	AVIATION LAUNCHING+RECOVERY	10.0	1700.0
1.31	LAUNCHING+RECOVERY AREAS	10.0	
1.312	LAUNCHING+RECOVERY AREAS		
1.312	AIRCRAFT HANDLING		
*1.34	AIRCRAFT STOWAGE	1700.0	1700.0
1.34	AVIATION MAINTENANCE	1700.0	1700.0
*1.30	AVIATION ORDNANCE	156.0	
1.372	CONTROL	130.0	
1.373	HANDLING		
1.374	STOWAGE		
1.38	AVIATION FUEL SYS		
1.38	AVIATION FOLL STS		
1.55	INTERMEDIATE MAINT FAC		
1.641	STOWAGE-WEAPONS		
1.7	FLAG FACILITIES		
1.73	HANDLING		
1.74	STOWAGE		
1.8	SPECIAL MISSIONS		
*1.9	SM ARMS, PYRO+SALU BAT	396.5	12.7
1.911	SM ARMS (LOCKER)	55.3	2617
1.921	PYROTECHNICS (LOCKER)	12.7	12.7
1.932	SALUTING BAT (MAGAZINE)	18.7	
1.95	LANDING FORCE EQUIP	106.9	
	Sand The French French		

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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# PRINTED REPORT NO. 3 - HUMAN SUPPORT AREA

	GROUP	TOTAL AREA FT2	
2. H		10978.3 6347.5 1821.0 1596.0 1596.0	384.4
2.1	LIVING	6347.5	340.0
2 11	OFFICER I TVINC	1821.0	340.0
2.111	BERTHING	1596.0	260.0
2.1111	SHIP OFFICER	1596.0	260.0
2.1115	FLAG OFFICER		
2.112	SANITARY	225.0	80,0
2.1121	SHIP OFFICER	225.0	
2.1125			
2.12	CPO LIVING	930.0	
2.121	BERTHING	744.0	
2.122	SANITARY	186.0	
2.13	CREW LIVING	3425.1	
2.131	BERTHING	2940.0	
2.132	SANITARY	485.1	
2 1332	RECREATION (LITRRARY)		
2.14	GENERAL SANITARY FACILITIES	110.0	
2.141	LADIES RETIRING RM	80,0	
2.142	RRIDCE WASHROOM.WC	15.0	
2.143		15.0	
2.15	BRIDGE WASHROOM+WC DECK WASHROOM+WC SHIP RECREATION FAC	61.4	
2.152			
2.152	MOTION PIC FILM+EQUIP PHYSICAL FITNESS	23.0	
2.155	PAND COUTD DM	23.0	
2.2	BAND EQUIP RM COMMISSARY	3154.4	
2.21	FOOD SERVICE	1935.8	
2.211	OFFICER (MESS+LOUNGE)	582.1	
2.212	CPO (MESS+LOUNGE)	535.6	
2.213	CREW (MESS+LOUNGE) COMMISSARY SERVICE SPACES	818.1	
2.22	COMMISSART SERVICE SPACES		
	FOOD STORAGE+ISSUE	430,5	
2.231 2.232	CHILL PROVISIONS FROZEN PROVISIONS	158.1	
2.232		57.2	
2.200	DRY PROVISIONS	215.1	
2.234 2.3		300.0	
2.3	MEDICAL+DENTAL (MEDICAL)	300.0	
2.4	GENERAL SERVICES	686.7	
2.41	SHIP STORE SPACES	246.6	
2.411	SHIP STORE	106.0	
2.412	CLOTHING+SM STORES ISSUE	17.0	
2.415	SHIP STORE STORES	123.6	
2.42	LAUNDRY FACILITIES	293,8	
2.43	DRY CLEANING+TAILOR SHOP		
2.44	BARBER SERVICE	80.0	
2.46	POSTAL SERVICE	54.4	
2.47	BRIG		
2.48	RELIGIOUS	12.0	
2.5	PERSONNEL STORES	171.4	44.4
2.51	BAGGAGE	35.0	
2.52	WARDROOM STOREROOM	14.4	14.4
2.53	CPO STORE ROOM	12.0	
2.54	COMMANDING OFFICER STRM	40.0	
2.55	FOUL WEATHER GEAR (LOCKER)	30.0	30.0
2,57	FOLDING CHAIR STOREROOM	40.0	
2.6	CBR PROTECTION	138.4	
2.7 2.9	LIFESAVING (LIFEJACKETS) POLLUTION CNTL SYS (SEWAGE)	20.0 159.9	

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 4 - SHIP SUPPORT AREA

6506	GROUP	TOTAL AREA FT2	DKHS
		ANLA FIZ	
3.	SHTP SUPPORT		1941.3
3.1	SHIP CNTL SYS(STEERING+DIVING)	619.7	
3.2	DAMAGE CNTL	473.8	
3.21	SHIP CNTL SYS(STEERING+DIVING) DAMAGE CNTL DAMAGE CNTL DAMAGE CNTL CENTRAL REPAIR STATIONS FIRE FIGHTING SHIP ADMINISTRATION AUXILIARY MACHINERY ENGINEERING AUX A/C+REFRIGERATION A/C (INC VENT) REFRIGERATION PUMP+COMPRESSOR RM DECK AUXILIARIES ANCHOR HANDLING LINE HANDLING AUXILIARY MACHINERY DELTA ELECTRICAL		
3.22	REPAIR STATIONS	243.1	
3.25	FIRE FIGHTING	230.7	
3.3	SHIP ADMINISTRATION	1299.0	
74	AUXILIARY MACHINERY	7852.9	789.5
3.41	AUXILIART MACHINERT ENGINEERING AUX A/C+REFRIGERATION A/C (INC VENT)	2073.3	789.5
3.411	A/C+REFRIGERATION	1640.2	789.5
3.411	A/C (INC VENT)	1640,2 1542.0	789.5
3.4112	REFRIGERATION	98.2	
3.411 3.417	PUMP+COMPRESSOR RM	433.1	
3.42	DECK AUXTI TARTES	612.0	
3 421	ANCHOR HANDLING	378.9	
3.421 3.422		233.1	
3.4X	AUXTETARY MACHTNERY DELTA	5167.6	
3 5	ELECTRICAL	127.9	
		121.13	
3.51 3.511	POWER GENERATION SHIP SERVICE POWER GEN		
2 517	EMERCENCY CENERATORS		
3.512 3.514	400 HERTZ PWR DIST+CNTL DEGAUSSING SHIP MAINTENANCE ENGINEERING DEPT AUX (FILTER CLEANING) ELECTRICAL		
3.52		2 0	
3.54	DECAUSSING	125.0	
3.6	SHID MAINTENAN/F	1438.9	
3.61		816 3	
2 211	AUX (FILTER CLEANING)	01013	
3 613	ELECTRICAL	133.2	
3.612 3.613	ELECTRICAL MECH (GENERAL WK SHOP) TEST LAB	533 1	
2.013	TEST LAB	60.0	
3.614 3.615		00:0	
3.62		472 7	
3.63	WEAPONS DEPT (ORDNANCE SHOP)	79.9	
	DECK DEPT (CARPENTER SHOP)	70.0	
3.64 3.7	STOREROOMS+ISSUE RMS	3540 0	354.0
3.71	SUPPY DEPT HAZARDOUS MATL (FLAM LIQ) SPECIAL CLOTHING CEN USE CONSUM PEPATE DAPI	1780 7	33 (10
3.711	HAZARDOUS MATE (FLAM LTO)	133.2	
3.712		72,5	
3.713	CEN LISE CONSUM DEDATE DART	1166.4	
3.713		408.5	
3.72		333.1	
3.72		519.3	46.6
			307.4
2.74	DECK DEPT (BOATSWAIN STORES) ACCESS (INTERIOR-NORMAL)	7012 2	797.7
2.0	WECESS (THIEVING-MONANE)	1 JTT 1 C	(3),1

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

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### PRINTED REPORT NO. 5 - SHIP MOBILITY SYSTEM AREA

SSCS	GROUP	TOTAL AREA FT2	DKHS AREA FT2
4.1 4.11 4.112-3 4.114 4.12 4.122-3 4.122-3	CONTROL STEAM (NUCLEAR) COMBUSTION AIR-EXHAUST CONTROL DIESEL COMBUSTION AIR EXHAUST	2868.2 2868.2	876.0 876.0
	GAS TURBINE COMBUSTION AIR EXHAIIST CONTROL	2868.2 827.3 1100.9 940.0	876.0 383.6 492.4

\* DENOTES INCLUSION OF PAYLOAD OR ADJUSTMENTS

# PRINTED REPORT NO. 6 - REQUIRED TANKAGE

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POLLUTION CNTRL IND-PRESENT

ENDURANCE FUEL, FT3	46244.
AVIATION FUEL, FT3	1191.
FRESH WATER, FT3	1028.
SEWAGE, FT3	385.
WASTE OIL WATER, FT3	925.
CLEAN BALLAST, FT3	12763.
TANKAGE VOL REQ, FT3	62536.

**D-**54

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# DESIGN SUMMARY

### PRINTED REPORT NO. 1 - SUMMARY

PRINCIPAL CHARACTERIS	TICS - FT	WEIGHT SUMMARY - LTOP	N
LBP	390.0	WEIGHT SUMMARY - LTO GROUP 1 - HULL STRUCTURE	1809.4
LOA	409.3	GROUP 2 - PROP PLANT	5Z1.4
LBP LOA BEAM, DWL BEAM, WEATHER DECK	55.0	GROUP 3 - ELECT PLANT	182.4
BEAM. WEATHER DECK	60.3	GROUP 4 - COMM + SURVEIL	354.8
DEPTH @ STA 10	36.5	GROUP 5 - AUX SYSTEMS	
DRAFT TO KEEL DWI	15.0	GROUP 6 - OUTFIT + FURN	299.4
DRAFT TO KEEL LWL	15.0	GROUP 7 - ARMAMENT	105.6
FREEBOARD @ STA 3	15.0 30.5		
GMT	5.5	SUM GROUPS 1-7 DESIGN MARGIN	3793.6
CP	0.650	DESIGN MARGIN	474.2
сх	0.919		
		LIGHTSHIP WEIGHT	4267.8
SPEED(KT): MAX= 26.5	SUST= 25.3	LOADS	1453.9
ENDURANCE: 4950.0 NM A		LOADS	
		FULL LOAD DISPLACEMENT	5721.8
TRANSMISSION TYPE: MAIN ENG: 4 GT @	MECH	FULL LOAD KG: FT	19.6
MAIN ENG: 4 GT @	13240.0 HP		
		MILITARY PAYLOAD WT - LTO	N 639.0
SHAFT POWER/SHAFT:	23516.1 HP	USABLE FUEL WI - LION	996.2
PROPELLERS: 2 - CP - 1	LS.S FT DIA		
		AREA SUMMARY - FT2	
SEP GEN: 1 GT @ PD GEN: 2 V5CF @	2500.0 KW	HULL AREA –	
PD GEN: 2 V5CF @	2000.0 KW	SUPERSTRUCTURE AREA -	7828.9
24 HR LOAD MAX MARG ELECT LOAD	1509.1	TOTAL AREA	50128.4
MAX MARG ELECT LOAD	3360.8		
		VOLUME SUMMARY - FT	3
OFF CPO ENL	. TOTAL	HULL VOLUME -	598974.2
MANNING 21 24 14	47 192	SUPERSTRUCTURE VOLUME -	67163.6
ACCOM 21 24 14	47 192		
		TOTAL VOLUME	666137.8

#### PRINTED REPORT NO. 2 - MANNING AND ACCOMMODATION SUMMARY

	SHIPS CREW	AIR DETACH	FLAG STAFF /OTHER		TOTAL ACCOMMODATION
OFFICERS CPO OEM	17. 23. 135.	4. 1. 12,	0. 0. 0.	21. 24. 147.	21. 24. 147.
TOTAL	175.	17.	0.	192.	192.

# PAYLOAD AND ADJUSTMENTS

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VCC KEV	-10.00	-20.00	۳. 8	-28.80	8	8.2	90.0g	8	9 8 8	-1- <b>4</b>	-10.00	1.10	1	38	3	8.52	22.8	22.00	4	8	38	31	5	8.8	8	21.00	14		38	3	8	-16.20	-28.40	8	14.0	14.60	2.70		19	08 11-			28	38			38	3 8	28	31	8	8.2		3	51	B.7-	2.2	3.5	39	3.0	55.02	2.2	25.60	2.50	7.50	16 00	3.04	
I FAC	5.90	DIO	25	MST	010	010	010	MST	5.8	₩ST	015						010	920	020		2				010	010	010				010	8	8	8	010	010	0H0			2	38	32	ŝ	3	32	3	31	â			8	ŝ	e ;		<b>a</b> 1	070	070	220				MAST	DTQ	010	8	212	ła	
400 Ju	3E.EL	9.4	15.00	2.44	2.68	0.00	I.75	<b>.</b> .	0.0	6.29	6.29	1.94	1		<b>e</b>	6.03	1.63	2.20	10.63	8			10.7	9.80 8	3.85	13.20	8			25	1.37	36.80	33.10	20.20	8.20	3.86	40		15 80	02.02		36	58	38	39		22	11	6.		6. 32	i i	21.02	5.90	4.5	1.20	2:-	8	33	, i	2	2.90	5.63	4.60	189.00	75 00		
MT KEY	M410	W532	1440	1440	264M	0440	MASI	T STM	¥452	W482	W487				W460	W471	M474	WF21	117.7			795M	28 <b>4</b> 4	18483	484M	W710			17-1M	01/M	WF21	M710	WF21	W164	W720	ME21	1220 1220	1071				MF Z L	7.844	77/M	401M	67.SM	M750	MF21	09/M	MF21	WF23	M780	N/F42	M542	W588	W588	W460	M740	WFZL	120	M452	N452	2644	M491	WF46	0117	OTTM	2
δų L		~	m	4	ŝ	v	~	*	0	9	:=	12	1	1	4	5	9	11	2	9 9	33	Ŗ	7	2	M	24	1	33	9	11	8	6	ĕ	31	32	. 2	1		2 2	2.5	2	2	<u></u>	2:	<b>‡</b> :	¥	4	1	÷.	Ŷ	4	4	4	2	3	2	2	4	5	2	52	8	6	Ş	19	15	1	
M			TACAN CUTTO									11	RDS1 NAV SYSTEM	S00-28 LA		SID-270V2 ME 35 DI 5 M/ 4		THE BO ULD SHOW CONTRICT		MOD (X) COUNTERMEASURES24RND5		TOWAHAWK WEAPON CONTROL SYSTEM	MC116 UECS	MERY) INTERDATED ECS	PALAJ UNICURATED FLO SV MUTE SAMME ANDE ANTE PHELIANY, HABVELADE	24 FRID LUFFI LIFES [FULLON-FURLENAL FURLENAL FULLES	MALE CIWS WCS	MKIE 20MM CIMS AMMOIGOORDS	2K EX-35 SEA VULCAN 25MM MOUNT W/ STINGER	25MM AMMO 2000BDS + 4X STERCER MISSILES	TA WEAR & TW/CA CITY THAM' COT		THAT A LA MARK - WOUND ADDADE I FUEL TT	THE STREET STREET AND THE OUT AND LEVEL 11	STATE TO A CONTRACT OF A CONTR								ž			×	¥	SMAL		1X LA	HELD REARM AND MACAZEN	C I H		DACT SYSTEM		ž	MORTAR SYSTEM		FURUNO RADAR	MK23 TAS					_	HELO DECK CORRECTION		
ð.	-	N	n ,	r v	n w			. a	n c	ο,	e la	~	m	*			, r		æ	s,	0	-	5	4 (7	n •	r,	n	ø	~		۰o	n c	) <del>,</del>	• •	•	m.	4	n	ø	~		<b>م</b>	0	~		m			ι uπ		. 65		ı.c		•	ı a								<b>.</b> .	-		ŝ	ł

D, FT2 SS/ONLY	8	8,8	38	8	88		8.0 8	8	8,8	38	169.00	38. 78	8,8	38	8	88	321.00	8.8 8	120.00	8	8 8		88	8	88	8	88	8	88	8	88	8	88	8,8	88	8 <sup>.</sup> 8	38	8,8	8. 02 8. 02	21.00	ខុខ	38	8.
AREA AXD HULL/SS	1830.00	8.8	00.18	8	88	8	8,8	8	8,8	<u>8</u> 9	8.1	- 0	352.00		8 <u>.</u>	88	8	88	<u>3</u> 8	8.5	202.00	8	88	8	88		32.8 8.8	75.00	88	8	203.00	-	156.00	8 <sub>8</sub> 8	9	8 8 8	38	8	38	8.8		00-00-T	3200.00
AREA KEY	ALIBL	NONE	INDN	NONE	NONE A1121	NONE	AIIZL	NON	NONE	NON	A1141	NON	A1142	AL121	NONE	NONE	A1210	A1210	AL210	NONE			NONE	NON	NONE	A1220	A1220 A1220	A1220	NONE	NONE	A 1900			NONE	OTELV	NONE	NONE	NONE	ALIZI	A1121	NONE	NONE	
ž	-	~ •	• 4	5	6 r	-	φĉ	13	22	13	5	11	8	28	23	22	5	22	32	82	28	#1	28	<b>*</b>	5 10 M M	93	80 00 10 00	ę	4 4	4	<b>\$</b> 4	÷	7	<b>\$</b> 7	22	33	3	3	85	80 G	8	55	69

s CRUISE	₹.	8-8 9-8			02.E	2	79.00	50.30	00'E	88	01.11	1.20	10.8	8	8:	2.9		14.80 55	8.5	39	8	36.60	88	10.00	88	12.10	8.5	28	15.00	8 5	8	នុខ	38		00.2	8	88	88		88	39		÷, •	12.00		88
N BATTLE		8.8					29.00	85.50	4.00	6.60	02.62	1.20	21.00	8	6.4	6.20	Ē	ō٩	9.01 1	20.02	8; ;	20.20	38		88		8.	28		8 S		9.7 7		-	02.2	2	ō	28	-	88	39	١Ō,		88		88
KW ADO, W CRUISE	17.40	8 S		8.		22.	20.02	02.02	90.m	4	11.10		2,21	R	22	2014		1.0	2.5	ŝŝ	Ŗ	36.60	88	10.00	<u>e</u> e	12.10	8,5	28	15.00	Ŗ P	38	ន់រ	ŖŖ	R,	06.1	8	22	22	8	88	33		82	12.00	8	88
τεν Keγ	ł	Ň	33	st.	££	£	£;	ŧŧ	t;	ŝ	££	NONE		NONE	ş	£3	ts t	ARM	ARM	ARM	NON	ARM	NONE	ARM	NON	ŝ	NONE	NONE	C†S	NONE	NON	ARM	NON	Nove	f Mar	NONE	NONE	XOM	NONE	ARM		3	ŝ	33 33	NONE	NONE
₩OK		N# 14	•	ŝ	0 1	. 10	n ;	33	3	5	4 1	2:	2 19	5	22	32	ន	23	22	22	2	5 2	25	81	2	18	8:	28	8	<del>2</del> 4	4	43	f ¥	\$:	<b>}</b> 4	Ş	22	12	Ω.	x :	3	5	88	×8	ថ	66

# PERFORMANCE ANALYSIS

#### PRINTED REPORT NO. 1 - SUMMARY

PERF DISP IND	FULL LOAD	MATN FNG NO	4.
TOWED BODY IND	NONE	MAIN ENG TYPE IND	GT
SHIP FUEL TYPE IND	JP-5	MAIN ENG PWR AVAIL, HP	13240.
PROP TYPE IND	CP	SEC ENG NO	0.
NO PROP SHAFTS	2.	SEC ENG TYPE IND	
SIG WAVE HT, FT	0.00	SEC ENG PWR AVAIL, HP	
MONTHS IN SERVICE	0.00	SS ENG NO	1.
HULL FOULING FAC	0.011	SS ENG TYPE IND	GT
PROP FOULING FAC	0.000	24 HR AVG ELECT LOAD, KW	1509.1
ANNUAL FUEL USAGE, BBL	0.	TRANS TYPE IND	MECH

#### SPEED PERFORMANCE SUMMARY

SPEED KT	DRAG LBF	RANGE NM	req Bhp Hp	ENG	PLN 0/L SC	SFC LBM/HP-HR	FUEL FLOW LTON/HR	FUEL CONS PROP NM/LTON COEF	TRNSP EFF
16.0	121097.	6509.	9318.	2	0	.610	2.44	6.5 0.664	67.5
17.0	133170.	6280.	10861.	2	0	. 577	2.69	6.3 0.665	61.6
18.0	149390.	5939.	12894.	2	0	.543	3.01	6.0 0.665	54.9
19.0	171606.	5485.	15648.	2	0	.511	3.44	5.5 0.663	47.8
20.0	185361.	5285.	17726.	2	0	. 492	3.76	5.3 0.665	44.4
21.0	206871.	4940.	20762.	2	0	.471	4.22	5.0 0.664	39.8
22.0	223398.	3906.	23424.	- 4	0	.553	5.59	3.9 0.665	36.9
23.0	242897.	3753.	26579.	4	0	.529	6.08	3.8 0.666	34.0
24.0	266843.	3568.	30450.	4	0	.506	6.68	3.6 0.665	31.0
25.0	303013.	3294.	36110.	4	0	.481	7.53	3.3 0.662	27.2
26.0	347426.	3003.	43240.	4	0	.457	8.60	3.0 0.658	23.6
26.5	372310.	2858.	47329.	4	0	.447	9.20	2.9 0.656	22.0

#### PRINTED REPORT NO. 2 - MISSION PERFORMANCE SUMMARY

ANNUAL FUEL USAGE, BBL 56172.

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MISSION SPEED KT PERCENT	PROFILE SIC HT-FT	S WAV PERCENT	RANGE NM	FUEL FLOW LTON/HR	FUEL CONS NM/LTON	PROPUL COEF	TRNSP EFF
6.0 11.9 14.0 46.6 20.0 35.6 25.0 4.4 30.0 1.5	0.0 4.0 6.5 10.2 17.0	1.7 15.7 11.6 42.0 29.0	5773.	2.98	5.8	0.655	96.6

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D-57

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# PRINTED REPORT NO. 3 - DETAILED MISSION PERFORMANCE

SIG WAVE HT, FT = 0.0 PROBABILITY OF OCCURANCE, PCNT = 1.7	SPEED KT	PROBABILITY PCNT	DRAG LBF	HP	FUEL CONS NM/LTON
	6.0 14.0 20.0	11.9 46.6 35.6	20038. 106890. 185361.	588. 7307. 17726.	6.5 6.6 5.3
	25.0 27.1	35.6 4.4 1.5	303013. 404997	36110. 52960.	3.3 2.7
SIG WAVE HT, FT = 4.0 PROBABILITY OF OCCURANCE, PCNT = 15.7	SPEED KT	PROBABILITY PCNT	DRAG LBF	REQ PROP HP	FUEL CONS NM/LTON
UCCURANCE, $P(N) = 13.7$	6.0 14.0 20.0	11.9 46.6 35.6	107117.	590. 7324. 17767.	6.5 6.6 5.3
	25.0 27.1	35.6 4.4 1.5		36194. 52960.	3.3 2.7
SIG WAVE HT, FT = 6.5 PROBABILITY OF OCCURANCE, PCNT = 11.6	SPEED KT	PROBABILITY PCNT	DRAG LBF	req prop Hp	FUEL CONS NM/LTON
ULUKANLE, FLNI = 11.6	6.0 14.0 20.0 25.0 27.1	46.6 35.6 4.4	20181. 107656. 186690. 305187. 405437.	593. 7365. 17864. 36392 52960.	6.5 6.6 5.3 3.3 2.7
SIG WAVE HT, FT = 10.2 PROBABILITY OF	KT	PROBABILITY PCNT	DRAG LBF	REQ PROP HP	FUEL CONS NM/LTON
OCCURANCE, PCNT = 42.0	6.0 14.0 20.0 25.0 27.0	11.9 46.6 35.6 4.4	20481. 109254.		6.4 6.5 5.2 3.3 2.7
SIG WAVE HT, FT = 17.0 PROBABILITY OF OCCURANCE. PCNT = 29.0	SPEED ĸT	PROBABILITY PCNT	DRAG LBF	REQ PROP	FUEL CONS
UCCURANCE, PUNI = 29.0	6.0 14.0 20.0 25.0 26.6	46.6 35.6 4.4	21628. 115370. 200067. 327054. 410068.	641. 7962. 19259. 39256. 52960.	6.3 6.3 5.0 3.1 2.6

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# HYDROSTATIC ANALYSIS

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#### PRINTED REPORT NO. 1 - SUMMARY

DISPLACEMENT, LTON	5721.8	MAX AREA STA LOC FM FP,FT	213.05
LCG LOC(+VE FWD MID), FT	-5.85	AREA AT MAX AREA STA, FT2	756.5
MIDSHIP DRAFT, FT	14.85	BEAM AT MAX AREA STA, FT	55.06
TRIM(+ 8Y STERN), FT	Z.36	DRAFT AT MAX AREA STA, FT	14.96
KG, FT	19.59	BLOCK COEF	0.599
SHIP LBP, FT	390.00	PRISMATIC COEF	0.653
METACENTRIC HT(GM), FT	5.57	SECTIONAL AREA COEF	0.918
WATERPLANE AREA, FT2	16895.4	WATERLINE LENGTH, FT	389.37
WETTED SURF AREA, FT2	22701.1		

#### PRINTED REPORT NO. 2 - HYDROSTATIC VARIABLES OF FORM

	TOTAL	APPDC	TOTAL			
			DISPL		~ ~	LCE.
DRAFT FT	VOLUME FT3	VOLUME FT3	LTON	LCB FT	KB FT	LCF FT
12.85	166615.	7829.	4763.6	-2.53	7.04	-21.27
13.14	171350	7842.	4899.0	-3.06	7.21	-22.01
13.43	176113.	7853.	5035.1	-3.57	7.38	-22.45
13.71	180896.	7862.	5171.9	-4.08	7.54	-22.63
14.00	185691.	7868.	5309.0	-4.55	7.71	-22.61
14.28	190495.	7871.	5446.3	-5.01	7.88	-22.58
14.57	195306.	7871.	5583.9	-5,44	8.04	-22.55
14.85	200129.	7871.	5721.8	-5.85	8.20	-22.52
15.14	204963.	7871.	5860.0	-6.24	8.37	-22.48
15.43	209809.	7871.	\$998.5	-6.62	8.53	-22.45
15.71	214666.	7871.	6137.4	-6.97	8.69	-22.40
16.00	219536.	7871.	6276.6	-7.31	8.85	-22.36
16.28	224416.	7871.	6416.1	-7.64	9.02	-22,31
16.57	229307.	7871.	6556.0	-7.95	9.18	-22.27
16.85	234209.	7871.	6696.1	-8.25	9.34	-22.22
			ONLY			
	WETTED	BLOCK	PRISMATIC	WPLANE	WPLANE	
DRAFT	SURFACE	COEFF	COEFF	COEFF	AREA	TP1
FT	FT2	-	-	-	FT2	LTON/IN
12.85	20985.3	0.571	0.633	0.768	16511.1	39.34
13.14	21281.5	0.575	0.636	0.773	16625.1	39.61
13.43	21549.2	0.579	0.639	0.777	16707.3	39.81
13.71	21793.6	0.583	0.642	0.780	16762.2	39.94
14.00	22019.8	0.587	0.645	0.782	16794.3	40.01
14.28	22246.1	0.591	0.647	0.784	16822.3	40.08
14.57	22473.3	0.595	0.650	0.786	16855.8	40.16
14.85	22701.1	0.599	0.653	0.788	16895.4	40.25
15.14	22928.9	0.603	0.655	0.790	16936.1	40.35
15.43	23156.8	0.606	0.658	0.791	16977.8	40.45
15.71	23384.6	0.609	0.660	0.793	17019.4	40.55
16.00	23612.3	0.612	0.662	0,794	17060.1	40.65
16.28	23839.7	0.615	0.665	0.796	17099.4	40.74
16.57	24067.1	0.617	0.667	0.797	17137.8	40.83
16.85	24294.5	0.620	0.669	0.798	17175.2	40.92
DRAFT	CID1TS	LONG BM	TRNSV BM	LONG KM	TRNSV KM	MT1
FT	NM/LTON	FT	FT	FT	FT	FT-LTON/IN
12.85	25.74	870.75	19.50	877.79	26.54	886.3
13.14	26.83	863.81	19.14	871.02	26.35	904.2
13.43	27.49	852.24	18.79	859.61	26.17	916.9
13.71	27.81	837.30	18,42	844,85	25.97	925.3
14.00	27.84	820.01	18.03	827.72	25.74	930.2
14.28	27.84	803.28	17.66	811.16	25.53	934.8
14.57	27.86	787.43	17.30	795.47	25.34	939.5
14.85	27.89	772.30	16.96	780,50	25.17	944.2
15.14	27.92	757.79	16.64	766.16	25.01	948.8
15.43	27.94	743.88	16.35	752.42	24.88	953.5
15.71	27.95	730.55	16.06	739.25	24.75	958.1
16.00	27.96	717.72	15.78	726.58	24.64	962.6
16.28	27.97	705.29	15.52	714.31	24.53	966.9
16.57	27.98	693.30	15.26	702.48	24.44	971.2
		681.73	15.01	-	24.35	975.4
16.85	27.98	001./J	12.01	691.07	44.33	J/J.4

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#### PRINTED REPORT NO. 3 - FLOODABLE LENGTH

LOCATION PERM FROM FP,FT 0.95 57.79 154.20 58.50 152.81 78.00 131.13 97.50 128.71 117.00 135.73 136.50 149.48 156.00 169.10 175.50 193.63 195.00 215.00 214.50 213.55 234.00 139.46 253.50 160.31 273.00 139.46 292.50 122.35 331.50 105.51 337.93 104.14

#### PRINTED REPORT NO. 4 - INTACT STATIC STABILITY

INTACT WIND SPEED, KT	100.00	LAT RESIST CENTER, FT	7.43
SAIL AREA, FT2	11380.3	TURN SPEED, KT	26.49
SAIL AREA FACTOR	1.25	TURN RADIUS, FT	818.63
SAIL AREA CTR ABV WL, FT	16.98	TURN HEEL ANGLE, DEG	10.04
WIND ARM RATIO	0.17	TURN ARM RATIO	0.23
WIND AREA RATIO	7.20	TURN AREA RATIO	0.79
WIND LEVER ARM, FT	0.75	TURN LEVER ARM, FT	1.02
WIND LIMITING KG, FT	24.08	TURN LIMITING KG, FT	21.72

TABLE OF INTACT RIGHTING ARMS(GZ), DRAFTS, AND TRIMS, FT

HEEL, DEG 0.00 5.00 10.00 20.00 30.00 40.00 50.00 60.00 70.00 80.00

 CZ
 0.00
 0.49
 1.00
 2.05
 3.04
 3.90
 4.38
 4.16
 3.50
 2.56

 TRIM
 2.36
 2.35
 2.28
 1.83
 0.86
 -0.72
 -2.90
 -6.37
 -12.74
 30.10

 DRAFT
 14.85
 14.84
 14.79
 14.56
 13.97
 12.65
 10.24
 6.37
 -0.93
 -22.26

#### PRINTED REPORT NO. 5 - DAMAGED STATIC STABILITY

LAT RESIST CENTER, FT	10.26	DAMAGED WIND SPEED, KT	34.02
SAIL AREA, FT2	8959.1	STATIC HEEL ANGLE, DEG	0.00
SAIL AREA FACTOR	1.25	AREA RATIO	21.01
SALL AREA CIR ABV WL, FI	14./1	MIN WL-MRGN LINE SEP, FT	15.36
WIND LEVER ARM, FT	0.07	LIMITING KG, FT	24.49

COMPARTMENT DESCRIPTIONS

COMP	SYMMETRY	PERM	FBHD, FT	ABHD, FT
1	0	0.950	-19.31	19.50
2	0	0.950	19.50	42.76
3	0	0.950	42.76	66.02
4	0	0.950	66.02	89.29
5	0	0.950	89,29	112.55
6	0	0.950	112.55	148.33
7	0	0.950	148.33	177.58 *
8	0	0.950	177.58	213.15 *
9	0	0.950	213.15	242.40 *
10	0	0.950	242.40	282.88
11	0	0.950	282.88	309.66
12	0	0.950	309,66	336.44
13	0	0.950	336.44	363.22
14	0	0.950	363.22	390.00
* DENO	TES COMP/	ARTMENT	IS DAMAG	ED.

TABLE OF DAMAGED RIGHTING ARMS(GZ), DRAFTS, AND TRIMS, FT

HEEL, DEG						-			40.0	45.0
GZ	0.00	0.35	0.71	1.10	1.52	1.97	2.48	2.98		
TRIM DRAFT			-2,40							

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# PRINTED REPORT NO. 6 - APPENDAGES

		TOTAL	TOTAL	C	ENTROID	
APPENDAGE	RADIUS	VOLUME	DISP	COOR	DINATES,	FT
	FT	FT3	LTON	х	Y	Z
1 SHELL	5.89	857.	24.5	200.85	0.00	8.58
Z SKEG	2.30	51.	1.5	299.09	0.00	0.72
3 BILGE KEEL	3.33	155.	4.4	195.00	26.78	7.38
4 BILGE KEEL	3.33	155.	4.4	195.00	-26.78	7.38
5 PROP ETC	4.39	355.	10.1	357.93	11.63	-0.34
6 PROP ETC	4.39	355.	10.1	357.93	-11.63	-0.34
7 SONAR DOME	11.13	5771.	165.0	14.00	0.00	-3.20
8 RUDDER	2.74	86.	2.5	383.09	11.63	5.43
9 RUDDER	2.74	86.	2.5	383.09	-11.63	5.43

D-61

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# SEAKEEPING ANALYSIS

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## PRINTED REPORT NO. 1 - SUMMARY

	FULL LOAD
BALES RANK	
RANK OF THE SYNTHESIZED SHIP (ACTUAL DISP)	7,746
RANK OF THE SYNTHESIZED SHIP (NORMALIZED)	3.206
RANK OF THE CLOSEST DATA BASE HULL (NORMALIZED)	3.460
ID NO OF CLOSEST DATA BASE SHIP	3
MCCREIGHT RANK	
RANK OF THE SYNTHESIZED SHIP (ACTUAL SHIP)	5.083
RANK OF THE CLOSEST DATA BASE HULL	5.654
ID NO OF CLOSEST DATA BASE SHIP	34

### PRINTED REPORT NO. 2 - SHIP GEOMETRY DATA

FULL LOAD WT, LTON 5721.8

	FULL LOAD
ACTUAL SHIP	
LBP, FT	390.00
BEAM, FT	54.87
DRAFT. FT	14.99
VERT PRISMATIC COEF (FWD)	0.8464
VERT PRISMATIC COEF (AFT)	
WATERPLANE COEF (FWD)	0.6711
WATERPLANE COEF (AFT)	0.9088
WP AREA AFT MIDSHIPS, FT2	9723.66
LCB FROM FP, FT	196.16
LCF FROM FP, FT	216.54
BML, FT	806.48
CUT-UP PT FROM FP, FT	248.63
NORMALIZED SHIP	
DISP, LTON	4232.1
LBP, FT	352.70
BEAM, FT	49.62
DRAFT, FT	13.55
CUT-UP PT FROM FP, FT	224.85

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MANNING ANALYSIS NOTE-THIS INTERIM MANNING MODEL PROVIDES GROSS TREND ANALYSIS BASED ON HISTORICAL MANNING DATA OF EXISTING SHIPS. REQUESTS FOR SHIP MANNING DETERMINATION SHOULD BE DIRECTED TO NAVSEA.

#### PRINTED REPORT NO. 1 - SUMMARY

TOTAL MMHRS REQ/WK	14125.6	NO WATCH STA	IDERS	37.
TOTAL MMHRS AVAIL/WK	11316.0	NO WATCHSTAN		111.
DEFERRED MMHRS/WK	2809.6	NO NON-WATCH		47.
	OFFICER	s cpo	ENLISTED	TOTAL
REQ MANNING	21.	17.	215.	253.
AVAIL MANNING	21.	24.	147.	192.
DIFFERENCE	0.	7.	-68.	-61.
ACCOMMODATIONS	21.	24.	147.	192.

#### PRINTED REPORT NO. 2 - MANNING AND ACCOMMODATION SUMMARY

	SHIPS CRFW	AIR DETACH	FLAG STAFF /OTHER	ACCOMMODATION
OFFICERS	17.	4.	0.	21.
CP0	23.	1.	. 0.	24.
OEM	135.	12.	0.	147.
TOTAL	175.	17.	. 0.	192.

#### PRINTED REPORT NO. 3 - DEPARTMENTAL MANNING ANALYSIS

DEPARTMENT	MANNING FACTOR	OFFICERS	CP0	ENLISTED	TOTAL
CO/EXEC/NAV/MED	1.0	3.	3.	13.	19.
OPERATIONS	1.0	3.	3.	60.	66.
COMBAT	1.0	5.	5.	54.	64.
ENGINEERING	1.0	4.	3.	44.	51.
SUPPLY	1.0	2.	۷.	32.	36.
AVIATION	1.0	4.	1.	12.	17.
FLAG STAFF/OTHER		0.	0.	0.	0.
REQ MANNING		21.	17.	215.	253.
AVAIL MANNING		21.	24.	147.	192.
DIFFERENCE		0.	7.	-68.	-61.

#### PRINTED REPORT NO. 4 - WEEKLY FUNCTIONAL WORKLOAD ANALYSIS

FUNCTION	WORKLOAD FACTOR		WEEKLY MHRS AVAIL	PERCENT
OPERATIONAL MANNING (OM)	1.0	5756.2		40.8
PLANNED MAINTENANCE (PM)				
+ CORRECTIVE MAINTENANCE (CM)	1.0	1871.7		13.3
OWN UNIT SUPPORT (OUS)	1.0	2911.9		20.6
FACILITY MAINTENANCE (FM)	1.0	1196.3		8.5
PRODUCTIVITY ALLOWANCE (PA)	1.0	1196.0		8.5
SERVICE DIVERSION ALLOWANCE (SDA)				
+ TRAINING (T)	1.0	1193.5		8.4
TOTAL MMHRS REQ/WK		14125.6		100.0
WATCHSTANDERS (74HRS/MAN-WK)			8214.0	
NON-WATCHSTANDERS (66HRS/MAN-WK)			3102.0	
TOTAL MMHRS AVAIL/WK			11316.0	80.1
DEFERRED MMHRS/WK			2809.6	19.9

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COST ANALYSIS REGARDING SHIP DESIGN TRADEOFFS AND COMPARATIVE EVALUATIONS. REQUESTS FOR ESTIMATES OF SHIP COSTS FOR BUDGETARY PURPOSES SHOULD BE DIRECTED TO NAVSEA.

#### PRINTED REPORT NO. 1 - SUMMARY

YEAR \$	1992.	NO OF SHIPS ACQUIRED	10.
INFLATION ESCALATION FAC	1.384	SERVICE LIFE, YR	30.0
LEARNING RATE	0.970	ANNUAL OPERATING HRS	2500.0
FUEL COST, \$/GAL	0.800	MILITARY P/L, LTON	545.4
PAYLOAD FUEL RATE, LTON/HR	0.33	LIGHTSHIP WT, LTON	4267.9
SHIP FUEL RAIE, LION/HR	1.00	FULL LOAD WT, LTON	57Z1.8

	COSTS(MILL	IONS OF D	OLLARS)
COST ITEM	TOT SHIP +	PAYLOAD	= TOTAL
LEAD SHIP	576.6	232.5*	809.1
FOLLOW SHIP	269.5	206.5*	476.0
AVG ACQUISITION COST/SHIP(10 SHIPS)	259.1	209.1*	468.2
LIFE CYCLE COST/SHIP(30 YEARS)			1266.1
TOTAL LIFE CYCLE COST(30 YEARS)			12661.1
DISCOUNTED LIFE CYCLE COST/SHIP			84.2**
DISCOUNTED TOTAL LIFE CYCLE COST			842.4**

\*ESTIMATED VALUE \*\*DISCOUNTED AT 10 PERCENT

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### PRINTED REPORT NO. 2 - UNIT ACQUISITION COSTS

PKIN	IED KEPUKI NU. Z -	UNTI N	ICTOTAT	TON CO:	212	
					LEAD	FOLLOW
					SHIP	SHIP
SWBS				KN	COSTS	COSTS
GROUP		UNITS	INPUTS	FACTORS	\$K	\$K
100	HULL STRUCTURE	LTON	1809.4		15377.	14454.
200	PROPULSION PLANT	HP	52960.0	2.35	39611.	37234.
300	ELECTRIC PLANT	LTON	182.4	1.00	11860.	11148.
400	COMMAND+SURVEILLANCE	LTON	354.8	3.15	17741.	16677.
500	AUX SYSTEMS	LTON	520.6	1.53	26717.	25114.
600	OUTFIT+FURNISHINGS	LTON	299.4	1.00	11924.	11 <b>2</b> 09.
700	ARMAMENT	LTON	105.6		1153.	1084.
	MARGIN	LTON	474.2		15548.	14615.
800	DESIGN+ENGINEERING			26.06	216856.	23962.
900	CONSTRUCTION SERVICES			4.25	35844.	33693.
	TOTAL CONSTRUCTION COST				392629.	189189.
	CONSTRUCTION COST				392629.	189189.
	PROFIT(10.0 PERCENT	OF CONS	TRUCTTON	COST)	39263.	
	PRICE				431892.	
	CHANGE ORDERS(12/8	PERCENT	OF PRICE	)	51827.	16649.
	NAVSEA SUPPORT (2,5				10797.	5203.
	POST DELIVERY CHARG	ES(S PER	CENT OF	PRICE)	21595.	10405.
	OUTFITTING(4 PERCEN			-	17276.	8324.
	H/M/E + GROWTH(10 P				43189.	20811.
	TOTAL SHIP COST				576576.	269500.
	ESTIMATED PAYLOAD COST				232489.	206457.
SHIP	PLUS PAYLOAD COST				809064.	475957.
	TED FIRST UNIT SHIP COS	T. SK	286701.9			
	T SYSTEM WEIGHT, LTON	•	545.4			
	JLSION SYSTEM WEIGHT, LT	ON	521.4			
ADJUS	STED FIRST UNIT SHIP COS	T EQUALS				
FOLL	OW SHIP TOTAL COST DIVI	DED BY	0.940			

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### PRINTED REPORT NO. 3 - LIFE CYCLE COSTS

IOC YEAR	2010.	PAYLOAD FUEL RATE, LTON/HR	0.33
R+D PROGRAM LENGTH, YRS	0.	SHIP FUEL RATE, LTON/HR	1.00
NUMBER OF SHIPS ACQUIRED	10.	TECH ADV COST, \$M	0.00
SERVICE LIFE, YRS	30.	ADDL FACILITY COST, \$M	0.00
NO OF OFFICERS/SHIP	21.	DEFERRED MMHRS REQ, HR/WK	0.
NO OF ENLISTED MEN/SHIP	171.	PRODUCTION RATE, SHIPS/YR	2.00

#### 30 - YEAR SYSTEMS COST (MILLIONS OF YEAR 1992 DOLLARS)

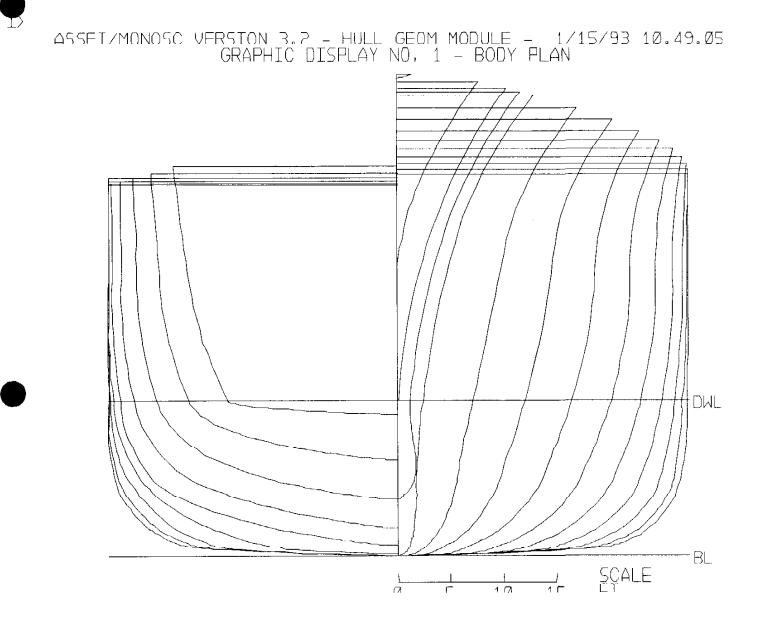
(MILLIONS OF YEAR 1992						
	SHIP	PAYLOAD	OTHER	TOTAL	SYSTEM	TOTAL
COST ELEMENT	NONREC	NONREC	NONREC	NONREC	RECUR	SYSTEM
R+D TOTAL	0.	0.	0.	0.		0.
DESIGN+DEVELMNT TEST+EVALUATION	0.		0.	0.		0.
TEST+EVALUATION	0.	0.	0.	0.		0.
INVESTMENT	2798.	2781.	4.	5583.		5583.
EQUIPMENT	2721.	2509.		5229.		5229.
PRIME	2591.			4682.		4682.
SUPPORT		418.		548.		548.
FACILITIES			0.	ο.		ο.
INITIAL SPARES	78.	272.		350.		350.
ASSOCIATED SYS			4.	4.		4.
OPERATIONS+SUPPRT					7405.	7405.
PERSONNEL					1048.	1048.
OPERATIONS					716.	716.
MAINTENANCE					2174.	2174.
ENERGY					204.	204.
REPL SPARES						2272.
MAJOR SUPPORT					976.	976.
ASSOCIATED SYS					15.	15.
LESS RESIDUAL VALU	JE					327.
LIFE CYCLE TOTAL	SYSTEMS CO					12661.
DISCOUNTED AT 10 F						842.
COST PER VEHICLE-U		FD 126	6			
COST PER VEHICLE-			4.			

D-65

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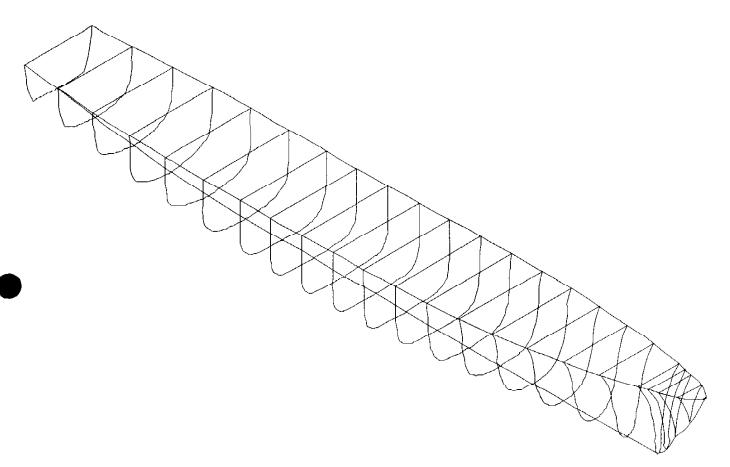
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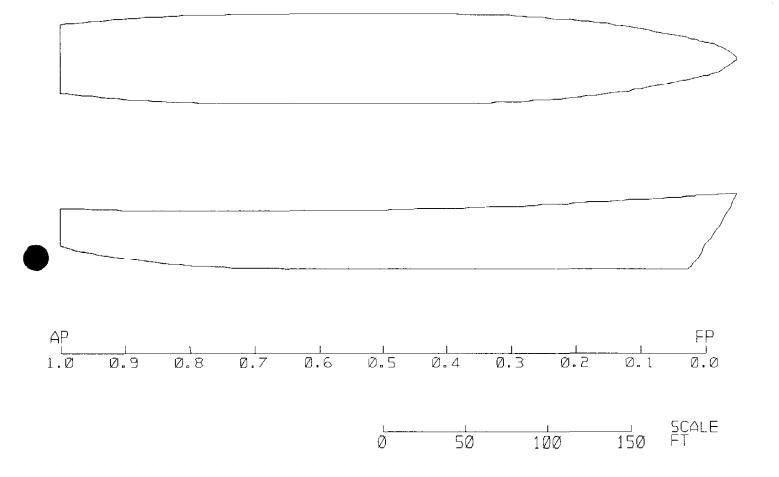
I) ASSET/MONOSC VERSION 3.2 - HULL GEOM MODULE - 1/15/93 10.49.05. GRAPHIC DISPLAY NO. 2 - HULL ISOMETRIC VIEW



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ASSET/MONOSC VERSION 3.2 - HULL GEOM MODULE - 1/15/93 10.49.05. GRAPHIC DISPLAY NO. 3 - HULL PROFILE AND WEATHER DECK PLAN VIEW

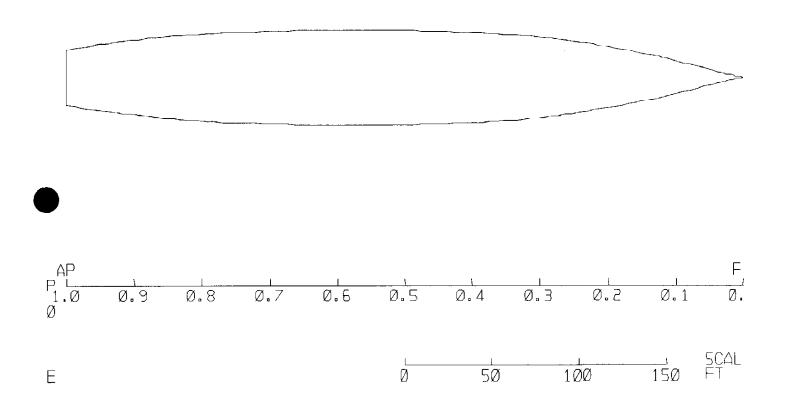
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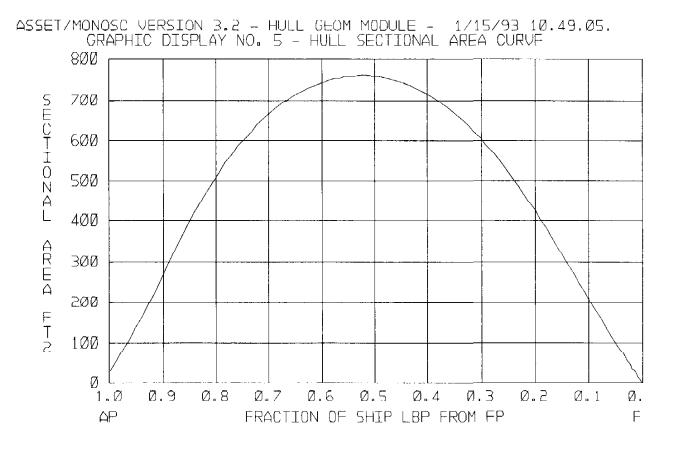
D-68

ASSET/MONOSC VERSION 3.2 — HULL GEOM MODULE — 1/15/93 10.49.05. GRAPHIC DISPLAY NO. 4 — DESIGN WATERLINE PLAN VIEW

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**D-**69

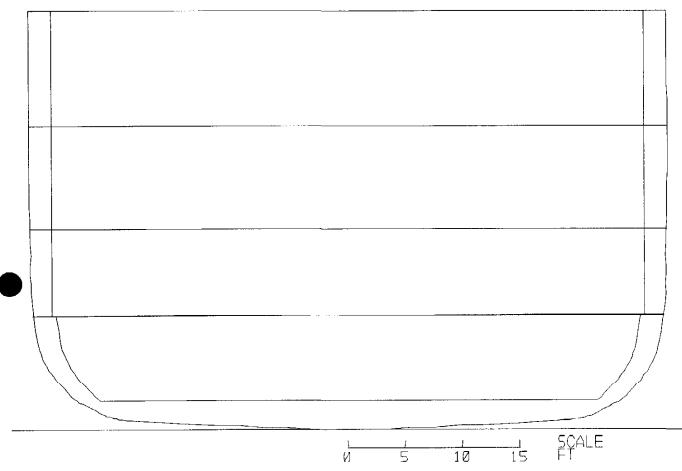


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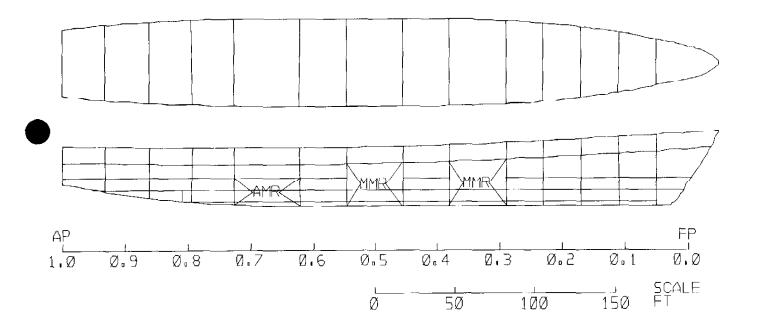
ASSET/MONOSC VERSION 3.2 - HULL SUBDIV MODULE - 1/14/93 14.14.14. GRAPHIC DISPLAY NO. 1 · MTDSHTP SECTION



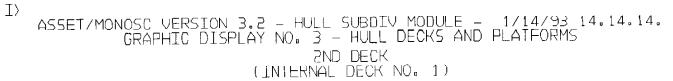
# ASSET/MONOSC VERSION 3.2 - HULL SUBDIV MODULE - 1/14/93 14.14.14. GRAPHIC DISPLAY NO. 2 - HULL DECKS AND PLATFORMS MAJN DECK

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TOTAL AREA, FT2	19563.4
HULL VOLUMÉ, FT3	59897Ø.



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			)TAL AR NUSABLE NUSABLE DST MR DST REQ JL ARR		Z FWD, FT AFT, FT FT2 GE AREA FT2	2 2 , FT2		0.0 0.0 0.0 0.0 		
					MMR		1R			
АР  1.Ø	 Ø.9	<u>1</u> Ø 1 8	0.7	 Ø.6	Ø.5 Ø	Ø.4 50	Ø.3 1	0.2 00	Ø. 1 150	FP Ø.Ø SCALE FT

D-73

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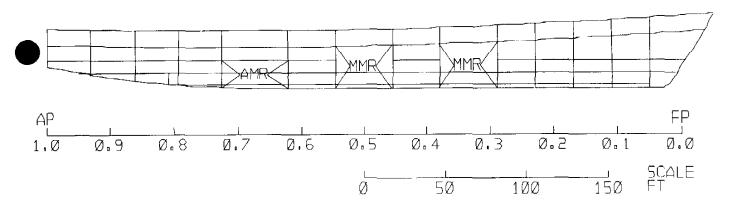
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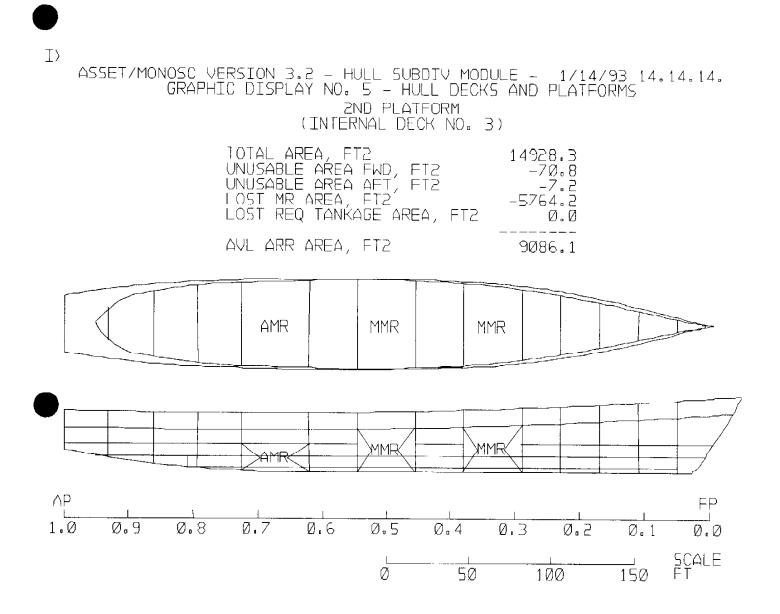
## ASSET/MONOSC VERSION 3.2 - HULL SUBDIV MODULE - 1/14/93 14.14.14. GRAPHIC DISPLAY NO. 4 - HULL DECKS AND PLATFORMS 1ST PLATFORM (INTERNAL DECK NO. 2)

TOTAL AREA, FT2	17254.4
UNUSABLE AREA FWD, FT2	−100.3
UNUSABLE AREA AFT, FT2	Ø.Ø
LOST MR AREA, FT2	-3769,9
LOST REQ TANKAGE AREA, F12	Ø.Ø
AVL ARR AREA, FT2	13384.2





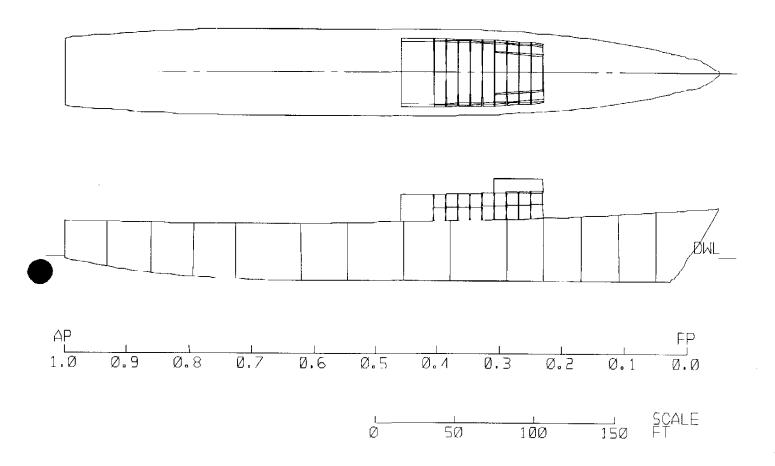
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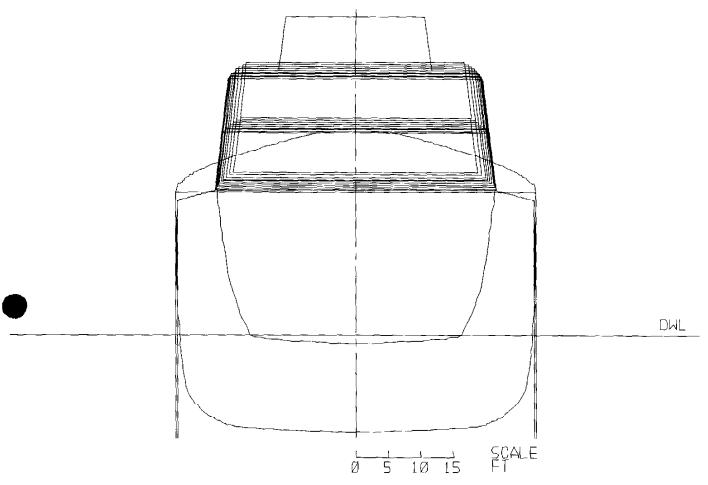
ASSET/MONOSC VERSION 3.2 - DECKHOUSE MODULE - 1/15/93 09.09.51. GRAPHIC DISPLAY NO. 1 - DECKHOUSE PROFILE AND PLAN VIEWS

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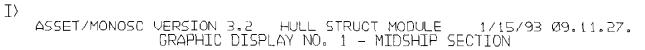


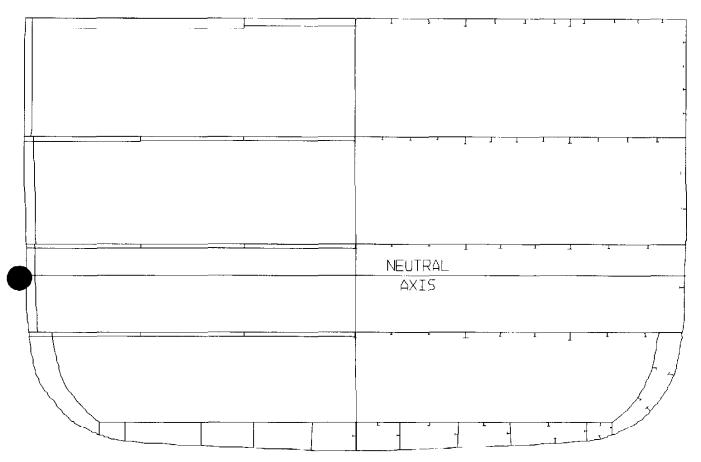


ASSET/MONOSC VERSION 3.2 - DECKHOUSE MODULE - 1/15/93 Ø9.Ø9.51. GRAPHIC DISPLAY NO, 2 - DECKHOUSE END VIEW



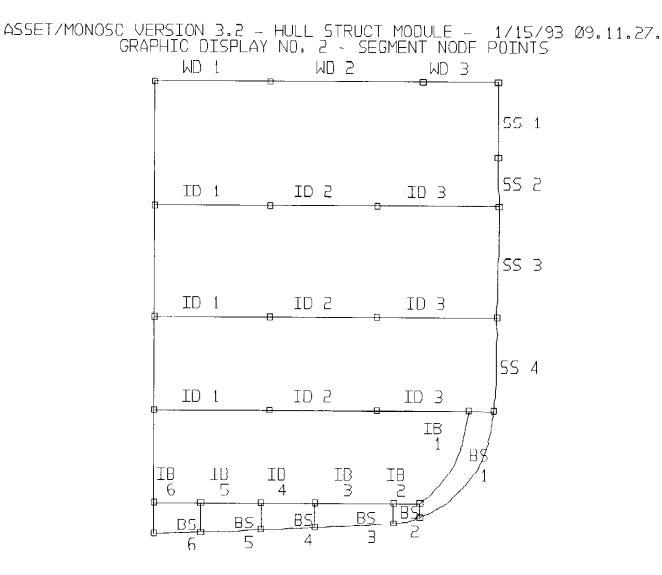
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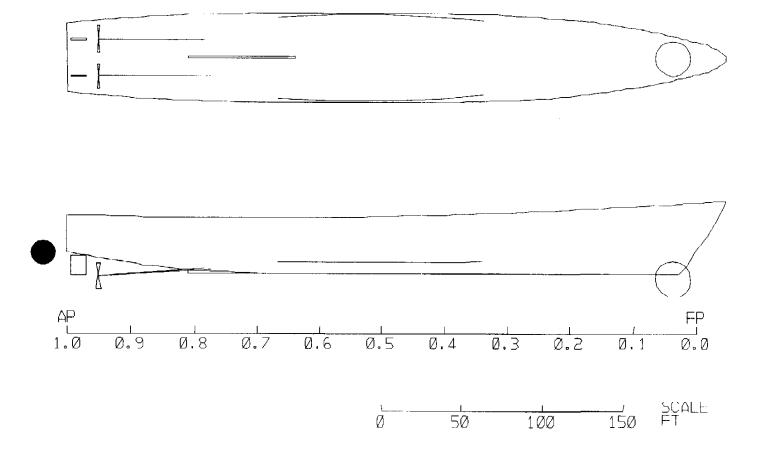


# D-79

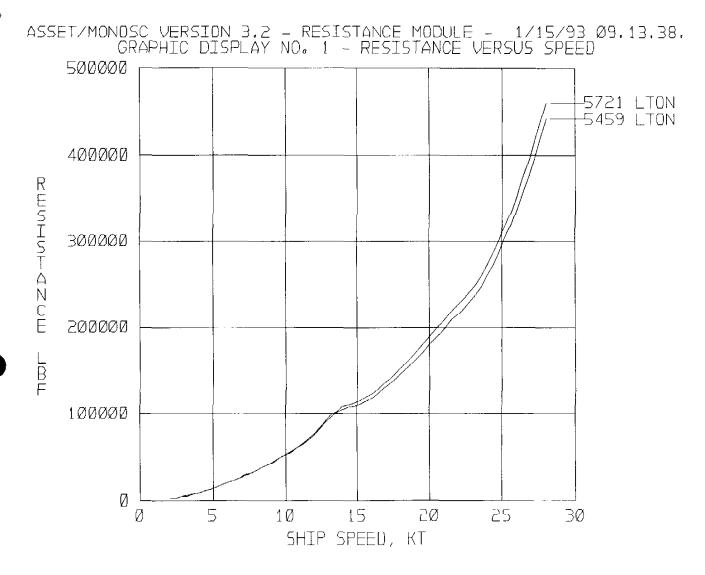
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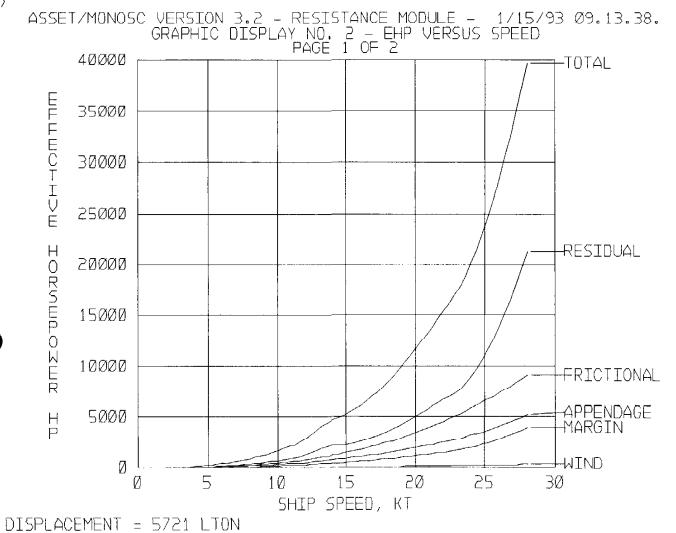
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ASSET/MONOSC VERSION 3.2 - APPENDAGE MODULE - 1/15/93 09.12.59. GRAPHIC DISPLAY NO. 1 - HULL PROFILE AND PLAN VIEW WITH APPENDAGES



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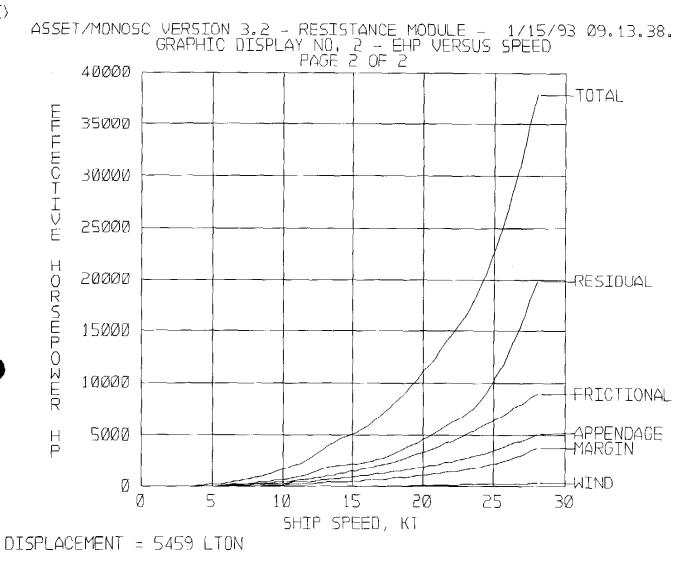


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D-82

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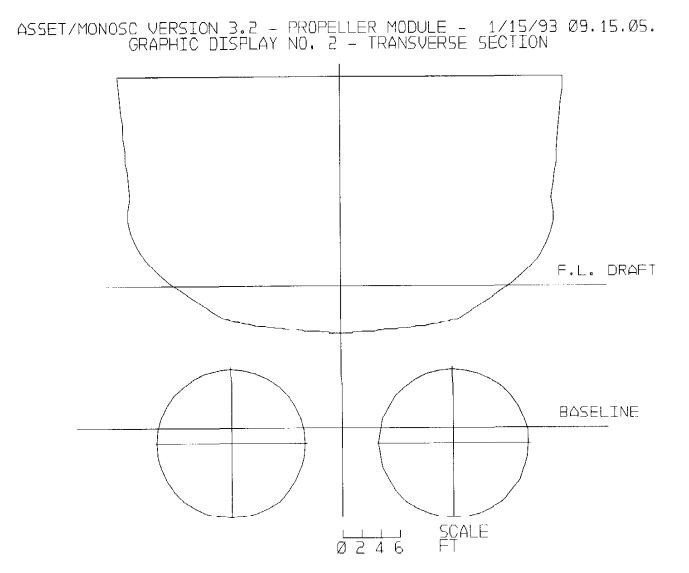


ASSET/MONOSC VERSION 3.2 - PROPELLER MODULE - 1/15/93 09.15.05. GRAPHIC DISPLAY NO. 1 - OPEN WATER DIAGRAM 1.2 THRUST/TORQUE 1.0 Ø.8 -EFFY Ø.6 COEF EFFY Ø.4 -10KQ Ø.2 ÷КТ ø.ø 🗵 Ø.Ø 1.Ø Ø.2 0.4 Ø.6 Ø.8 1.2 ADVANCE COEF (J)

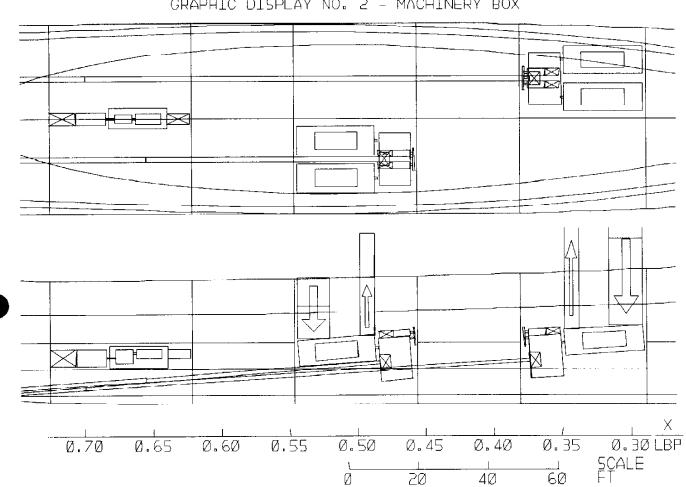
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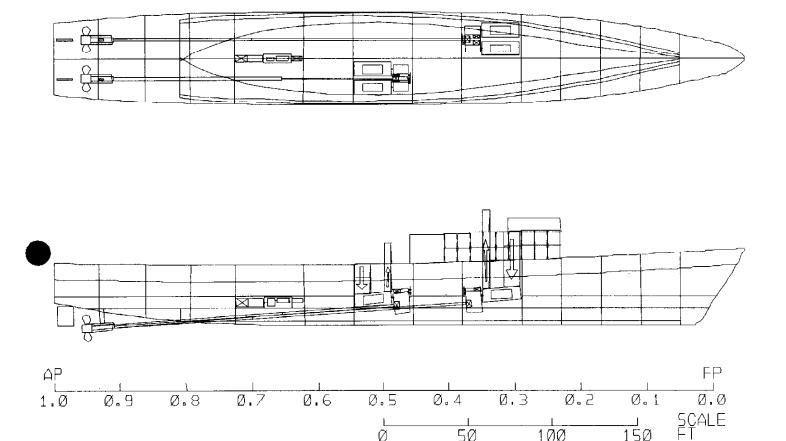


ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHIC DISPLAY NO. 2 - MACHINERY BOX

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ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHIC DISPLAY NO, 1 SHIP MACHINERY LAYOUT

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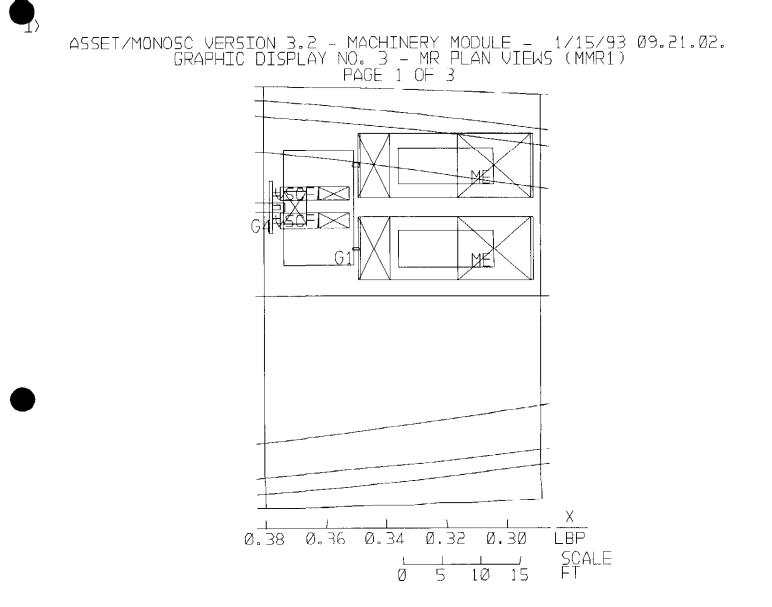


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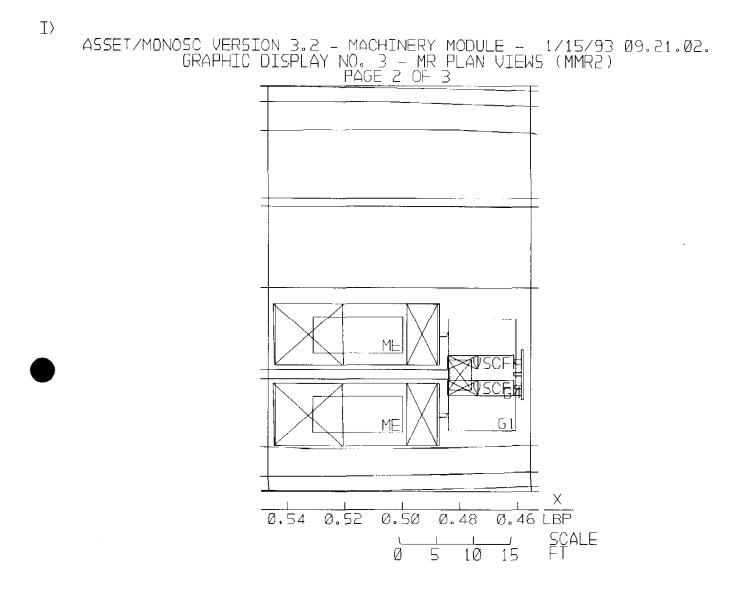
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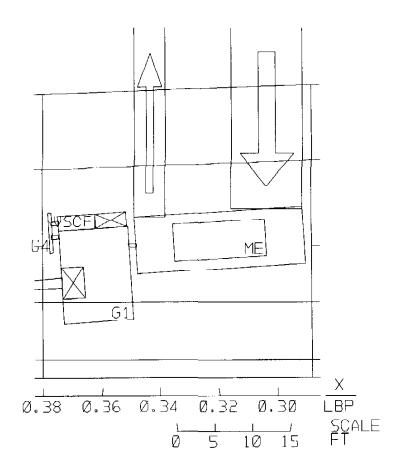


ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHTC DISPLAY NO, 3 - MR PLAN VIEWS (AMR1) PAGE 3 OF 3 SSE G17= SSG LBP ł 0.72 Ø.68 Ø.66 0.70 Ø.64 SCALE FT 

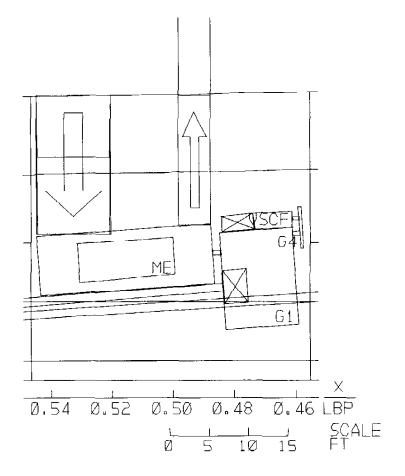
**D-90** 



ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHIC DISPLAY NO. 4 - MR PROFILE VIEWS (MMR1) PAGE 1 OF 3



# ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHIC DISPLAY NO. 4 - MR PROFILE VIEWS (MMR2) PAGE 2 OF 3

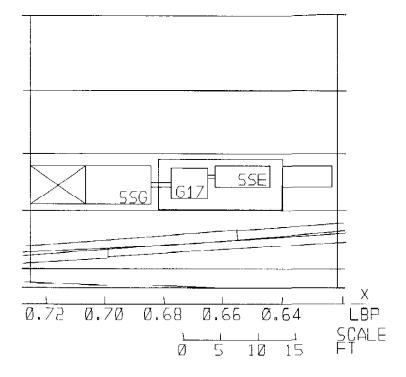




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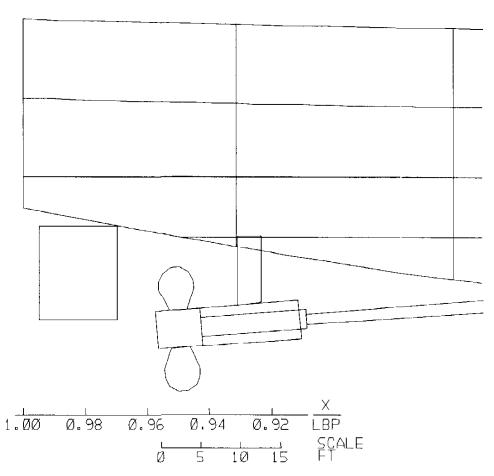
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# ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 09.21.02. GRAPHIC DISPLAY NO, 4 - MR PROFILE VIEWS (AMR1) PAGE 3 OF 3



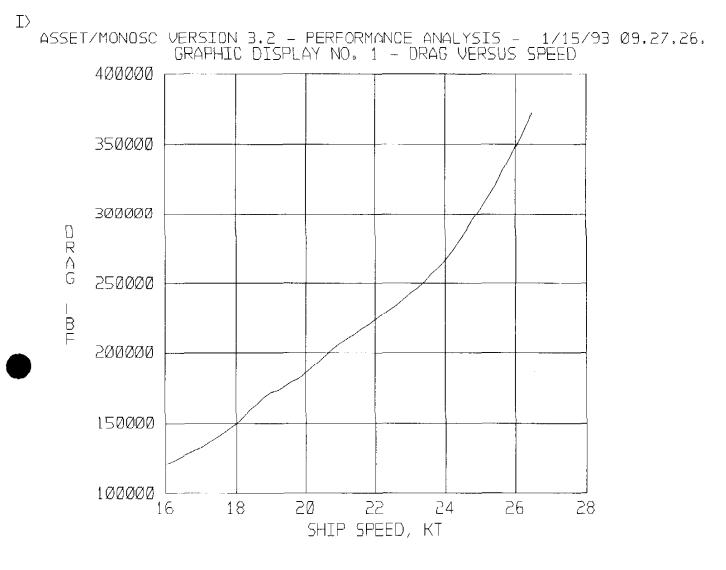
ASSET/MONOSC VERSION 3.2 - MACHINERY MODULE - 1/15/93 Ø9.21.02. GRAPHTC DISPLAY NO. 5 - PROPULSION APPENDAGES PROFILE VIEW

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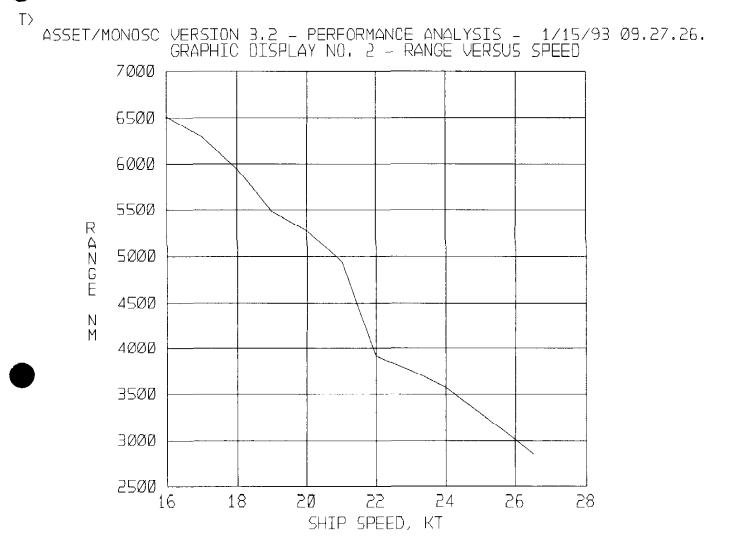
D-94

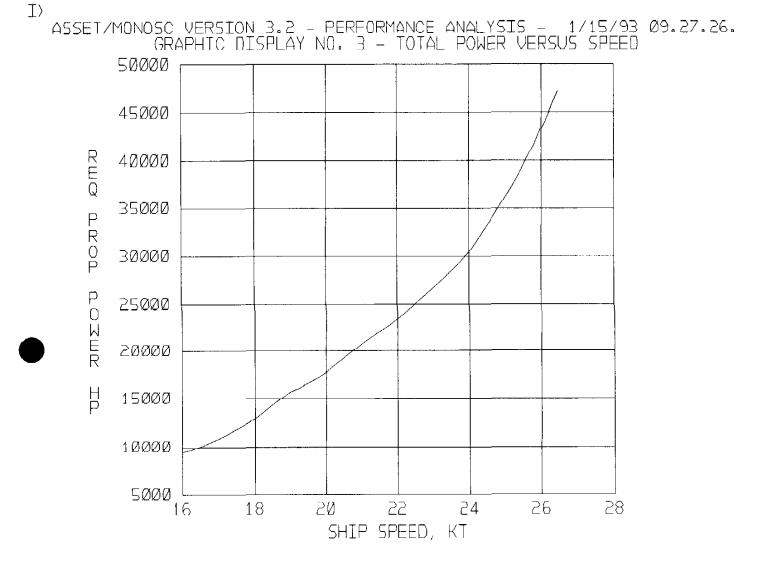
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D-95

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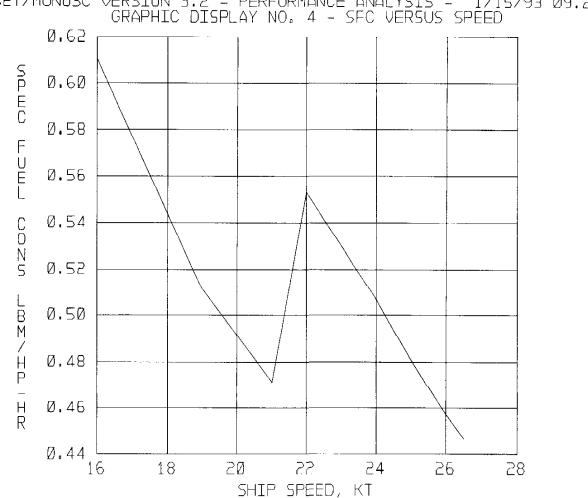


D-97

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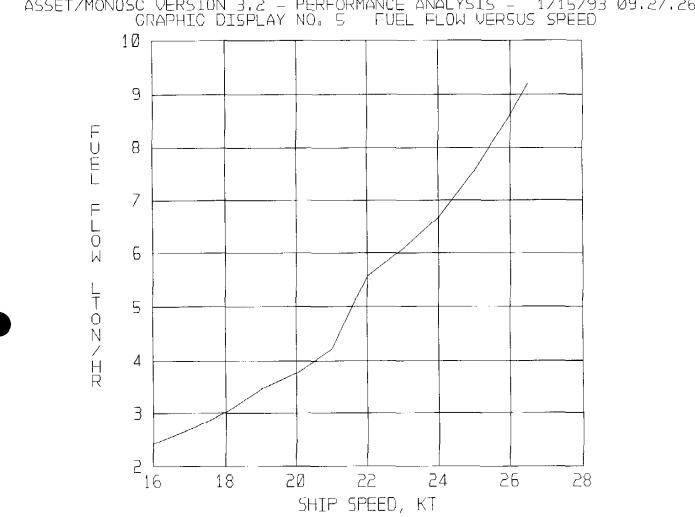
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ASSET/MONDSC VERSION 3.2 - PERFORMANCE ANALYSIS - 1/15/93 Ø9.27.26. GRAPHIC DISPLAY NO. 4 - SFC VERSUS SPEED

**D-98** 

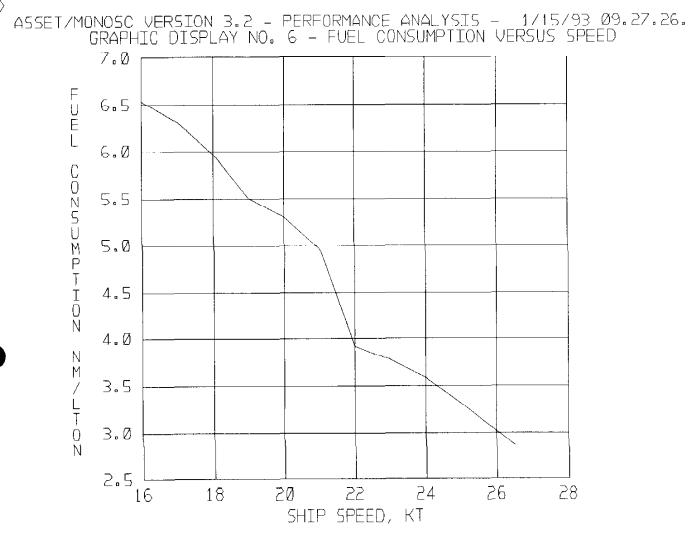
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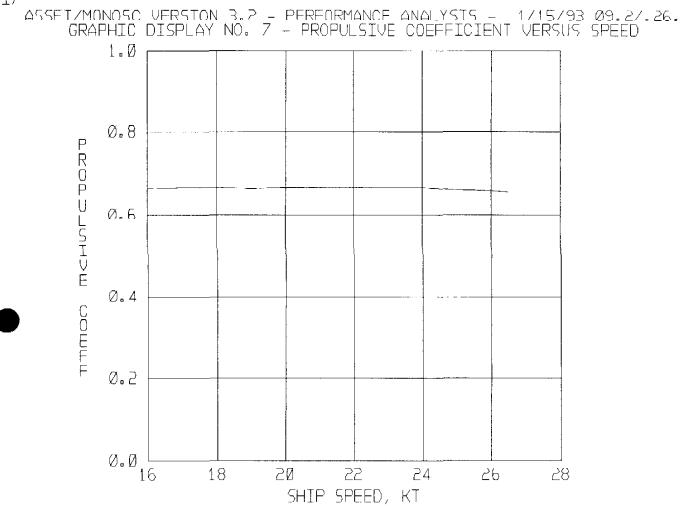
ASSET/MONDSC VERSION 3.2 - PERFORMANCE ANALYSIS - 1/15/93 Ø9.27.26. GRAPHIC DISPLAY NO. 5 FUEL FLOW VERSUS SPEED

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D-99



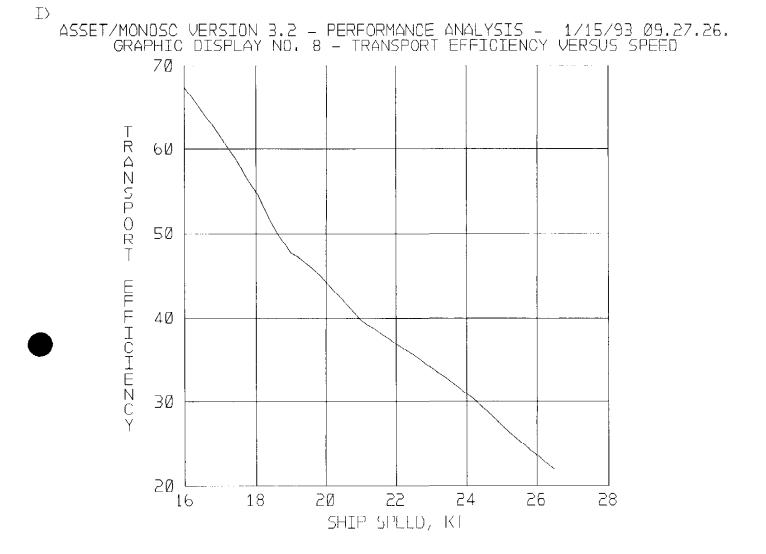
**D-100** 



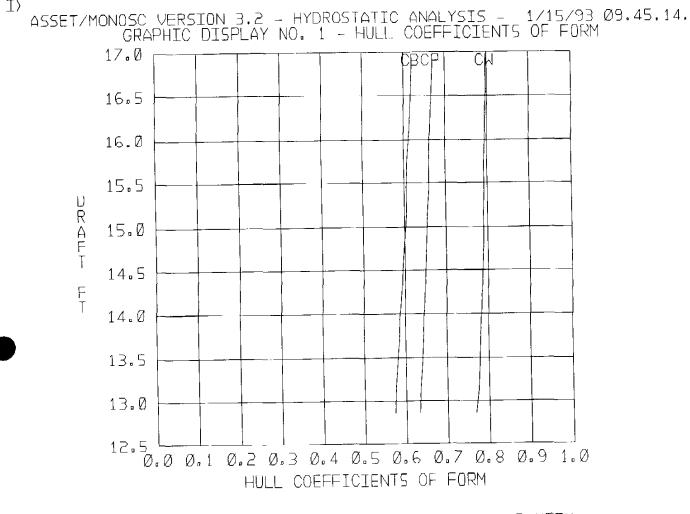
**D-101** 

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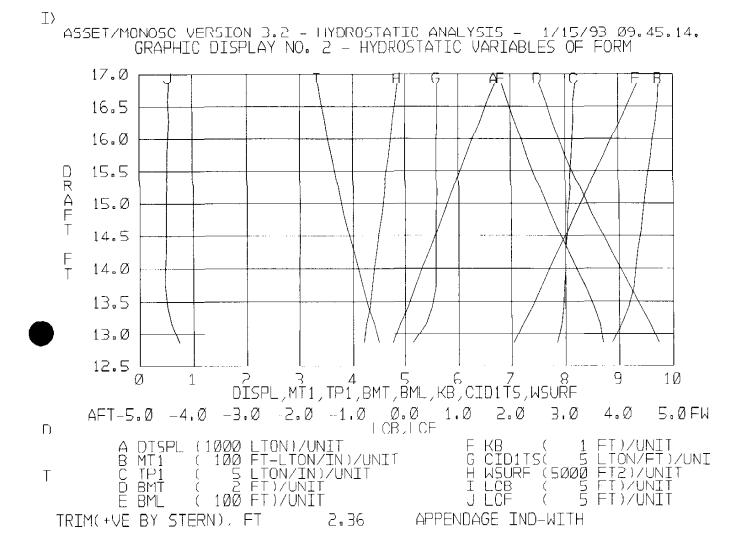
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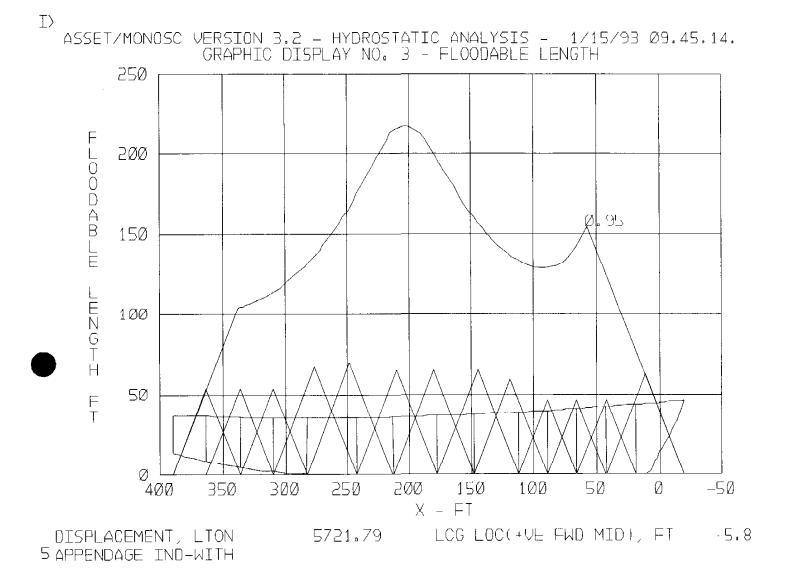
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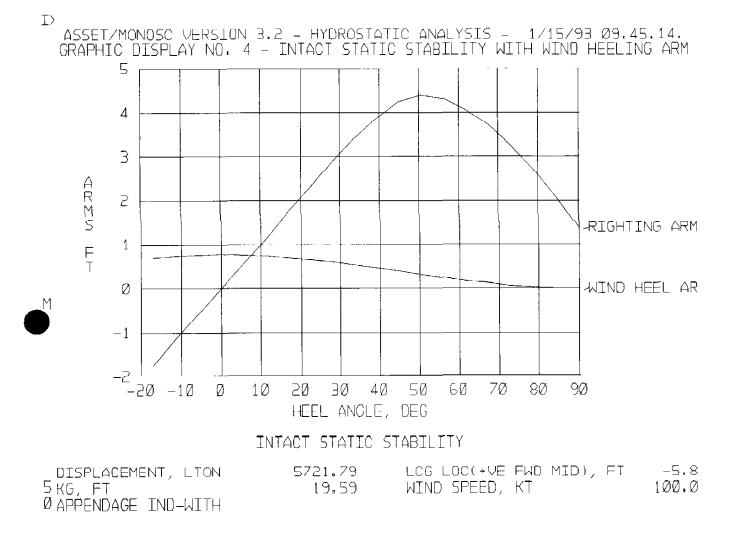
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**D**-104

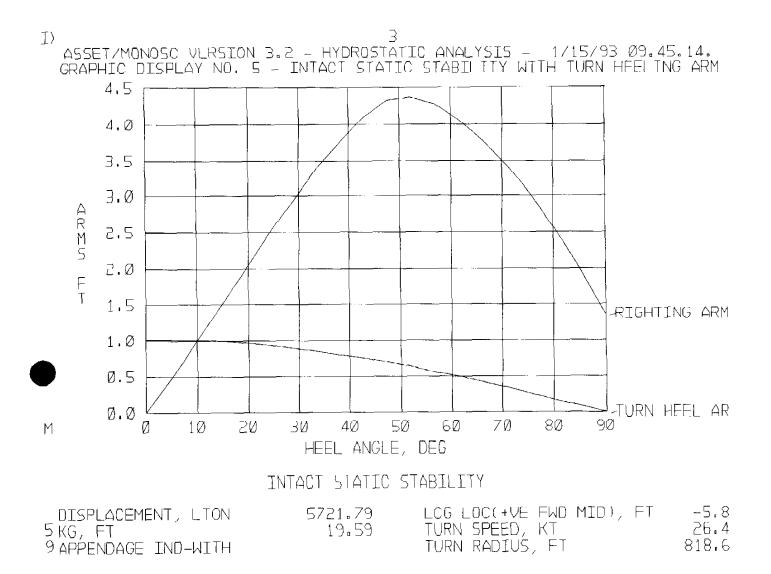


**D-105** 

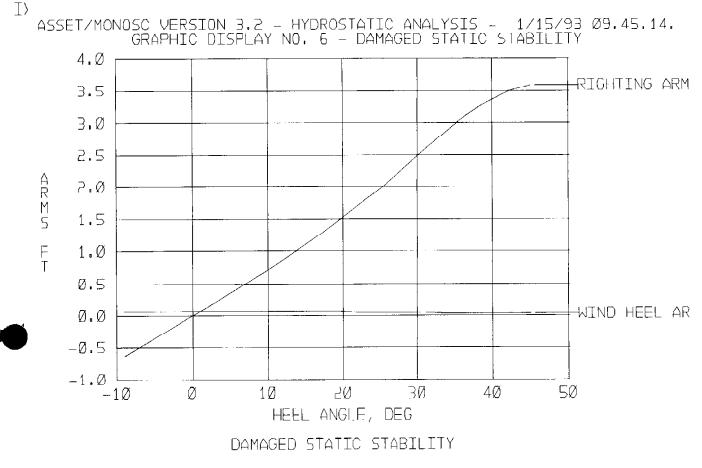


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D-107



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